

# **Part XIII.**

# **Beyond the Context-Free Languages**

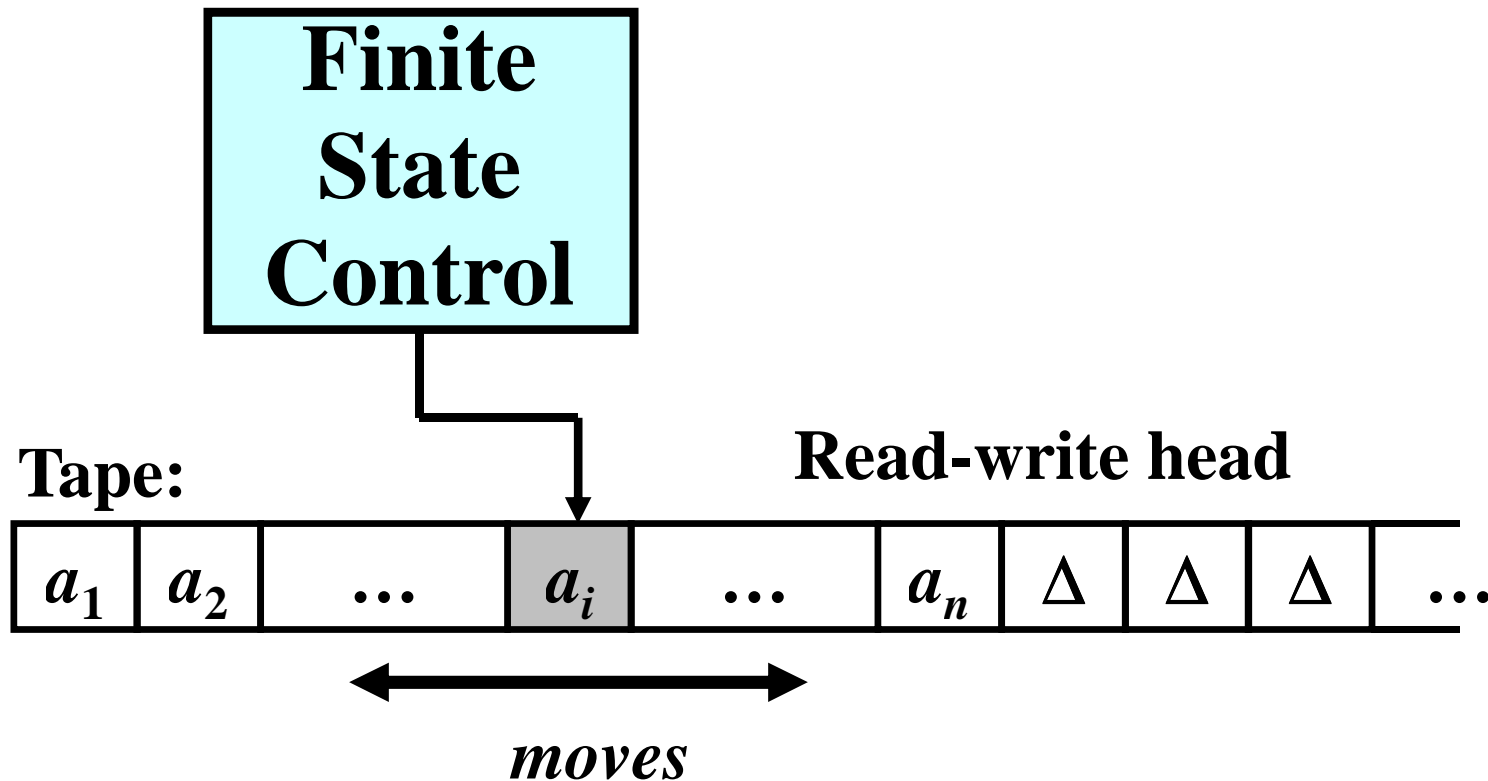
# Alan Turing (1912 – 1954)



# Turing Machines (TM)

**Gist: The most powerful computational model.**

---



**Note:**  $\Delta$  = blank

# Turing Machines: Definition

**Definition:** A *Turing machine* (TM) is a 6-tuple  $M = (Q, \Sigma, \Gamma, R, s, F)$ , where

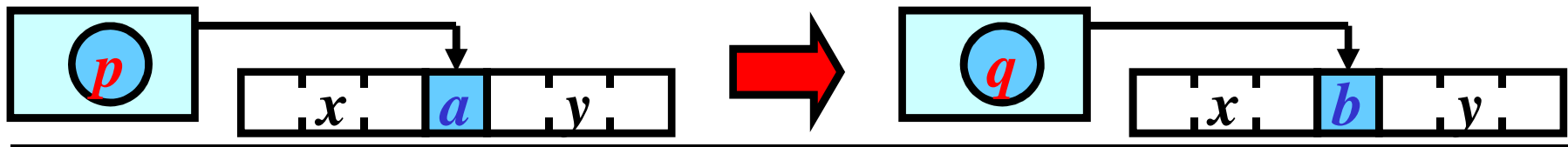
- $Q$  is a *finite set of states*
- $\Sigma$  is an *input alphabet*
- $\Gamma$  is a *tape alphabet*;  $\Delta \in \Gamma$ ;  $\Sigma \subseteq \Gamma$
- $R$  is a *finite set of rules* of the form:  $pa \rightarrow qbt$ ,  
where  $p, q \in Q$ ,  $a, b \in \Gamma$ ,  $t \in \{S, R, L\}$
- $s \in Q$  is the *start state*
- $F \subseteq Q$  is a set of *final states*

**Mathematical note:**

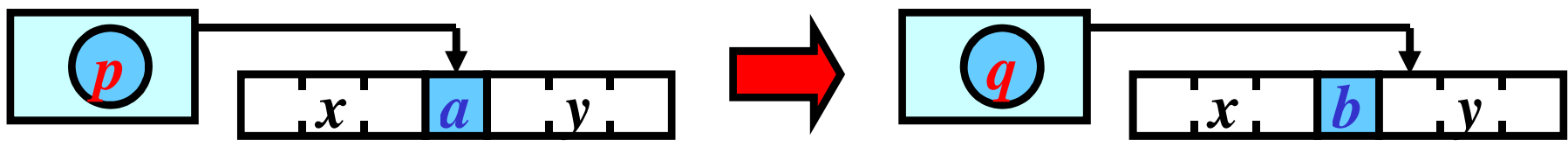
- Mathematically,  $R$  is a relation from  $Q \times \Gamma$  to  $Q \times \Gamma \times \{S, R, L\}$
- Instead of  $(pa, qbt)$ , we write  $pa \rightarrow qbt$

# Interpretation of Rules

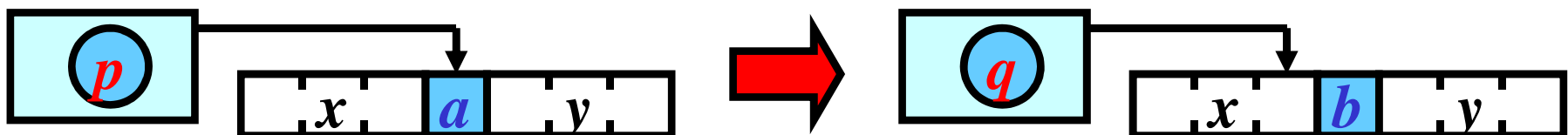
- $pa \rightarrow qbS$ : If the current state and tape symbol are  $p$  and  $a$ , respectively, then replace  $a$  with  $b$ , change  $p$  to  $q$ , and keep the head  $S$ tationary.



- $pa \rightarrow qbR$ : If the current state and tape symbol are  $p$  and  $a$ , respectively, then replace  $a$  with  $b$ , shift the head a square  $R$ ight, and change  $p$  to  $q$ .




- $pa \rightarrow qbL$ : If the current state and tape symbol are  $p$  and  $a$ , respectively, then replace  $a$  with  $b$ , shift the head a square  $L$ eft, and change  $p$  to  $q$ .



# Graphical Representation

 represents  $q \in Q$

$\rightarrow$   represents the initial state  $s \in Q$

 represents a final state  $f \in F$

  $\xrightarrow{a/b, S}$   denotes  $pa \rightarrow qbS \in R$

  $\xrightarrow{a/b, R}$   denotes  $pa \rightarrow qbR \in R$

  $\xrightarrow{a/b, L}$   denotes  $pa \rightarrow qbL \in R$

# Turing Machine: Example 1/2

$M = (Q, \Sigma, \Gamma, R, s, F)$

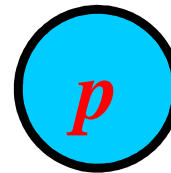
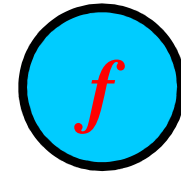
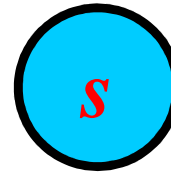
where:

# Turing Machine: Example 1/2

$M = (Q, \Sigma, \Gamma, R, s, F)$

where:

- $Q = \{s, p, q, f\};$



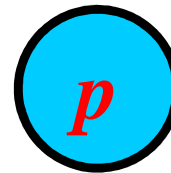
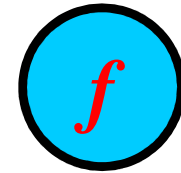
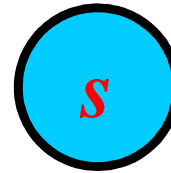


# Turing Machine: Example 1/2

$M = (Q, \Sigma, \Gamma, R, s, F)$

where:

- $Q = \{s, p, q, f\};$
- $\Sigma = \{a, b\};$

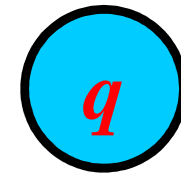
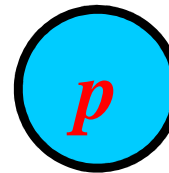
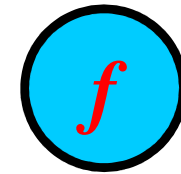
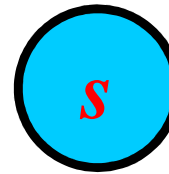


# Turing Machine: Example 1/2

$$M = (Q, \Sigma, \Gamma, R, s, F)$$

where:

- $Q = \{s, p, q, f\};$
- $\Sigma = \{a, b\};$
- $\Gamma = \{a, b, \Delta\};$

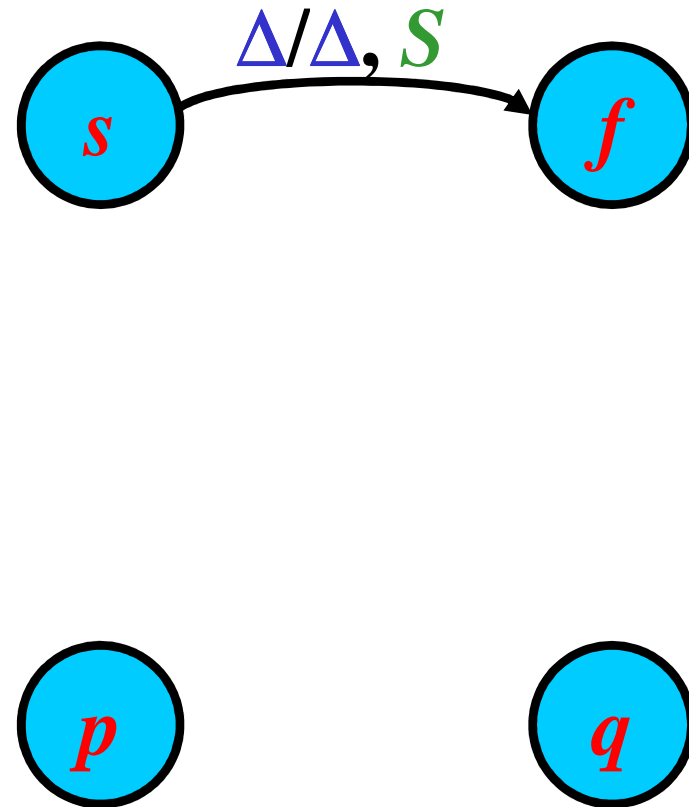


# Turing Machine: Example 1/2

$$M = (Q, \Sigma, \Gamma, R, s, F)$$

where:

- $Q = \{s, p, q, f\}$ ;
- $\Sigma = \{a, b\}$ ;
- $\Gamma = \{a, b, \Delta\}$ ;
- $R = \{s\Delta \rightarrow f\Delta S,$

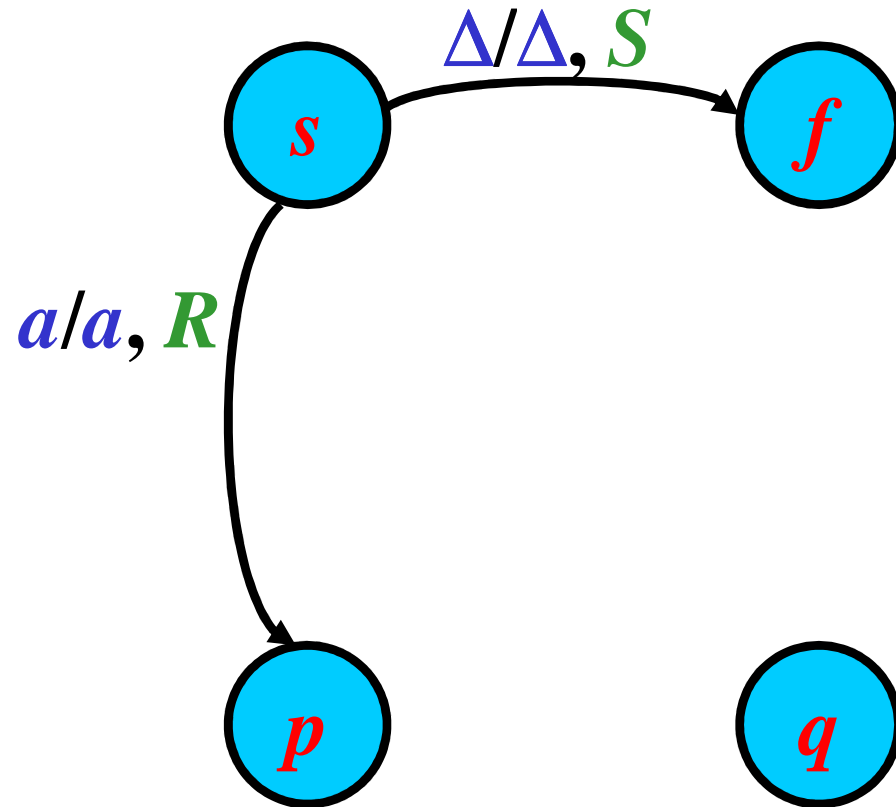


# Turing Machine: Example 1/2

$M = (Q, \Sigma, \Gamma, R, s, F)$

where:

- $Q = \{s, p, q, f\}$ ;
- $\Sigma = \{a, b\}$ ;
- $\Gamma = \{a, b, \Delta\}$ ;
- $R = \{s\Delta \rightarrow f\Delta S, \\ sa \rightarrow paR,$

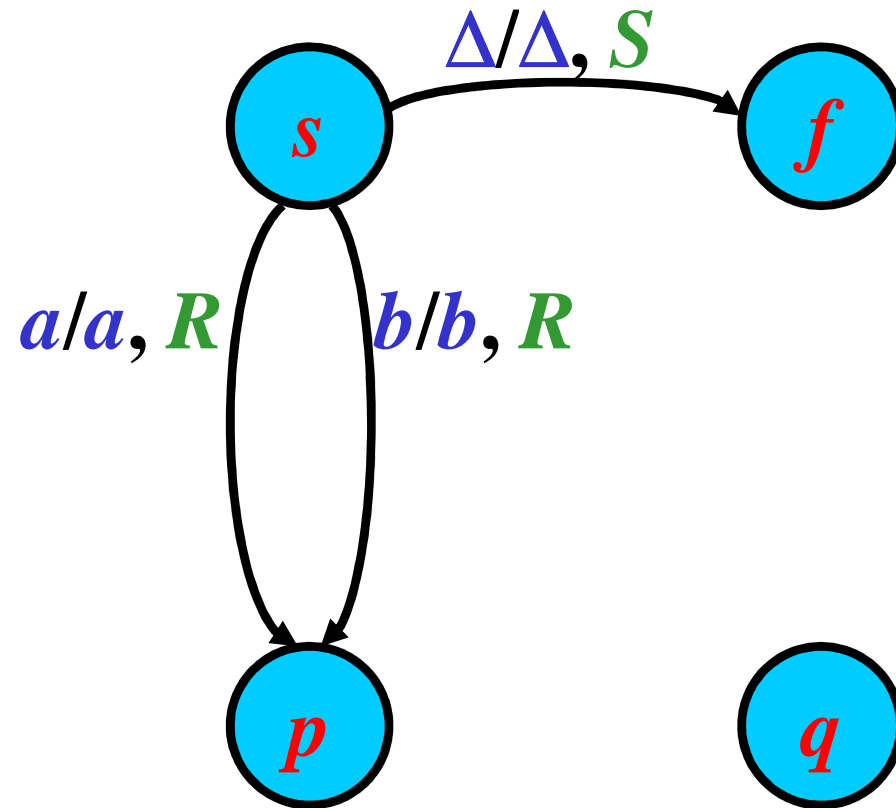


# Turing Machine: Example 1/2

$M = (Q, \Sigma, \Gamma, R, s, F)$

where:

- $Q = \{s, p, q, f\};$
- $\Sigma = \{a, b\};$
- $\Gamma = \{a, b, \Delta\};$
- $R = \{s\Delta \rightarrow f\Delta S,$   
 $sa \rightarrow paR,$   
 $sb \rightarrow pbR,$

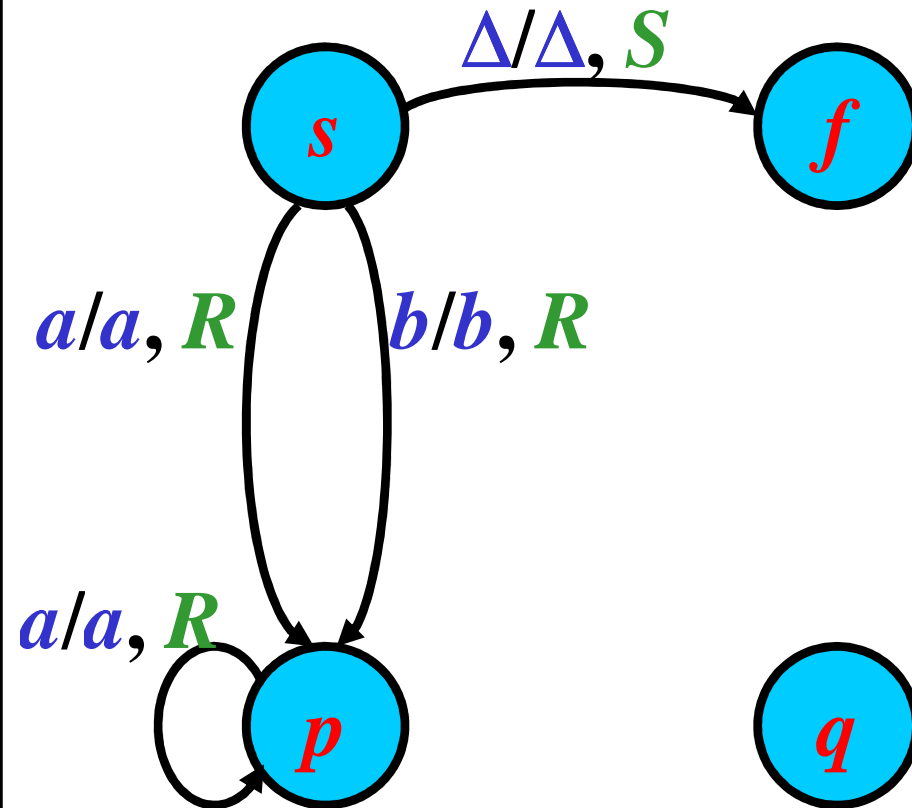


# Turing Machine: Example 1/2

$M = (Q, \Sigma, \Gamma, R, s, F)$

where:

- $Q = \{s, p, q, f\}$ ;
- $\Sigma = \{a, b\}$ ;
- $\Gamma = \{a, b, \Delta\}$ ;
- $R = \{s\Delta \rightarrow f\Delta S,$   
 $sa \rightarrow paR,$   
 $sb \rightarrow pbR,$   
 $pa \rightarrow paR,$

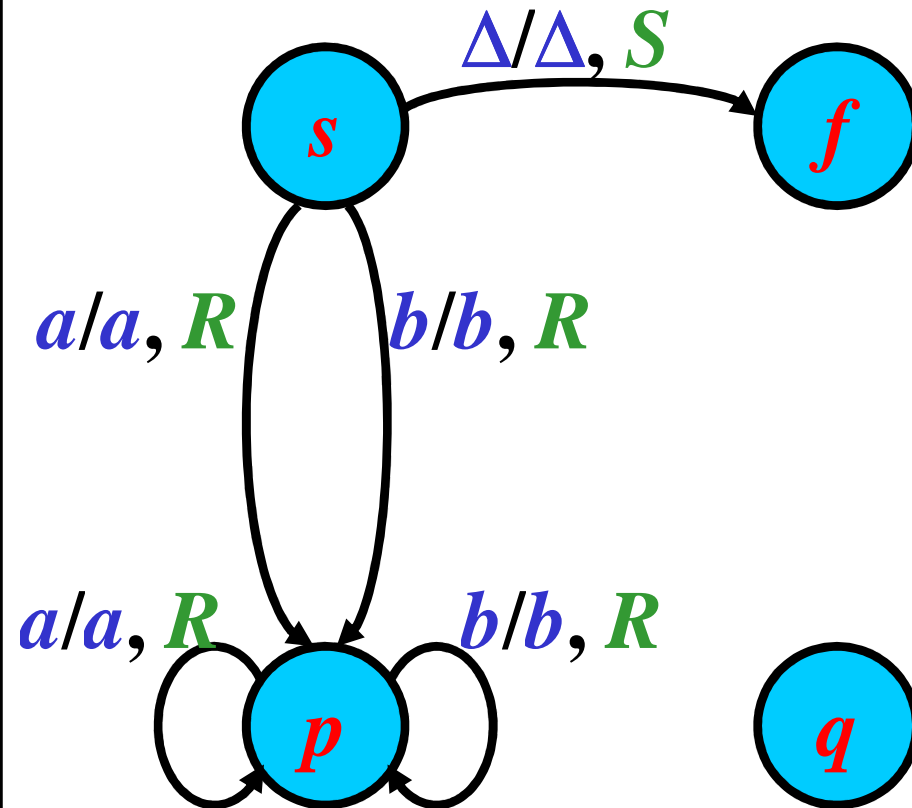


# Turing Machine: Example 1/2

$M = (Q, \Sigma, \Gamma, R, s, F)$

where:

- $Q = \{s, p, q, f\}$ ;
- $\Sigma = \{a, b\}$ ;
- $\Gamma = \{a, b, \Delta\}$ ;
- $R = \{s\Delta \rightarrow f\Delta S,$   
 $sa \rightarrow paR,$   
 $sb \rightarrow pbR,$   
 $pa \rightarrow paR,$   
 $pb \rightarrow pbR,$

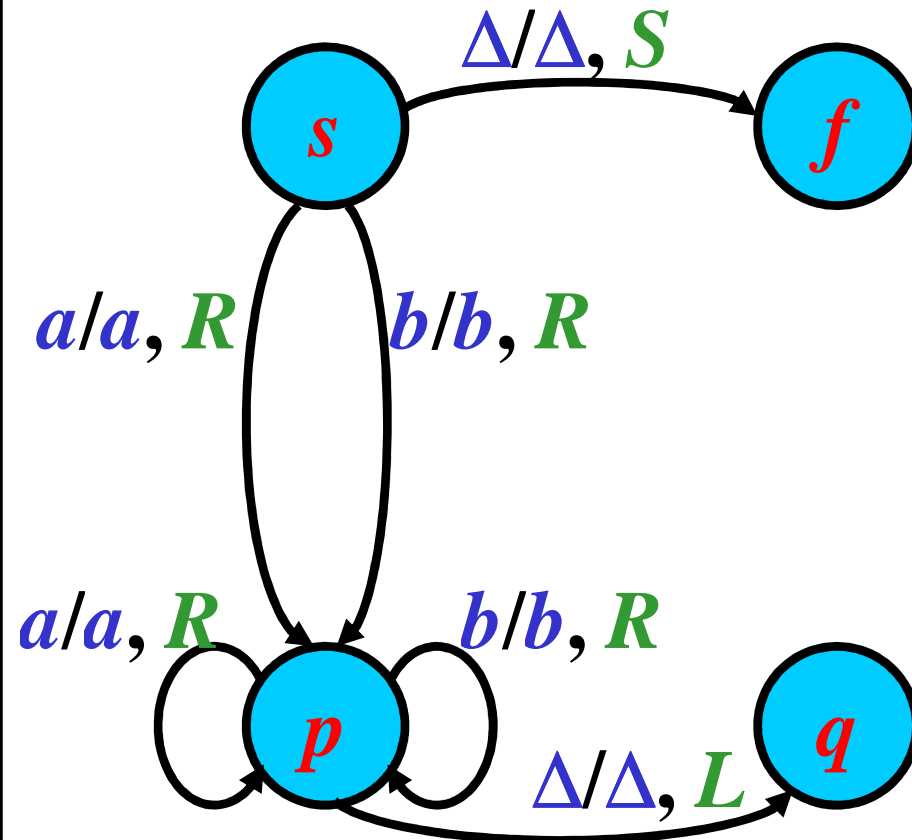


# Turing Machine: Example 1/2

$M = (Q, \Sigma, \Gamma, R, s, F)$

where:

- $Q = \{s, p, q, f\}$ ;
- $\Sigma = \{a, b\}$ ;
- $\Gamma = \{a, b, \Delta\}$ ;
- $R = \{$   
 $s\Delta \rightarrow f\Delta S,$   
 $sa \rightarrow paR,$   
 $sb \rightarrow pbR,$   
 $pa \rightarrow paR,$   
 $pb \rightarrow pbR,$   
 $p\Delta \rightarrow q\Delta L,$



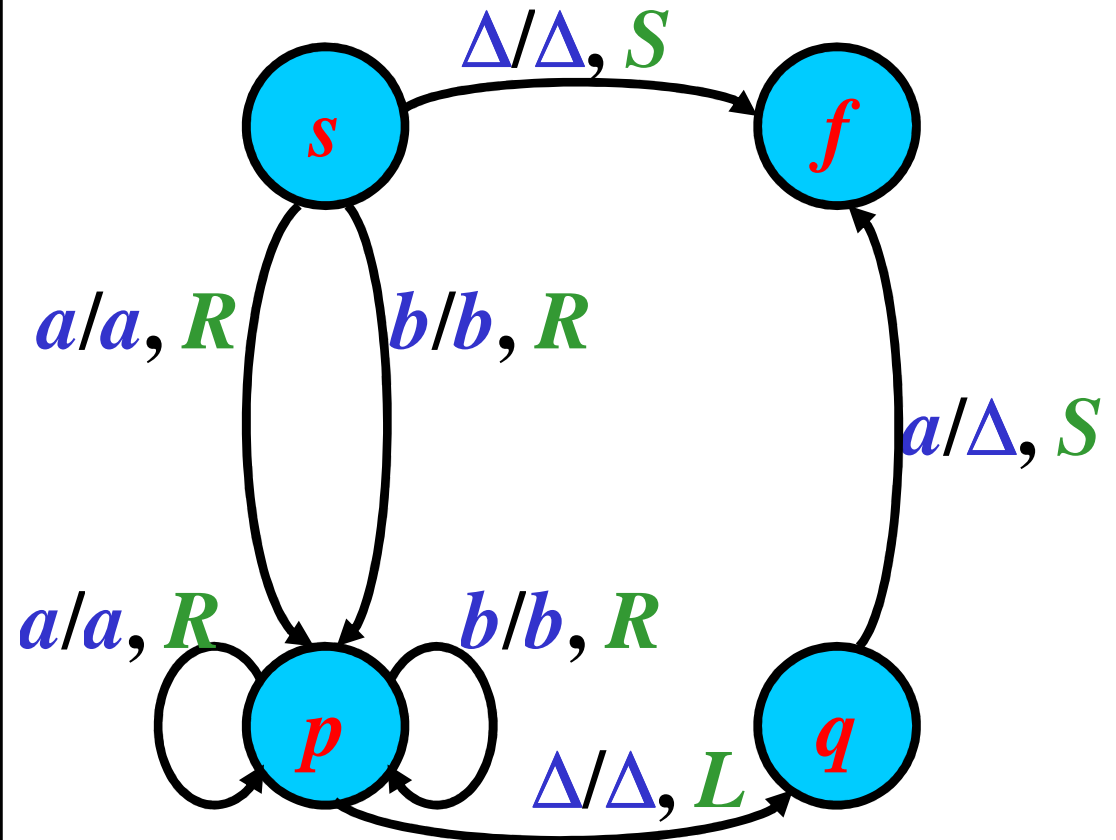


# Turing Machine: Example 1/2

$M = (Q, \Sigma, \Gamma, R, s, F)$

where:

- $Q = \{s, p, q, f\}$ ;
- $\Sigma = \{a, b\}$ ;
- $\Gamma = \{a, b, \Delta\}$ ;
- $R = \{$   
 $s\Delta \rightarrow f\Delta S,$   
 $sa \rightarrow paR,$   
 $sb \rightarrow pbR,$   
 $pa \rightarrow paR,$   
 $pb \rightarrow pbR,$   
 $p\Delta \rightarrow q\Delta L,$   
 $qa \rightarrow f\Delta S,$

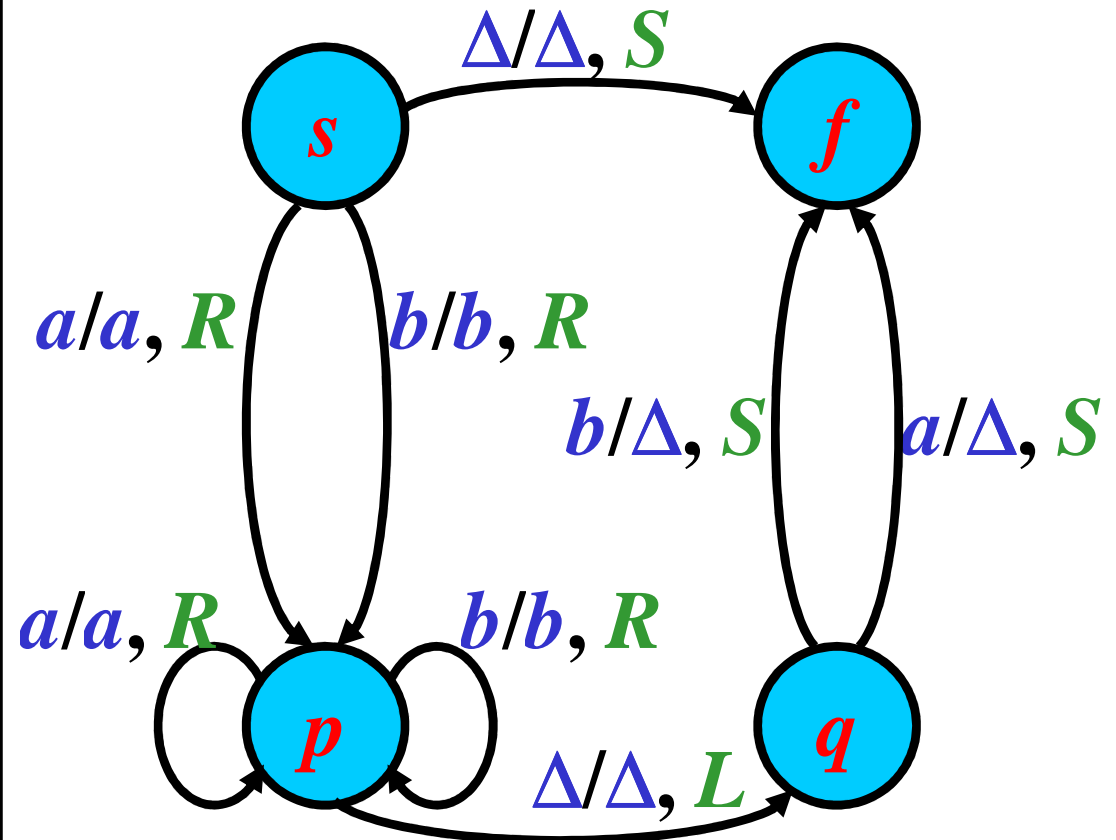


# Turing Machine: Example 1/2

$M = (Q, \Sigma, \Gamma, R, s, F)$

where:

- $Q = \{s, p, q, f\}$ ;
- $\Sigma = \{a, b\}$ ;
- $\Gamma = \{a, b, \Delta\}$ ;
- $R = \{$   
 $s\Delta \rightarrow f\Delta S,$   
 $sa \rightarrow paR,$   
 $sb \rightarrow pbR,$   
 $pa \rightarrow paR,$   
 $pb \rightarrow pbR,$   
 $p\Delta \rightarrow q\Delta L,$   
 $qa \rightarrow f\Delta S,$   
 $qb \rightarrow f\Delta S\}$

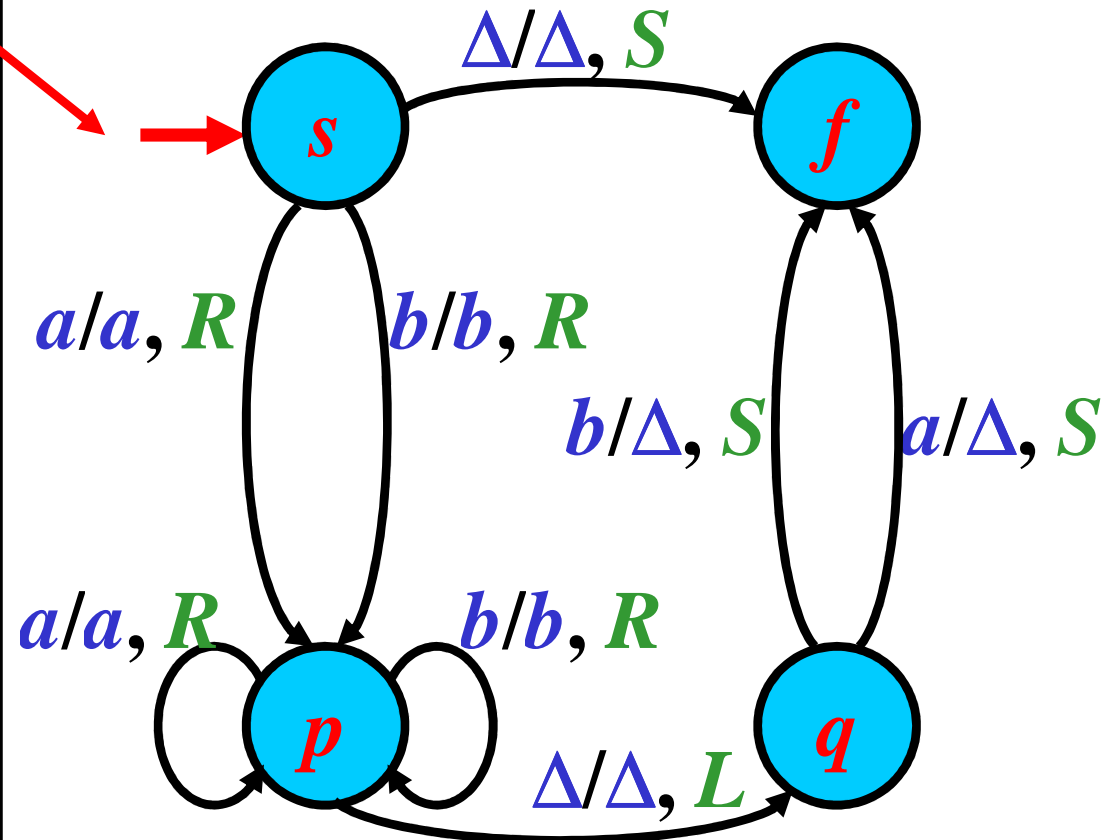


# Turing Machine: Example 1/2

$M = (Q, \Sigma, \Gamma, R, s, F)$

where:

- $Q = \{s, p, q, f\}$ ;
- $\Sigma = \{a, b\}$ ;
- $\Gamma = \{a, b, \Delta\}$ ;
- $R = \{$   
 $s\Delta \rightarrow f\Delta S,$   
 $sa \rightarrow paR,$   
 $sb \rightarrow pbR,$   
 $pa \rightarrow paR,$   
 $pb \rightarrow pbR,$   
 $p\Delta \rightarrow q\Delta L,$   
 $qa \rightarrow f\Delta S,$   
 $qb \rightarrow f\Delta S\}$

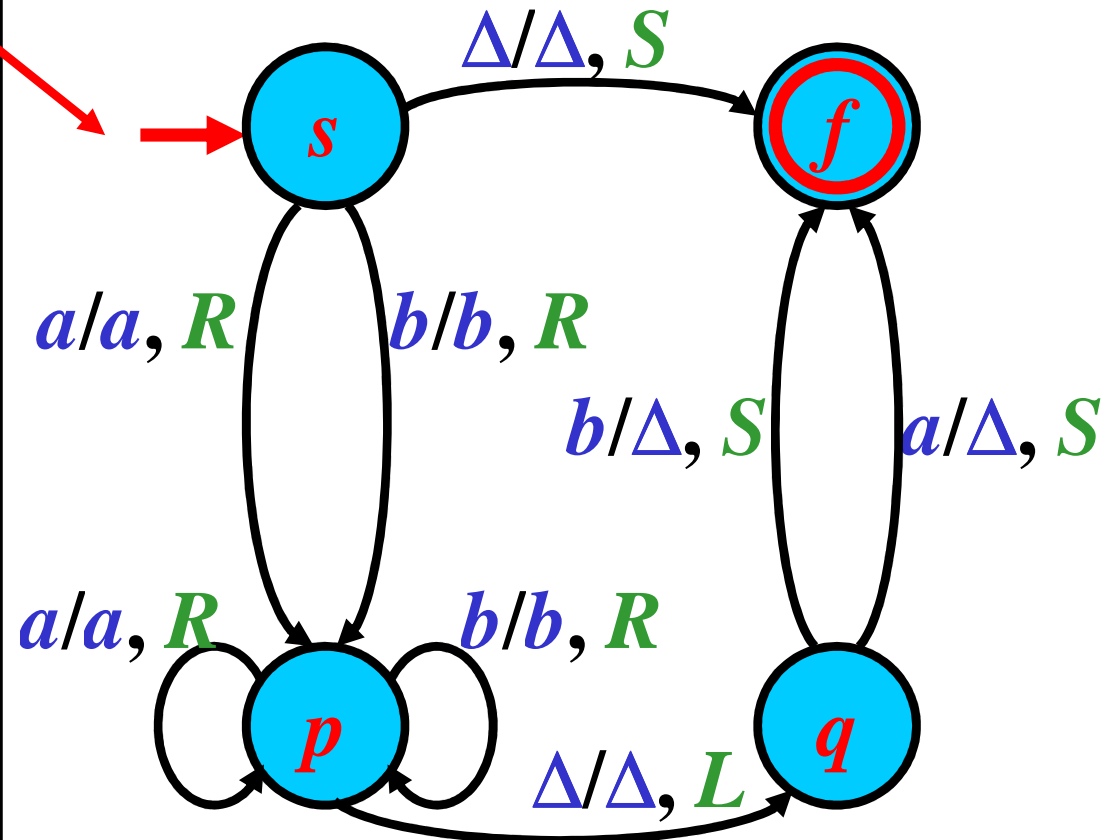


# Turing Machine: Example 1/2

$M = (Q, \Sigma, \Gamma, R, s, F)$

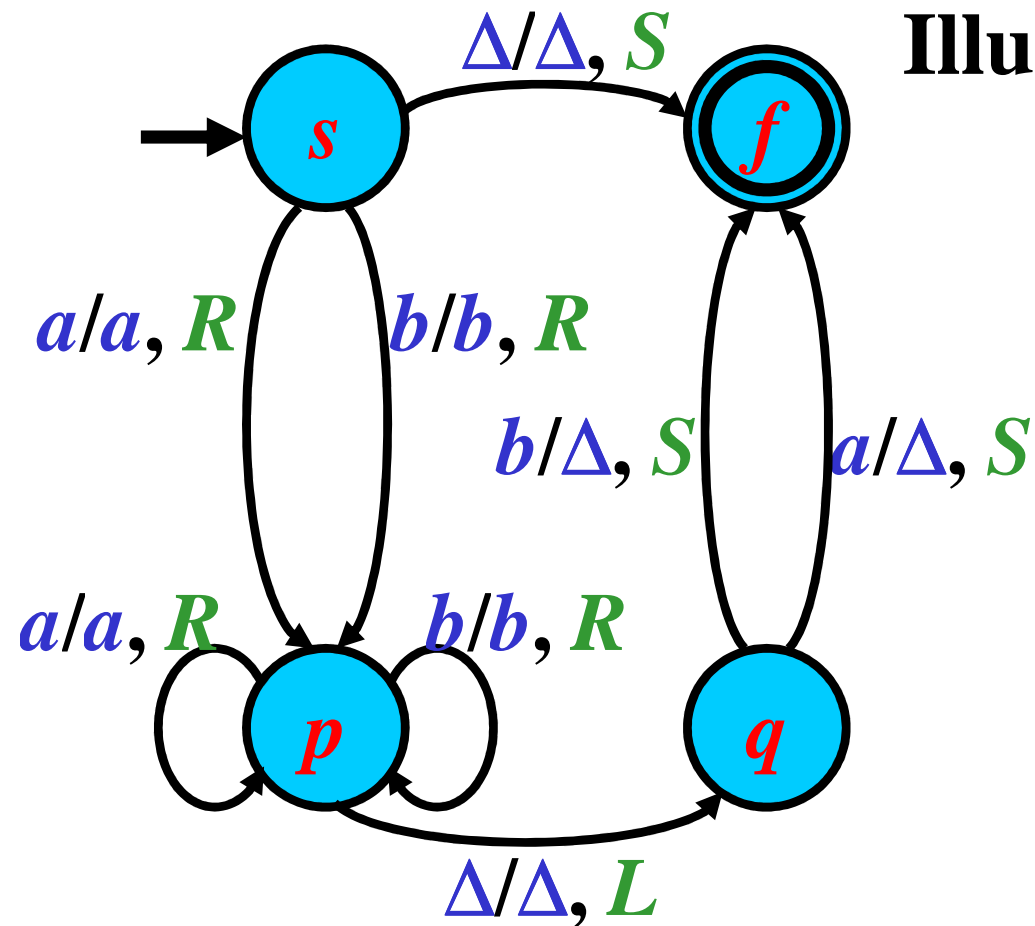
where:

- $Q = \{s, p, q, f\}$ ;
- $\Sigma = \{a, b\}$ ;
- $\Gamma = \{a, b, \Delta\}$ ;
- $R = \{$   
 $s\Delta \rightarrow f\Delta S,$   
 $sa \rightarrow paR,$   
 $sb \rightarrow pbR,$   
 $pa \rightarrow paR,$   
 $pb \rightarrow pbR,$   
 $p\Delta \rightarrow q\Delta L,$   
 $qa \rightarrow f\Delta S,$   
 $qb \rightarrow f\Delta S$   
 $\}$
- $F = \{f\}$



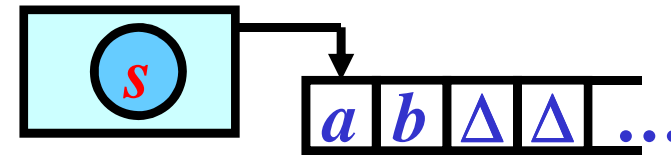
# Turing Machine: Example 2/2

TM  $M$ :



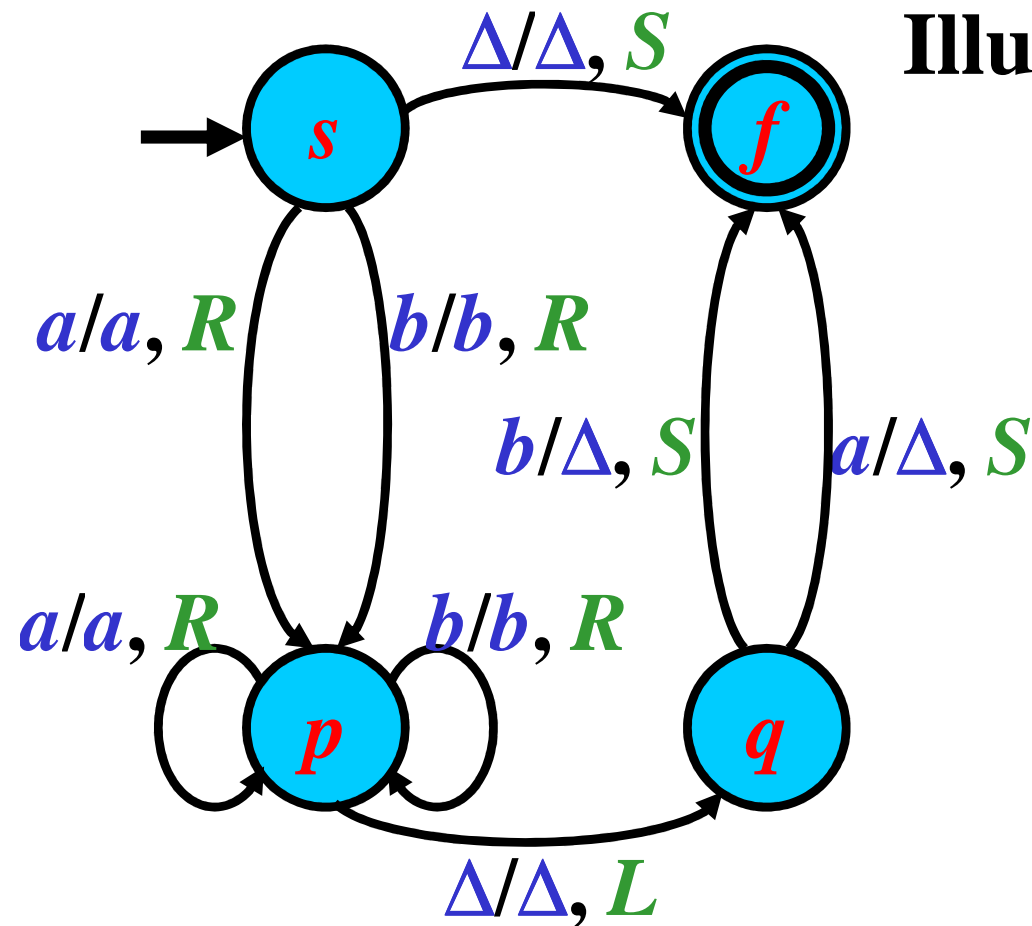
**Note:**  $M$  deletes a symbol before the first occurrence of  $\Delta$ :

**Illustration:**



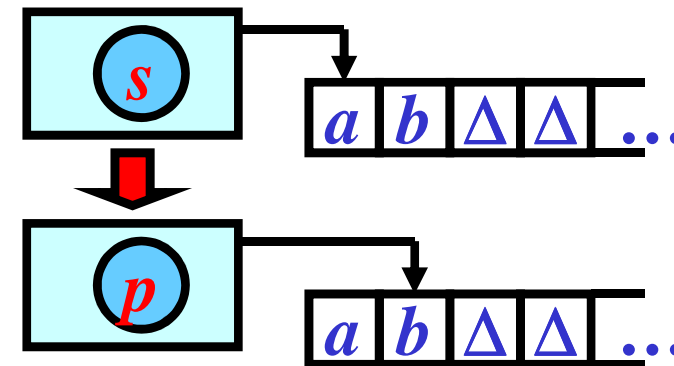
# Turing Machine: Example 2/2

TM  $M$ :



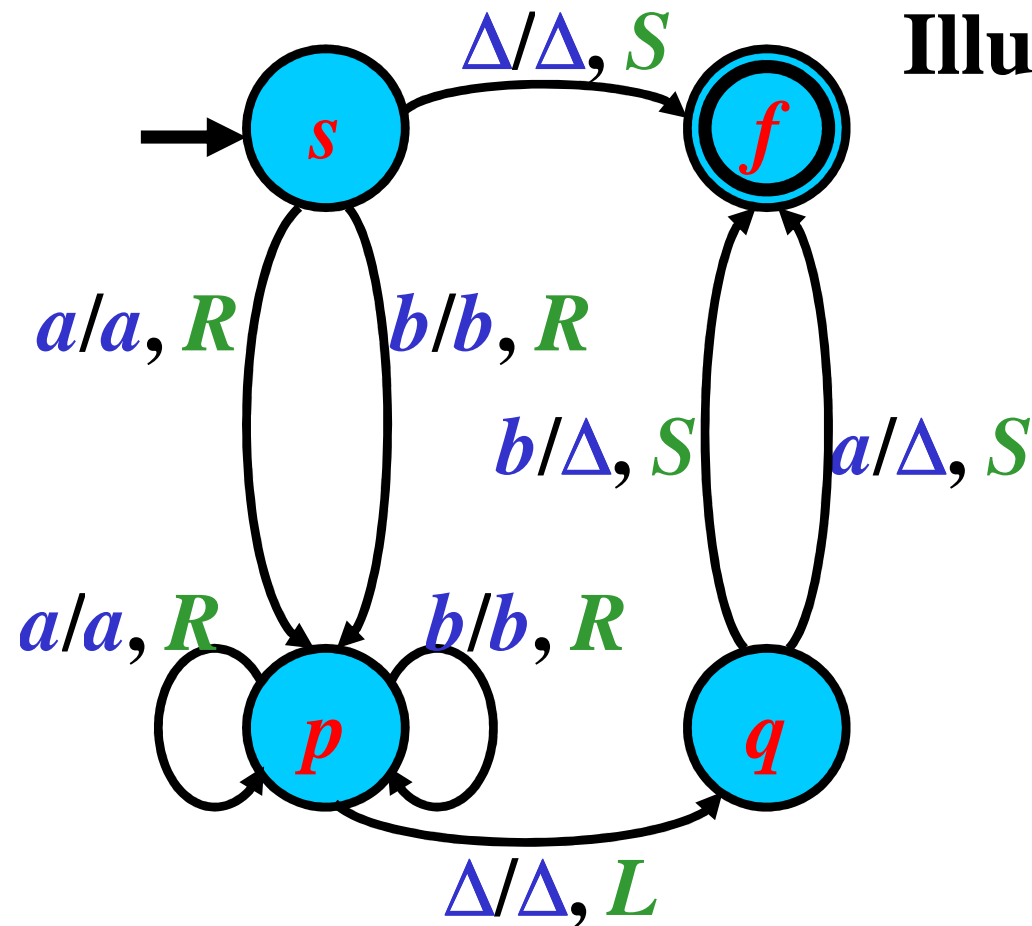
**Note:**  $M$  deletes a symbol before the first occurrence of  $\Delta$ :

**Illustration:**



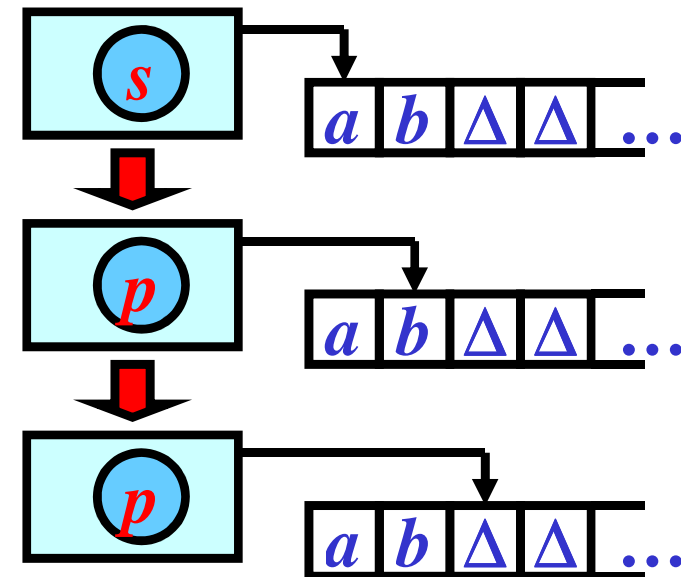
# Turing Machine: Example 2/2

TM  $M$ :



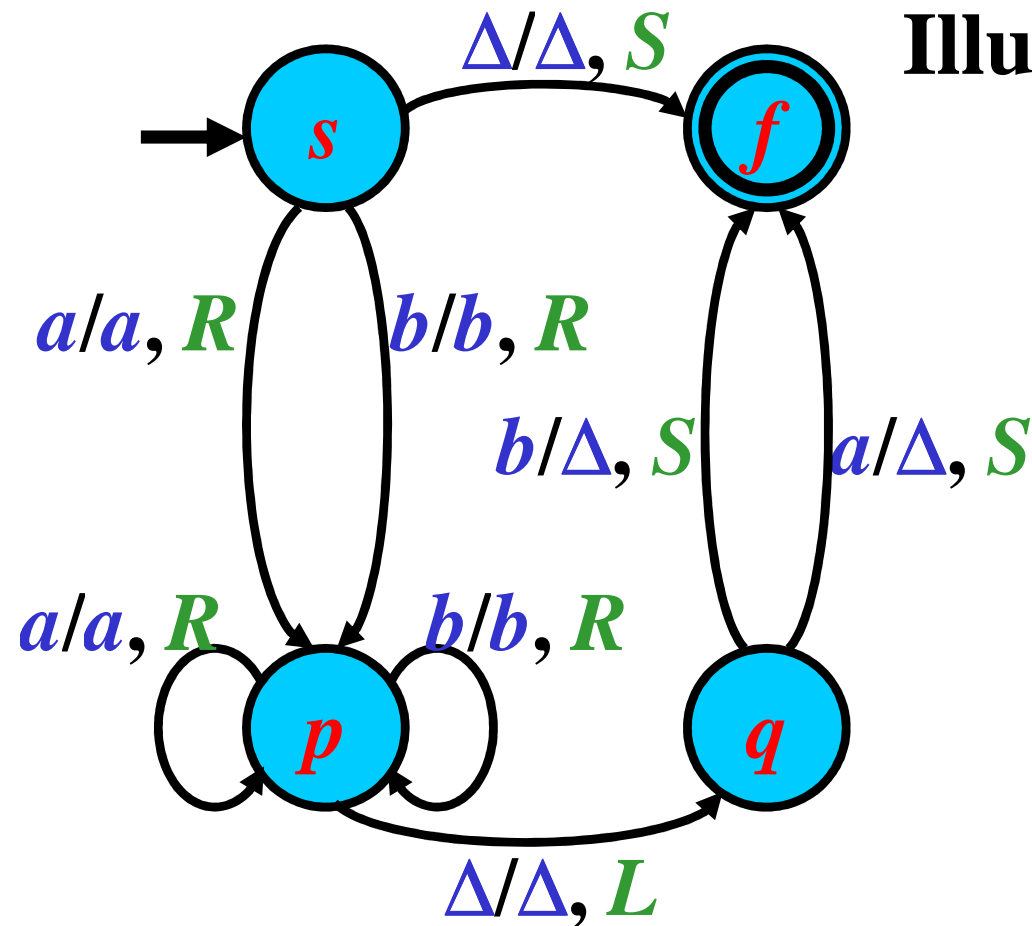
**Note:**  $M$  deletes a symbol before the first occurrence of  $\Delta$ :

**Illustration:**



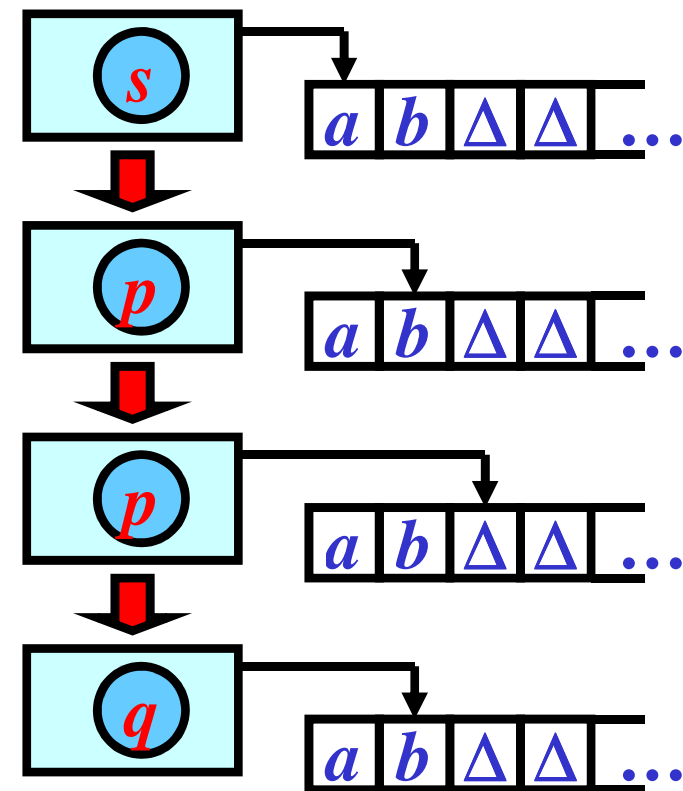
# Turing Machine: Example 2/2

TM  $M$ :



**Note:**  $M$  deletes a symbol before the first occurrence of  $\Delta$ :

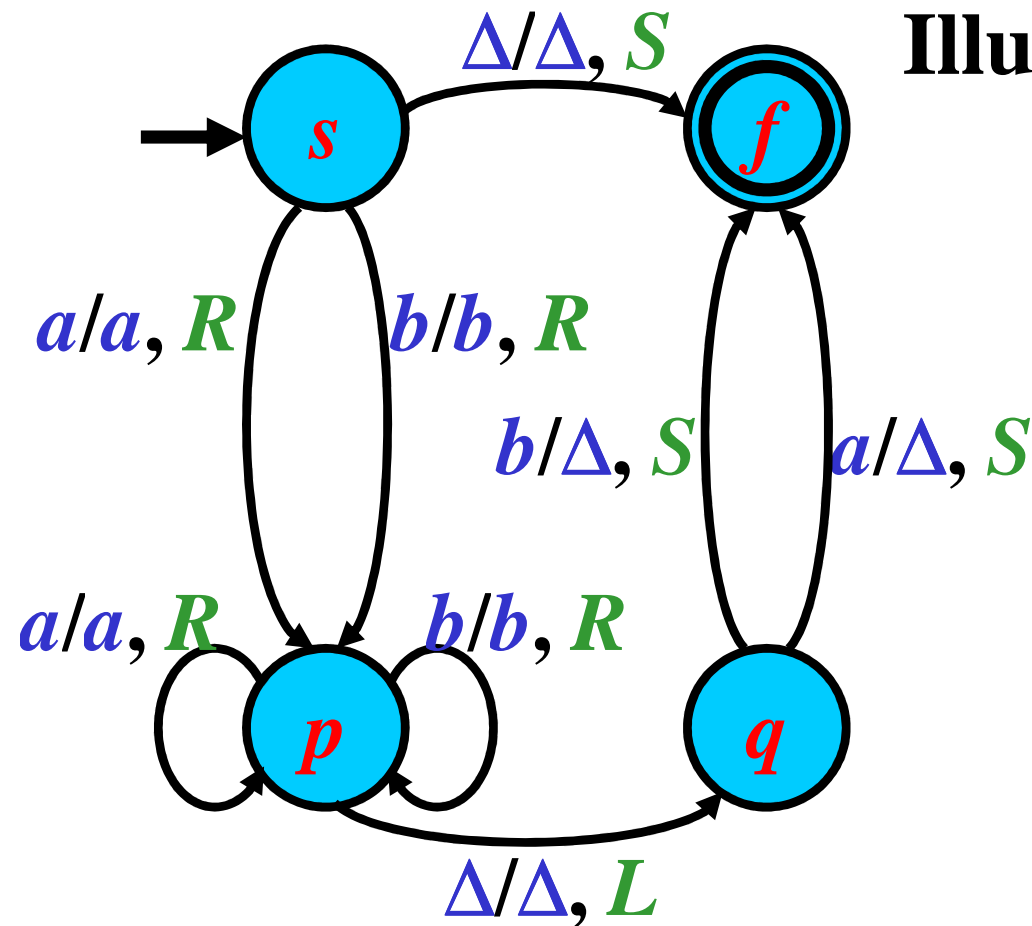
**Illustration:**





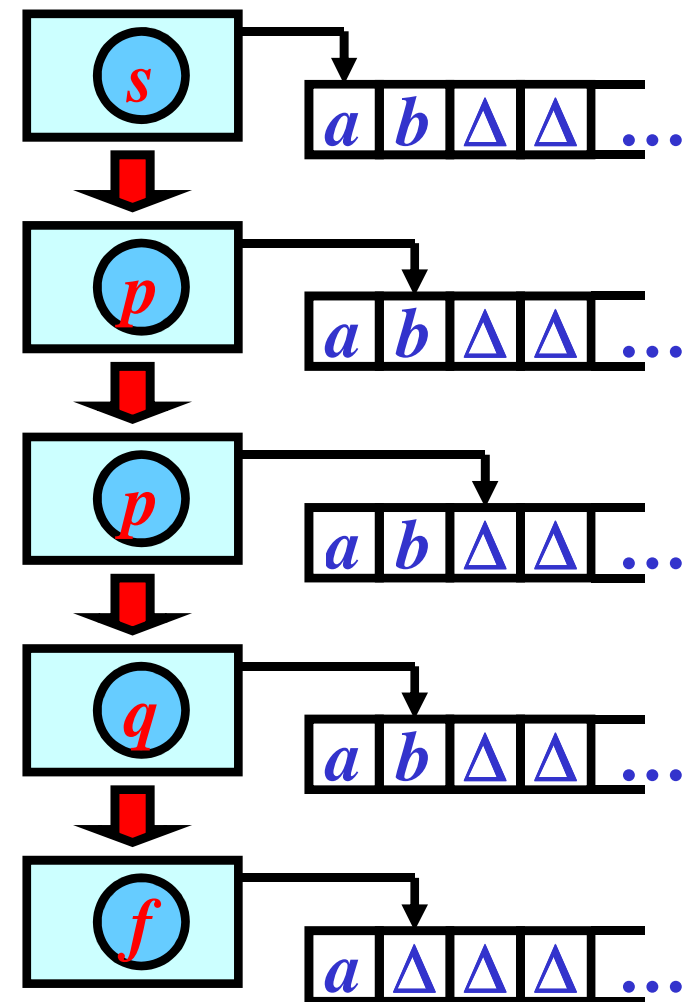
# Turing Machine: Example 2/2

TM  $M$ :



**Note:**  $M$  deletes a symbol before the first occurrence of  $\Delta$ :

**Illustration:**

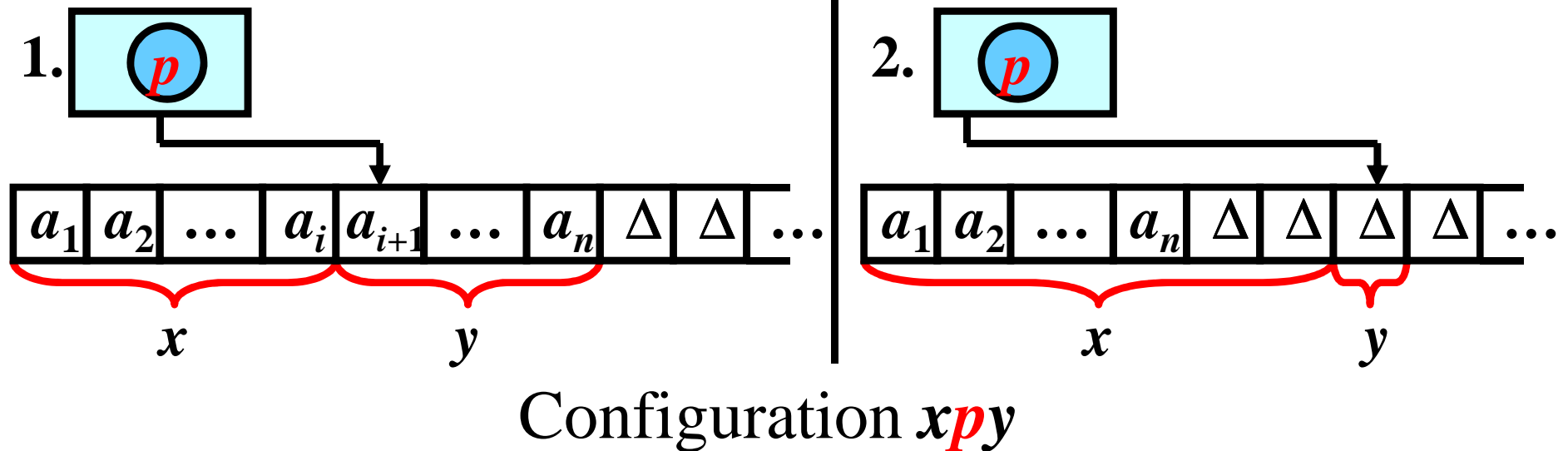


# TM Configuration

## Gist: Instantaneous description of TM

What does a configuration describes?

1) Current state 2) Tape Contents 3) Position of the head



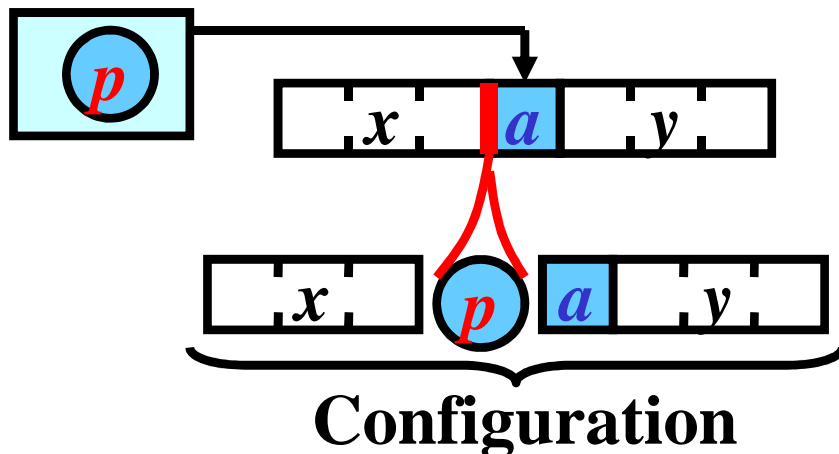
**Definition:** Let  $M = (Q, \Sigma, \Gamma, R, s, F)$  be a TM.  
 A *configuration* of  $M$  is a string  $\chi = xpy$ , where  
 $x \in \Gamma^*$ ,  $p \in Q$ ,  $y \in \Gamma^*(\Gamma - \{\Delta\}) \cup \{\Delta\}$ .

# Stationary Move

**Definition:** Let  $\chi, \chi'$  be two configurations of  $M$ . Then,  $M$  makes a *stationary move* from  $\chi$  to  $\chi'$  according to  $r$ , written as  $\chi \vdash_s \chi' [r]$  or, simply,  $\chi \vdash_s \chi'$  if

$$\chi = xpa y, \chi' = xqby \text{ and } r: pa \rightarrow qbS \in R$$

**Illustration:**

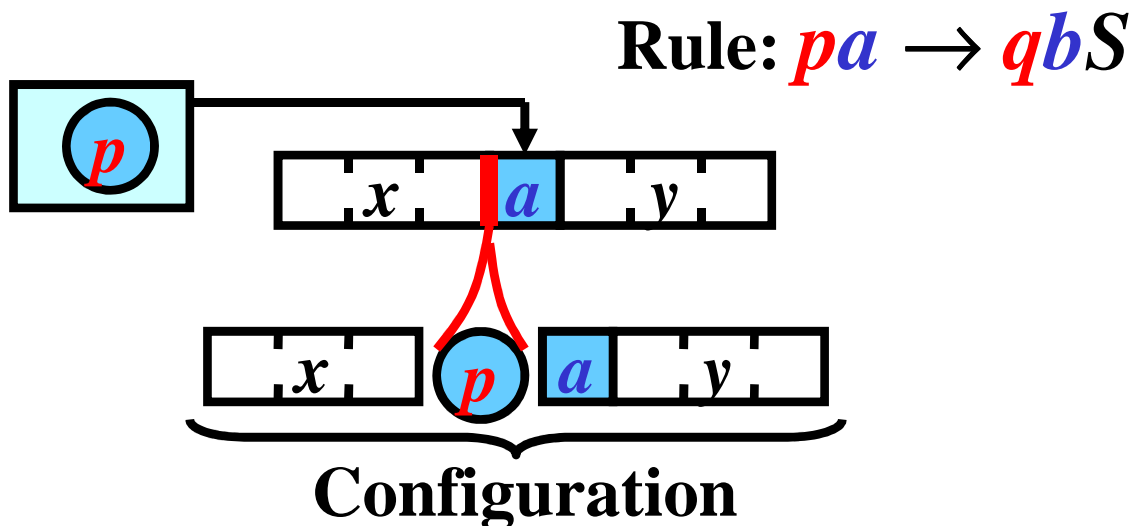


# Stationary Move

**Definition:** Let  $\chi, \chi'$  be two configurations of  $M$ . Then,  $M$  makes a *stationary move* from  $\chi$  to  $\chi'$  according to  $r$ , written as  $\chi \vdash_s \chi' [r]$  or, simply,  $\chi \vdash_s \chi'$  if

$$\chi = xpay, \chi' = xqby \text{ and } r: pa \rightarrow qbS \in R$$

**Illustration:**

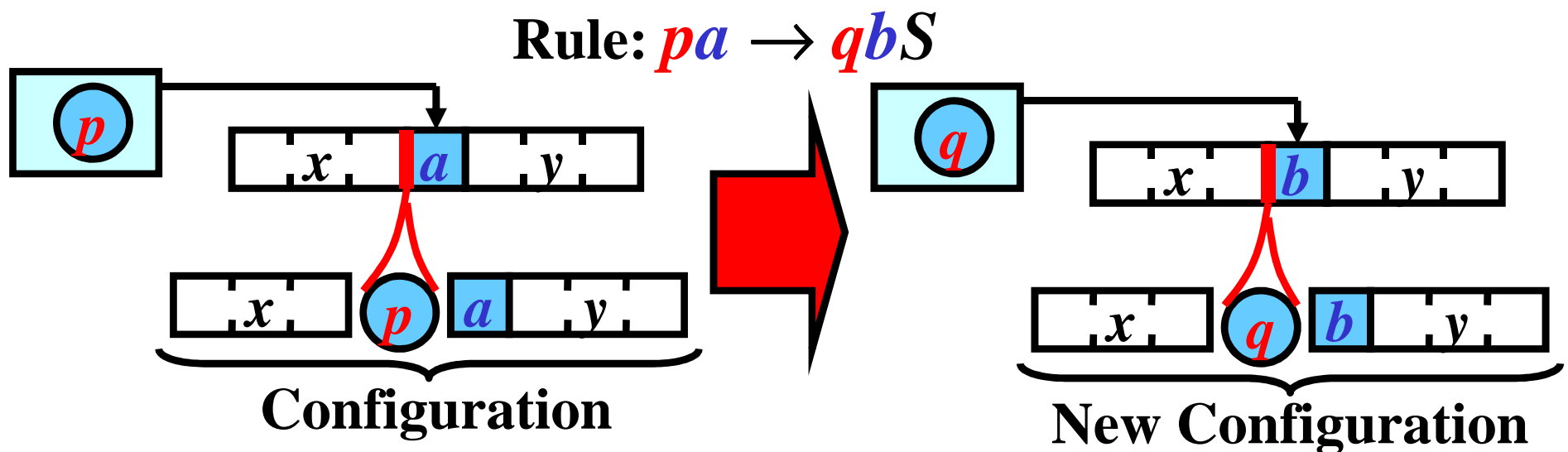


# Stationary Move

**Definition:** Let  $\chi, \chi'$  be two configurations of  $M$ . Then,  $M$  makes a *stationary move* from  $\chi$  to  $\chi'$  according to  $r$ , written as  $\chi \vdash_s \chi' [r]$  or, simply,  $\chi \vdash_s \chi'$  if

$$\chi = x p a y, \chi' = x q b y \text{ and } r: p a \rightarrow q b S \in R$$

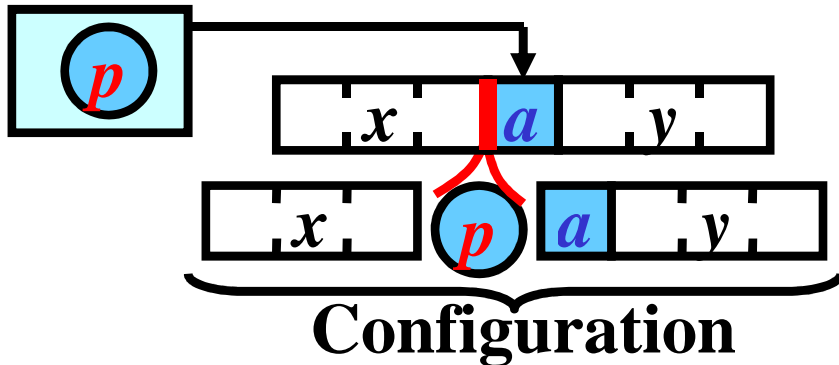
**Illustration:**



# Right Move

**Definition:** Let  $\chi, \chi'$  be two configurations of  $M$ . Then,  $M$  makes a *right move* from  $\chi$  to  $\chi'$  according to  $r$ , written as  $\chi \vdash_R \chi' [r]$  or, simply,  $\chi \vdash_R \chi'$  if  $\chi = xpay$ ,  $r: pa \rightarrow qb$ ,  $R \in R$  and

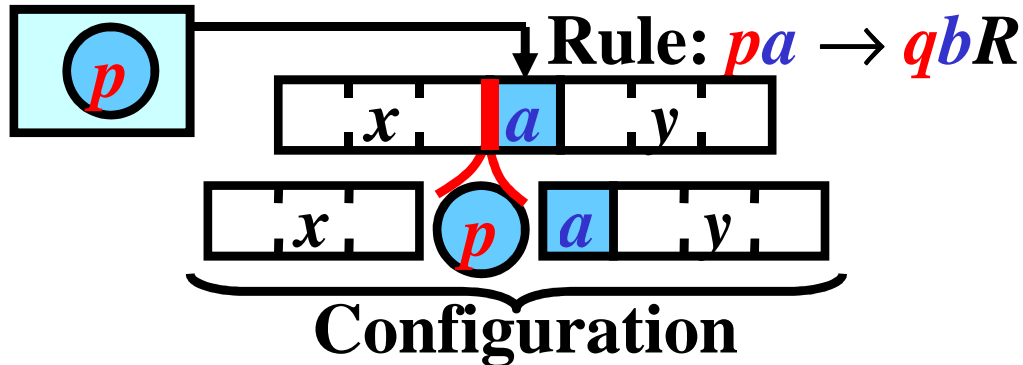
- (1)  $\chi' = x bqy$ ,  $y \neq \varepsilon$  or
- (2)  $\chi' = x bq\Delta$ ,  $y = \varepsilon$



# Right Move

**Definition:** Let  $\chi, \chi'$  be two configurations of  $M$ . Then,  $M$  makes a *right move* from  $\chi$  to  $\chi'$  according to  $r$ , written as  $\chi \vdash_R \chi' [r]$  or, simply,  $\chi \vdash_R \chi'$  if  $\chi = xpay$ ,  $r: pa \rightarrow qbR \in R$  and

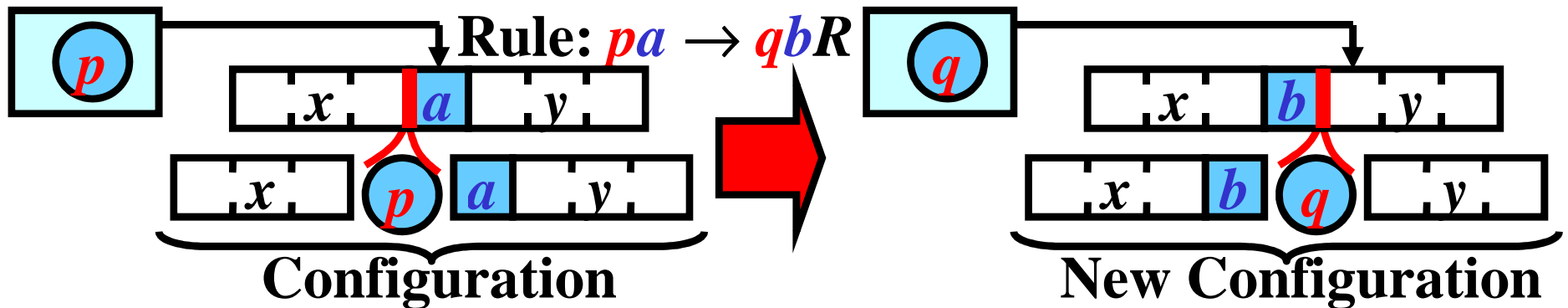
- (1)  $\chi' = x bqy$ ,  $y \neq \varepsilon$  or
- (2)  $\chi' = x bq\Delta$ ,  $y = \varepsilon$



# Right Move

**Definition:** Let  $\chi, \chi'$  be two configurations of  $M$ . Then,  $M$  makes a *right move* from  $\chi$  to  $\chi'$  according to  $r$ , written as  $\chi \vdash_R \chi' [r]$  or, simply,  $\chi \vdash_R \chi'$  if  $\chi = xpay$ ,  $r: pa \rightarrow qbR \in R$  and

- (1)  $\chi' = x bqy$ ,  $y \neq \varepsilon$  or
- (2)  $\chi' = x bq\Delta$ ,  $y = \varepsilon$

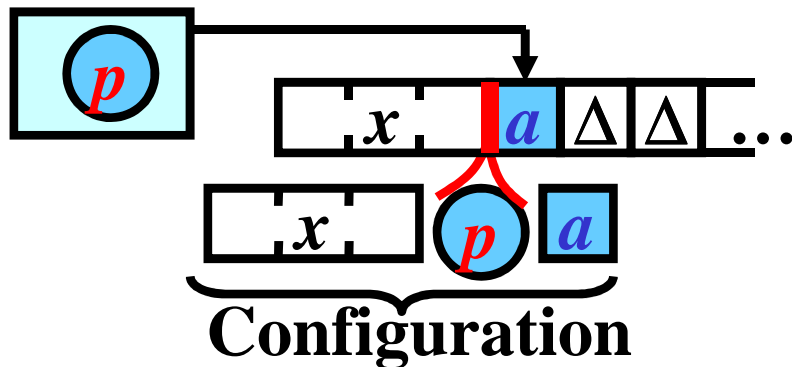
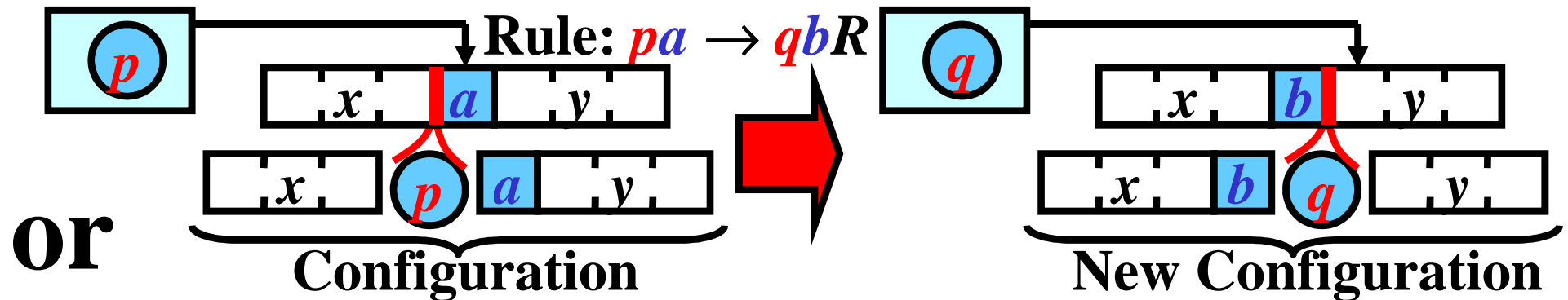




# Right Move

**Definition:** Let  $\chi, \chi'$  be two configurations of  $M$ . Then,  $M$  makes a *right move* from  $\chi$  to  $\chi'$  according to  $r$ , written as  $\chi \vdash_R \chi' [r]$  or, simply,  $\chi \vdash_R \chi'$  if  $\chi = xpay$ ,  $r: pa \rightarrow qbR \in R$  and

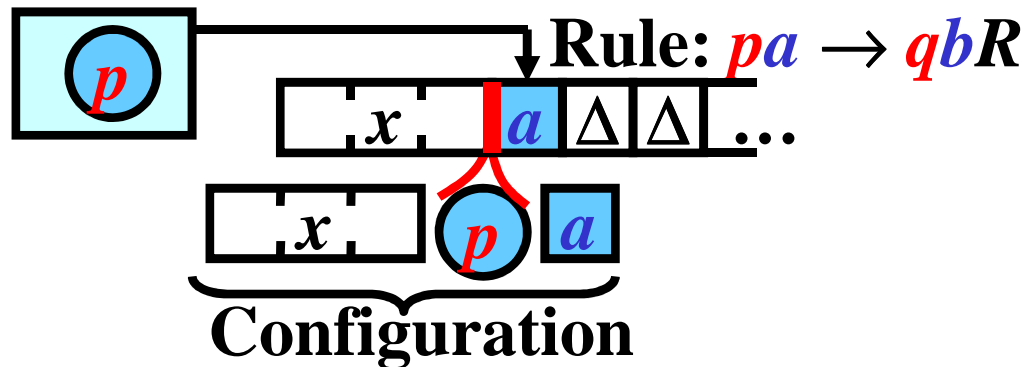
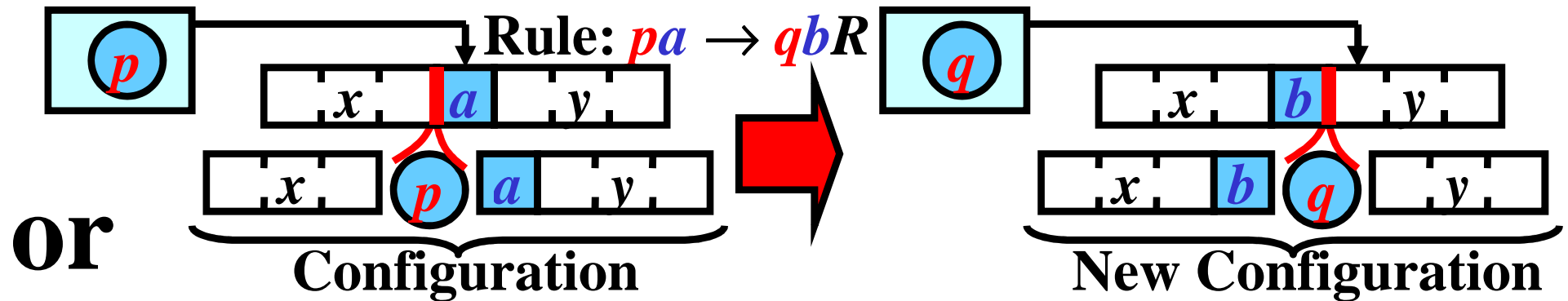
- (1)  $\chi' = x bqy$ ,  $y \neq \varepsilon$  or
- (2)  $\chi' = x bq\Delta$ ,  $y = \varepsilon$



# Right Move

**Definition:** Let  $\chi, \chi'$  be two configurations of  $M$ . Then,  $M$  makes a *right move* from  $\chi$  to  $\chi'$  according to  $r$ , written as  $\chi \vdash_R \chi' [r]$  or, simply,  $\chi \vdash_R \chi'$  if  $\chi = xpay$ ,  $r: pa \rightarrow qbR \in R$  and

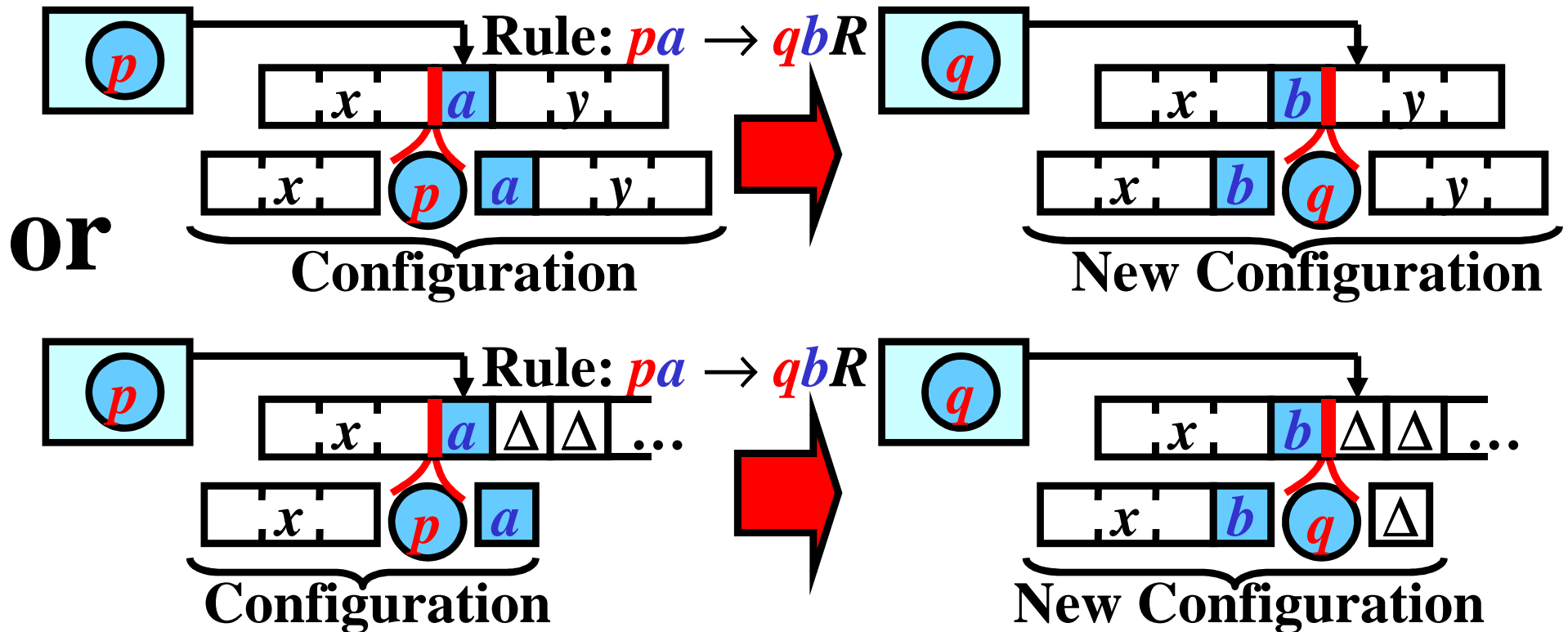
- (1)  $\chi' = x bqy$ ,  $y \neq \varepsilon$  or
- (2)  $\chi' = x bq\Delta$ ,  $y = \varepsilon$



# Right Move

**Definition:** Let  $\chi, \chi'$  be two configurations of  $M$ . Then,  $M$  makes a *right move* from  $\chi$  to  $\chi'$  according to  $r$ , written as  $\chi \vdash_R \chi' [r]$  or, simply,  $\chi \vdash_R \chi'$  if  $\chi = xpay$ ,  $r: pa \rightarrow qbR \in R$  and

- (1)  $\chi' = x bqy$ ,  $y \neq \varepsilon$  or
- (2)  $\chi' = x bq\Delta$ ,  $y = \varepsilon$

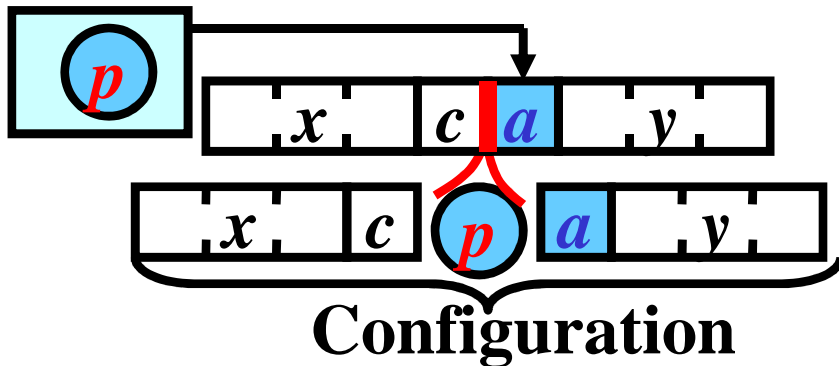


# Left Move

**Definition:** Let  $\chi, \chi'$  be two configurations of  $M$ . Then,  $M$  makes a *left move* from  $\chi$  to  $\chi'$  according to  $r$ , written as  $\chi \vdash_L \chi' [r]$  or, simply,  $\chi \vdash_L \chi'$  if

(1)  $\chi = xc\textcolor{red}{p}\textcolor{blue}{a}y$ ,  $\chi' = x\textcolor{red}{q}c\textcolor{blue}{b}y$ ,  $y \neq \varepsilon$  or  $\textcolor{blue}{b} \neq \Delta$ ,  $r: \textcolor{red}{p}\textcolor{blue}{a} \rightarrow \textcolor{red}{q}\textcolor{blue}{b}L \in R$  or

(2)  $\chi = xc\textcolor{red}{p}\textcolor{blue}{a}$ ,  $\chi' = x\textcolor{red}{q}c$ ,  $r: \textcolor{red}{p}\textcolor{blue}{a} \rightarrow \textcolor{red}{q}\Delta L \in R$

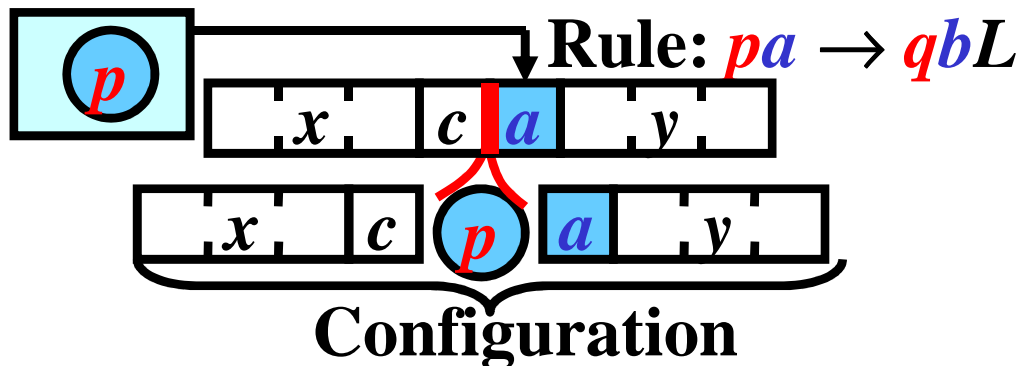


# Left Move

**Definition:** Let  $\chi, \chi'$  be two configurations of  $M$ . Then,  $M$  makes a *left move* from  $\chi$  to  $\chi'$  according to  $r$ , written as  $\chi \vdash_L \chi' [r]$  or, simply,  $\chi \vdash_L \chi'$  if

(1)  $\chi = xc\textcolor{red}{p}\textcolor{blue}{a}y$ ,  $\chi' = x\textcolor{red}{q}c\textcolor{blue}{b}y$ ,  $y \neq \varepsilon$  or  $\textcolor{blue}{b} \neq \Delta$ ,  $r: \textcolor{red}{p}\textcolor{blue}{a} \rightarrow \textcolor{red}{q}\textcolor{blue}{b}L \in R$  or

(2)  $\chi = xc\textcolor{red}{p}\textcolor{blue}{a}$ ,  $\chi' = x\textcolor{red}{q}c$ ,  $r: \textcolor{red}{p}\textcolor{blue}{a} \rightarrow \textcolor{red}{q}\Delta L \in R$

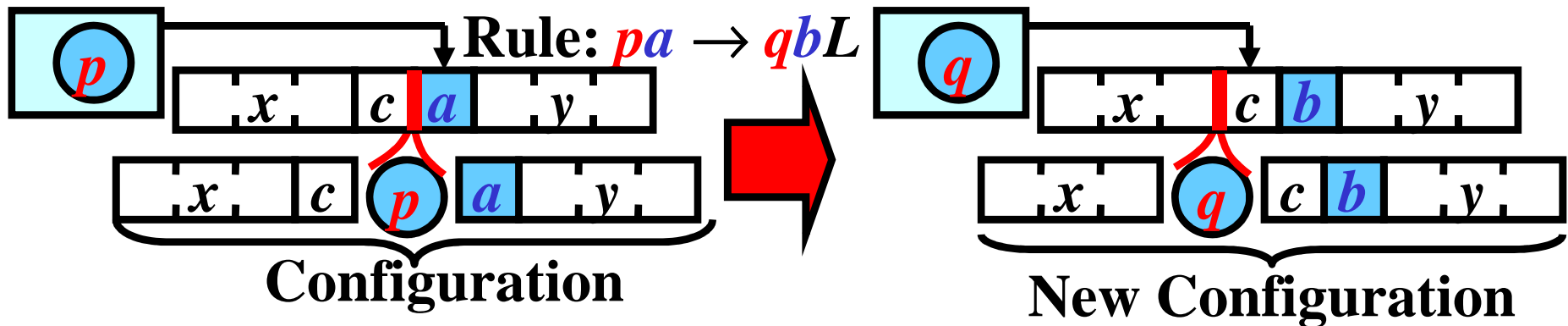


# Left Move

**Definition:** Let  $\chi, \chi'$  be two configurations of  $M$ . Then,  $M$  makes a *left move* from  $\chi$  to  $\chi'$  according to  $r$ , written as  $\chi \vdash_L \chi' [r]$  or, simply,  $\chi \vdash_L \chi'$  if

(1)  $\chi = xc\textcolor{red}{p}\textcolor{blue}{a}y$ ,  $\chi' = x\textcolor{red}{q}c\textcolor{blue}{b}y$ ,  $y \neq \varepsilon$  or  $\textcolor{blue}{b} \neq \Delta$ ,  $r: \textcolor{red}{p}\textcolor{blue}{a} \rightarrow \textcolor{red}{q}\textcolor{blue}{b}L \in R$  or

(2)  $\chi = xc\textcolor{red}{p}\textcolor{blue}{a}$ ,  $\chi' = x\textcolor{red}{q}c$ ,  $r: \textcolor{red}{p}\textcolor{blue}{a} \rightarrow \textcolor{red}{q}\Delta L \in R$

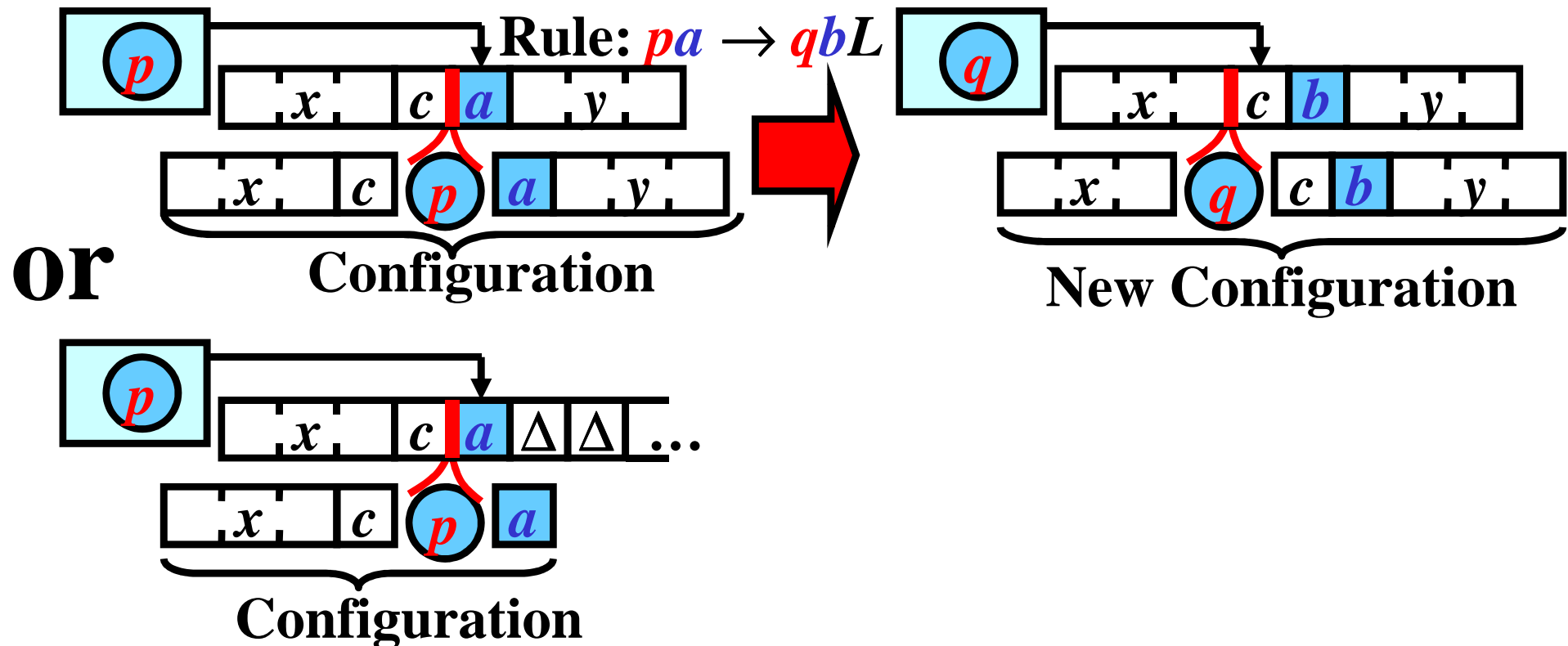


# Left Move

**Definition:** Let  $\chi, \chi'$  be two configurations of  $M$ . Then,  $M$  makes a *left move* from  $\chi$  to  $\chi'$  according to  $r$ , written as  $\chi \vdash_L \chi' [r]$  or, simply,  $\chi \vdash_L \chi'$  if

(1)  $\chi = xc\textcolor{red}{p}\textcolor{blue}{a}y$ ,  $\chi' = x\textcolor{red}{q}c\textcolor{blue}{b}y$ ,  $y \neq \varepsilon$  or  $\textcolor{blue}{b} \neq \Delta$ ,  $r: \textcolor{red}{p}\textcolor{blue}{a} \rightarrow \textcolor{red}{q}\textcolor{blue}{b}L \in R$  or

(2)  $\chi = xc\textcolor{red}{p}\textcolor{blue}{a}$ ,  $\chi' = x\textcolor{red}{q}c$ ,  $r: \textcolor{red}{p}\textcolor{blue}{a} \rightarrow \textcolor{red}{q}\Delta L \in R$

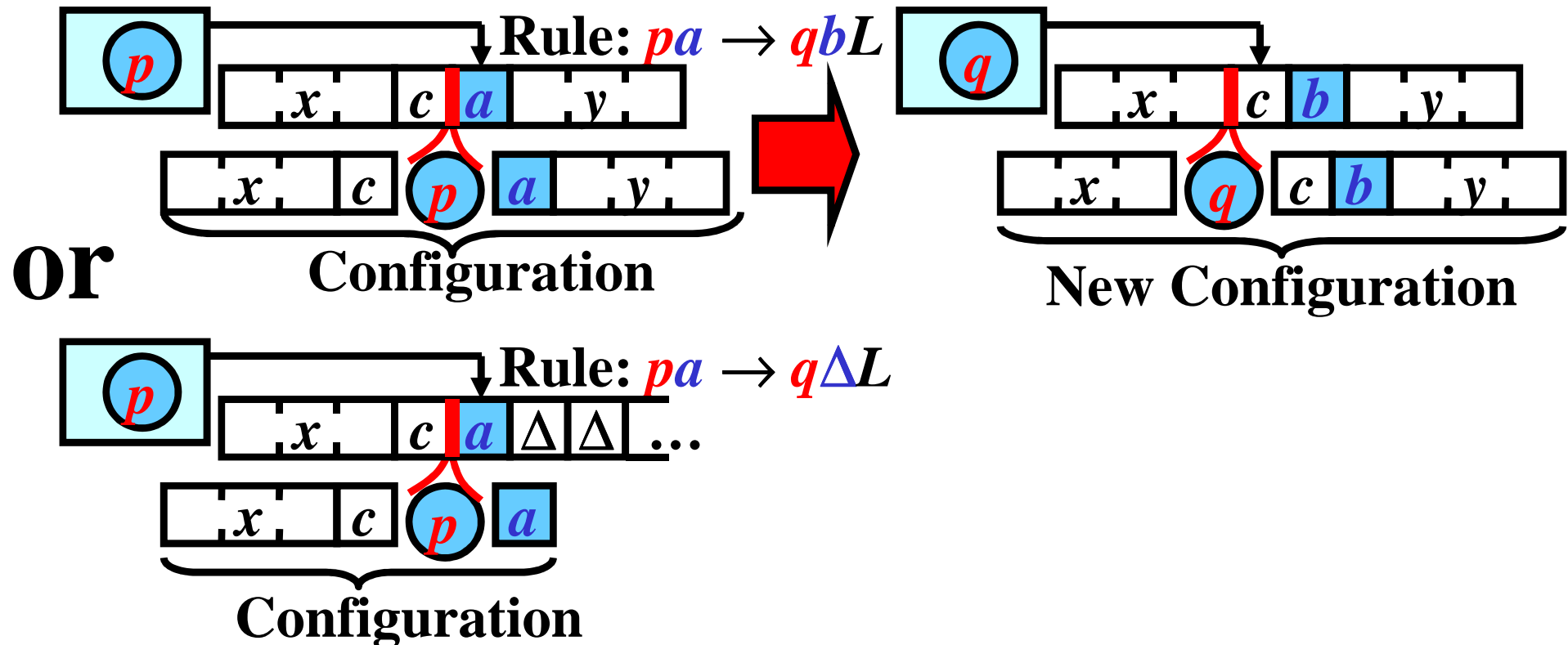


# Left Move

**Definition:** Let  $\chi, \chi'$  be two configurations of  $M$ . Then,  $M$  makes a *left move* from  $\chi$  to  $\chi'$  according to  $r$ , written as  $\chi \vdash_L \chi' [r]$  or, simply,  $\chi \vdash_L \chi'$  if

(1)  $\chi = xc\textcolor{red}{p}\textcolor{blue}{a}y$ ,  $\chi' = x\textcolor{red}{q}c\textcolor{blue}{b}y$ ,  $y \neq \varepsilon$  or  $\textcolor{blue}{b} \neq \Delta$ ,  $r: \textcolor{red}{p}\textcolor{blue}{a} \rightarrow \textcolor{red}{q}\textcolor{blue}{b}L \in R$  or

(2)  $\chi = xc\textcolor{red}{p}\textcolor{blue}{a}$ ,  $\chi' = x\textcolor{red}{q}c$ ,  $r: \textcolor{red}{p}\textcolor{blue}{a} \rightarrow \textcolor{red}{q}\Delta L \in R$



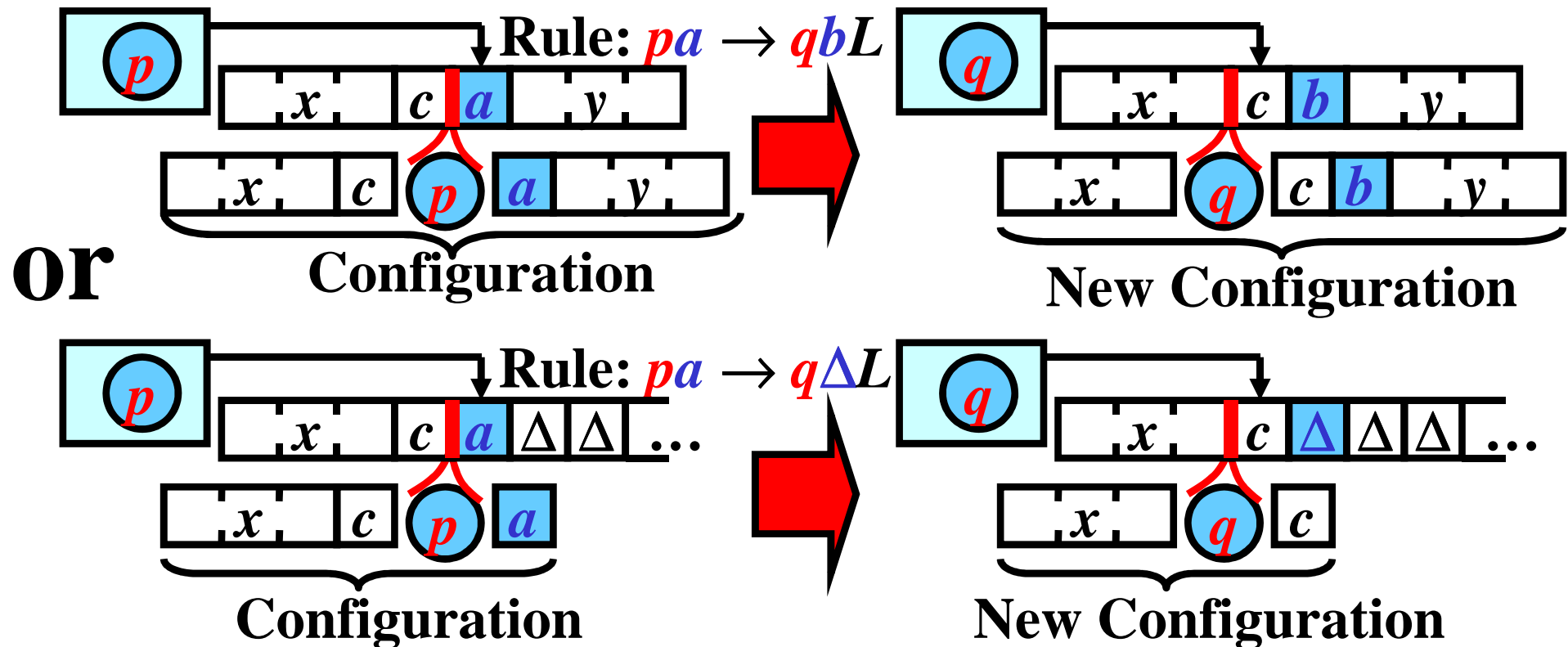


# Left Move

**Definition:** Let  $\chi, \chi'$  be two configurations of  $M$ . Then,  $M$  makes a *left move* from  $\chi$  to  $\chi'$  according to  $r$ , written as  $\chi \vdash_L \chi' [r]$  or, simply,  $\chi \vdash_L \chi'$  if

(1)  $\chi = xc\textcolor{red}{p}\textcolor{blue}{a}y$ ,  $\chi' = x\textcolor{red}{q}c\textcolor{blue}{b}y$ ,  $y \neq \varepsilon$  or  $\textcolor{blue}{b} \neq \Delta$ ,  $r: \textcolor{red}{p}\textcolor{blue}{a} \rightarrow \textcolor{red}{q}\textcolor{blue}{b}L \in R$  or

(2)  $\chi = xc\textcolor{red}{p}\textcolor{blue}{a}$ ,  $\chi' = x\textcolor{red}{q}c$ ,  $r: \textcolor{red}{p}\textcolor{blue}{a} \rightarrow \textcolor{red}{q}\Delta L \in R$



# Move

**Definition:** Let  $\chi, \chi'$  be two configurations of  $M$ . Then,  $M$  makes a *move* from  $\chi$  to  $\chi'$  according to a rule  $r$ , written as  $\chi \vdash \chi' [r]$  or, simply,  $\chi \vdash \chi'$  if  $\chi \vdash_X \chi' [r]$  for some  $X \in \{S, R, L\}$ .

## Sequence of Moves 1/2

**Gist: Several consecutive computational steps**

**Definition:** Let  $\chi$  be a configuration.  $M$  makes *zero moves* from  $\chi$  to  $\chi$ ; in symbols,

$$\chi \vdash^0 \chi [\varepsilon] \text{ or, simply, } \chi \vdash^0 \chi$$

**Definition:** Let  $\chi_0, \chi_1, \dots, \chi_n$  be a sequence of configurations,  $n \geq 1$ , and  $\chi_{i-1} \vdash \chi_i [r_i]$ ,  $r_i \in R$ , for all  $i = 1, \dots, n$ ; that is,

$$\chi_0 \vdash \chi_1 [r_1] \vdash \chi_2 [r_2] \dots \vdash \chi_n [r_n]$$

Then,  $M$  makes *n moves* from  $\chi_0$  to  $\chi_n$ ,

$$\chi_0 \vdash^n \chi_n [r_1 \dots r_n] \text{ or, simply, } \chi_0 \vdash^n \chi_n$$

## Sequence of Moves 2/2

If  $\chi_0 \vdash^n \chi_n [\rho]$  for some  $n \geq 1$ , then

$\chi_0 \vdash^+ \chi_n [\rho]$  or, simply,  $\chi_0 \vdash^+ \chi_n$

If  $\chi_0 \vdash^n \chi_n [\rho]$  for some  $n \geq 0$ , then

$\chi_0 \vdash^* \chi_n [\rho]$  or, simply,  $\chi_0 \vdash^* \chi_n$

**Example:** Consider

$apbc \vdash aqac$  [1:  $pb \rightarrow qaS$ ], and

$aqac \vdash acrc$  [2:  $qa \rightarrow rcR$ ].

Then,  $apbc \vdash^2 acrc$  [1 2],

$apbc \vdash^+ acrc$  [1 2],

$apbc \vdash^* acrc$  [1 2]

# TM as a Language Acceptor

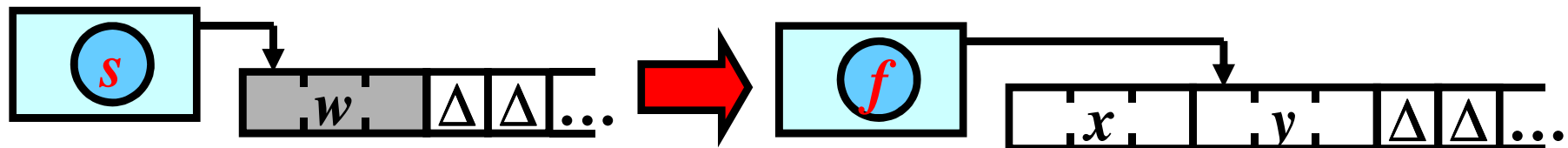
**Gist:  $M$  accepts  $w$  by a sequence of moves from  $s$  to a final state.**

**Definition:** Let  $M = (Q, \Sigma, \Gamma, R, s, F)$  be a TM. The *language accepted by  $M$* ,  $L(M)$ , is defined as:

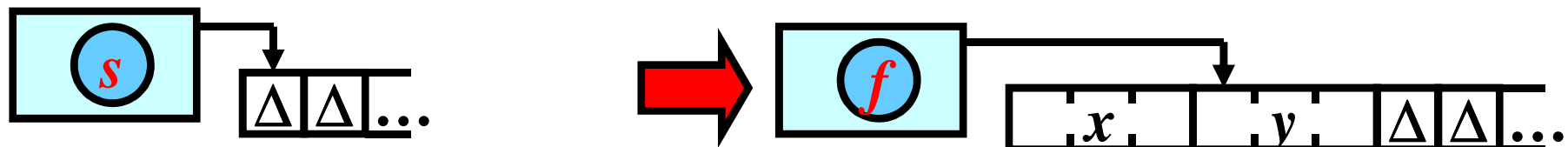
$$L(M) = \{w: w \in \Sigma^*, sw \vdash^* xfy; x, y \in \Gamma^*, f \in F\} \cup \{\varepsilon: s\Delta \vdash^* xfy; x, y \in \Gamma^*, f \in F\}$$

## Illustration:

- For  $w \neq \varepsilon$ :

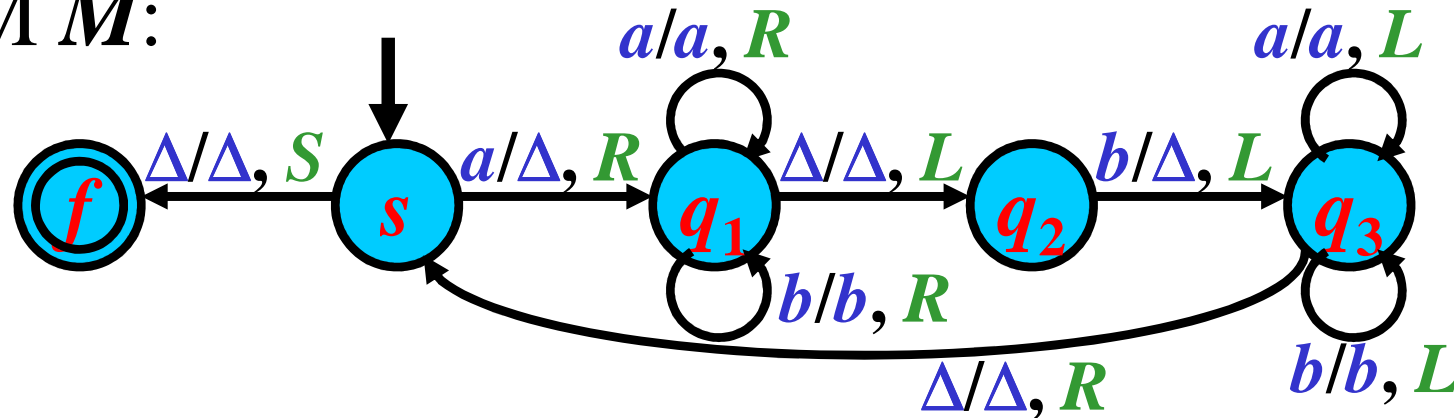


- For  $w = \varepsilon$ :



# TM as an Acceptor: Example

TM  $M$ :




---

$sabba \mid - \Delta q_1 abb \mid - \Delta a q_1 bb \mid - \Delta ab q_1 b \mid - \Delta abb q_1 \Delta \mid - \Delta ab q_2 b$   
 $\mid - \Delta a q_3 b \mid - \Delta q_3 ab \mid - q_3 \Delta ab \mid - \Delta sab \mid - \Delta \Delta q_1 b \mid - \Delta \Delta q_1 b$   
 $\mid - \Delta \Delta b q_1 \Delta \mid - \Delta \Delta q_2 b \mid - \Delta q_3 \Delta \mid - s \Delta \mid - f \Delta$

---

**Summary:**  $abba \in L(M)$

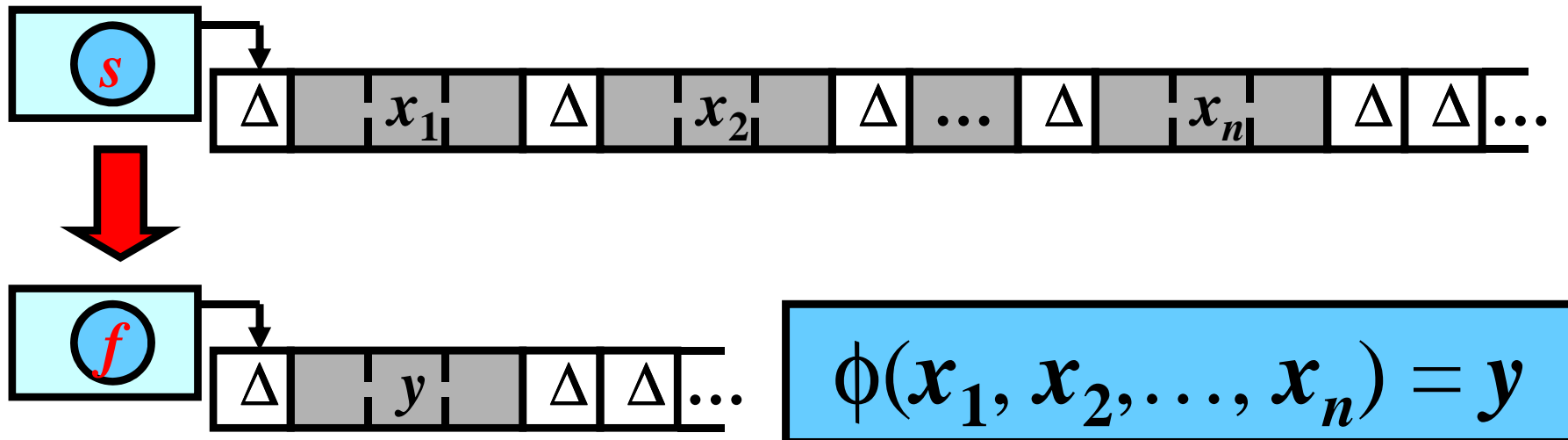
---

**Note:**  $L(M) = \{a^n b^n : n \geq 0\}$

# TM as a Computational Model

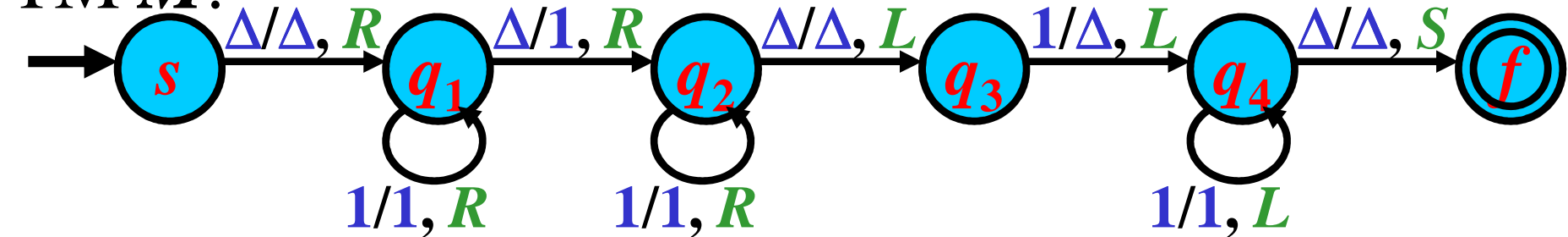
**Definition:** Let  $M = (Q, \Sigma, \Gamma, R, s, F)$  be a TM;  
*n*-place function  $\phi$  is computed by  $M$  provided that  
 $s \Delta x_1 \Delta x_2 \dots \Delta x_n \vdash^* f \Delta y$  with  $f \in F$  if and only if  
 $\phi(x_1, x_2, \dots, x_n) = y$ .

**Illustration:**



# TM as a Computational Model: Example

TM  $M$ :



$s\Delta 11\Delta 11 \mid - \Delta q_1 11 \Delta 11 \mid - \Delta 1 q_1 1 \Delta 11 \mid - \Delta 11 q_1 \Delta 11 \mid - \Delta 111 q_2 11$   
 $\mid - \Delta 1111 q_2 1 \mid - \Delta 11111 q_2 \Delta \mid - \Delta 1111 q_3 1 \mid - \Delta 111 q_4 1$   
 $\mid - \Delta 11 q_4 11 \mid - \Delta 1 q_4 111 \mid - \Delta q_4 1111 \mid - q_4 \Delta 1111$   
 $\mid - f \Delta 1111$

**Summary:**  $\phi(11, 11) = 1111$

**Note:**  $\phi(x_1, x_2) = x_1 + x_2$ , where

- $x_1 = 1^a$  represents a natural number  $a$
- $x_2 = 1^b$  represents a natural number  $b$



# Deterministic Turing Machine (DTM)

**Gist: Deterministic TM makes no more than one move from any configuration.**

**Definition:** Let  $M = (Q, \Sigma, \Gamma, R, s, F)$  be a TM.  $M$  is a *deterministic TM* if for each rule  $pa \rightarrow qbt \in R$  it holds that  $R - \{pa \rightarrow qbt\}$  contains no rule with the left-hand side equal to  $pa$ .

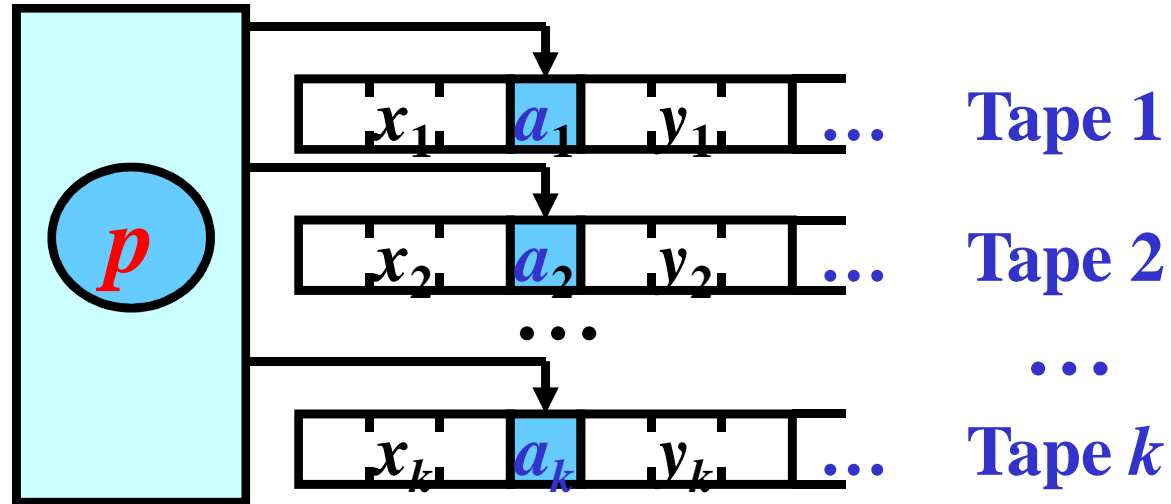
**Theorem:** For every TM  $M$ , there is an equivalent DTM  $M_d$ .

**Proof:** See page 634 in [Meduna: Automata and Languages]

# $k$ -Tape Turing Machine

**Gist:** Turing machine with  $k$  tapes

**Illustration:**



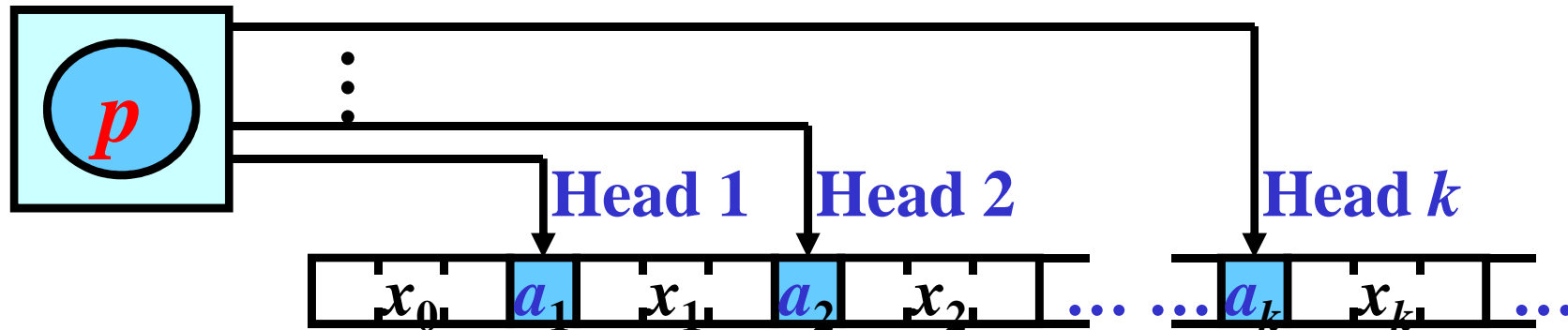
**Theorem:** For every  $k$ -tape TM  $M_t$ , there is an equivalent TM  $M$ .

**Proof:** See page 662 in [Meduna: Automata and Languages]

# $k$ -Head Turing Machine

**Gist: Turing machine with  $k$  heads**

**Illustration:**



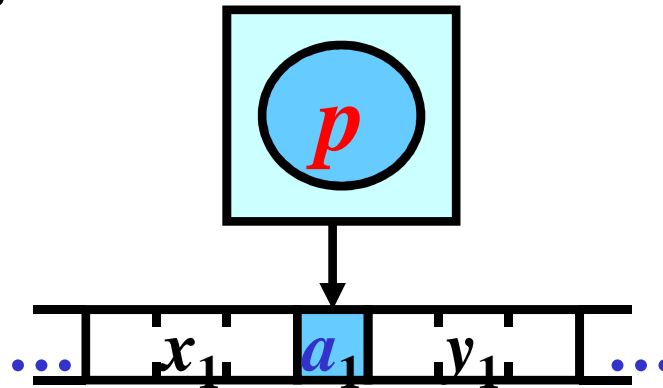
**Theorem:** For every  $k$ -head TM  $M_h$ , there is an equivalent TM  $M$ .

**Proof:** See page 667 in [Meduna: Automata and Languages]

# TM with Two-way Infinite Tapes

**Gist:** Turing machine with tape infinite both to the right and to the left

**Illustration:**



**Theorem:** For every TM with two-way infinite tapes  $M_b$ , there is an equivalent TM  $M$ .

**Proof:** See page 673 in [Meduna: Automata and Languages]

# Description of a Turing Machine

**Gist: Turing machine representation using a string over  $\{0, 1\}$**

- Assume that TM  $M$  has the form  $M = (Q, \Sigma, \Gamma, R, q_0, \{q_1\})$ , where  $Q = \{q_0, q_1, \dots, q_m\}$ ,  $\Gamma = \{a_0, a_1, \dots, a_n\}$  so that  $a_0 = \Delta$
- Let  $\delta$  is the mapping from  $(Q \cup \Gamma \cup \{S, L, R\})$  to  $\{0, 1\}^*$

defined as:

$$\begin{aligned}\delta(S) &= 01, \delta(L) = 001, \delta(R) = 0001, \\ \delta(q_i) &= 0^{i+1}1 \text{ for all } i = 0 \dots m, \\ \delta(a_i) &= 0^{i+1}1 \text{ for all } i = 0 \dots n\end{aligned}$$

- For every  $r: pa \rightarrow qbt \in R$  we define

$$\delta(r) = \delta(p)\delta(a)\delta(q)\delta(b)\delta(t)1$$

- Let  $R = \{r_0, r_1, \dots, r_k\}$ . Then

$\delta(M) = 111\delta(r_0)\delta(r_1)\dots\delta(r_k)1$  is the description of TM  $M$

# Description of TM: Example

$M = (Q, \Sigma, \Gamma, R, q_0, \{q_1\})$ , where

$Q = \{q_0, q_1\}$ ;  $\Sigma = \{a_1, a_2\}$ ;  $\Gamma = \{\Delta, a_1, a_2\}$ ;

$R = \{1: q_0 a_1 \rightarrow q_0 a_2 R, 2: q_0 a_2 \rightarrow q_0 a_1 R, 3: q_0 \Delta \rightarrow q_1 \Delta S\}$

**Task:** Description of  $M$ ,  $\delta(M)$ .

$\delta(S) = 01$ ,  $\delta(L) = 001$ ,  $\delta(R) = 0001$ ,

$\delta(q_0) = 01$ ,  $\delta(q_1) = 001$ ,

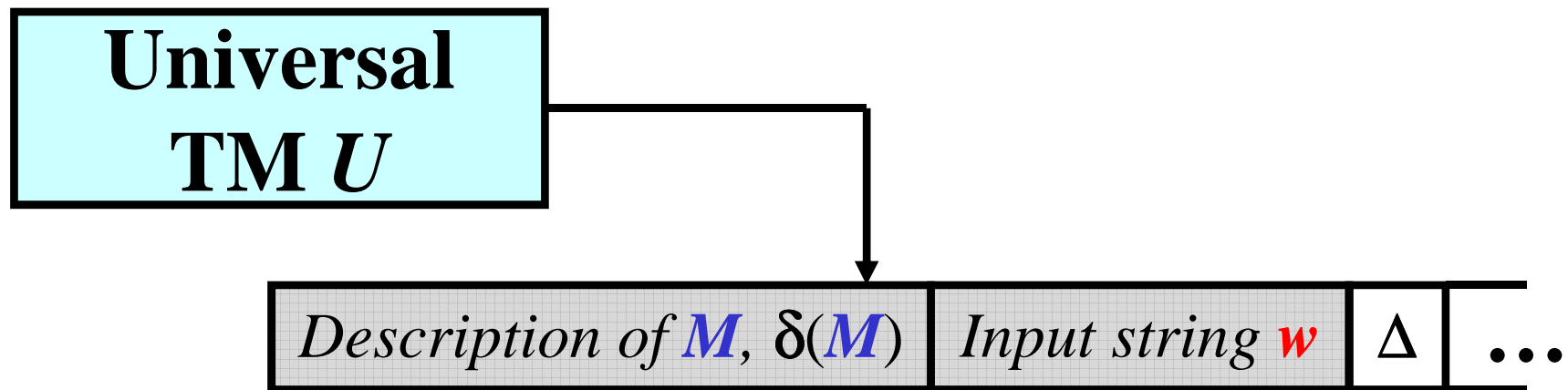
$\delta(\Delta) = 01$ ,  $\delta(a_1) = 001$ ,  $\delta(a_2) = 0001$ .

$$\begin{aligned}
 \delta(M) &= 111\delta(1)\delta(2)\delta(3)1 \\
 &= 111\delta(q_0)\delta(a_1)\delta(q_0)\delta(a_2)\delta(R)1 \\
 &\quad \delta(q_0)\delta(a_2)\delta(q_0)\delta(a_1)\delta(R)1 \\
 &\quad \delta(q_0)\delta(\Delta)\delta(q_1)\delta(\Delta)\delta(S)11 \\
 &= 1110100101000100011 \\
 &\quad 0100010100100011 \\
 &\quad 0101001010111
 \end{aligned}$$

# Universal Turing Machine

**Gist: Universal TM can simulate every DTM**

**Illustration:**



**Note:** Universal TM  $U$  reads the description of TM  $M$ , and the input string  $w$ , and then simulates the moves that  $M$  makes with  $w$ .

# Unrestricted Grammar: Definition

## Gist: Generalization of CFG

**Definition:** An *unrestricted grammar* (URG) is a quadruple  $G = (N, T, P, S)$ , where

- $N$  is an alphabet of *nonterminals*
- $T$  is an alphabet of *terminals*,  $N \cap T = \emptyset$
- $P$  is a finite set of *rules* of the form  $x \rightarrow y$ ,  
where  $x \in (N \cup T)^* N (N \cup T)^*$ ,  $y \in (N \cup T)^*$
- $S \in N$  is the *start nonterminal*

### Mathematical Note on Rules:

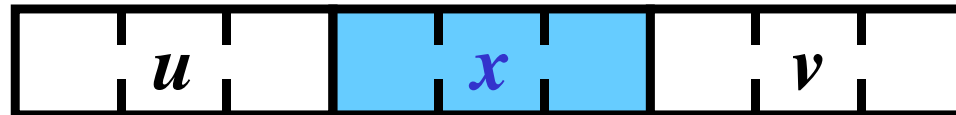
- Strictly mathematically,  $P$  is a finite relation from  $(N \cup T)^* N (N \cup T)^*$  to  $(N \cup T)^*$
- Instead of  $(x, y) \in P$ , we write  $x \rightarrow y \in P$



# Derivation Step

**Gist: A change of a string by a rule.**

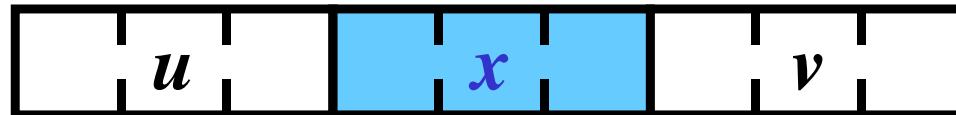
**Definition:** Let  $G = (N, T, P, S)$  be a URG. Let  $u, v \in (N \cup T)^*$  and  $p: x \rightarrow y \in P$ . Then,  $uxv$  *directly derives*  $uyv$  according to  $p$  in  $G$ , written as  $uxv \Rightarrow uyv [p]$  or, simply,  $uxv \Rightarrow uyv$ .



# Derivation Step

**Gist: A change of a string by a rule.**

**Definition:** Let  $G = (N, T, P, S)$  be a URG. Let  $u, v \in (N \cup T)^*$  and  $p: x \rightarrow y \in P$ . Then,  $uxv$  directly derives  $uyv$  according to  $p$  in  $G$ , written as  $uxv \Rightarrow uyv [p]$  or, simply,  $uxv \Rightarrow uyv$ .

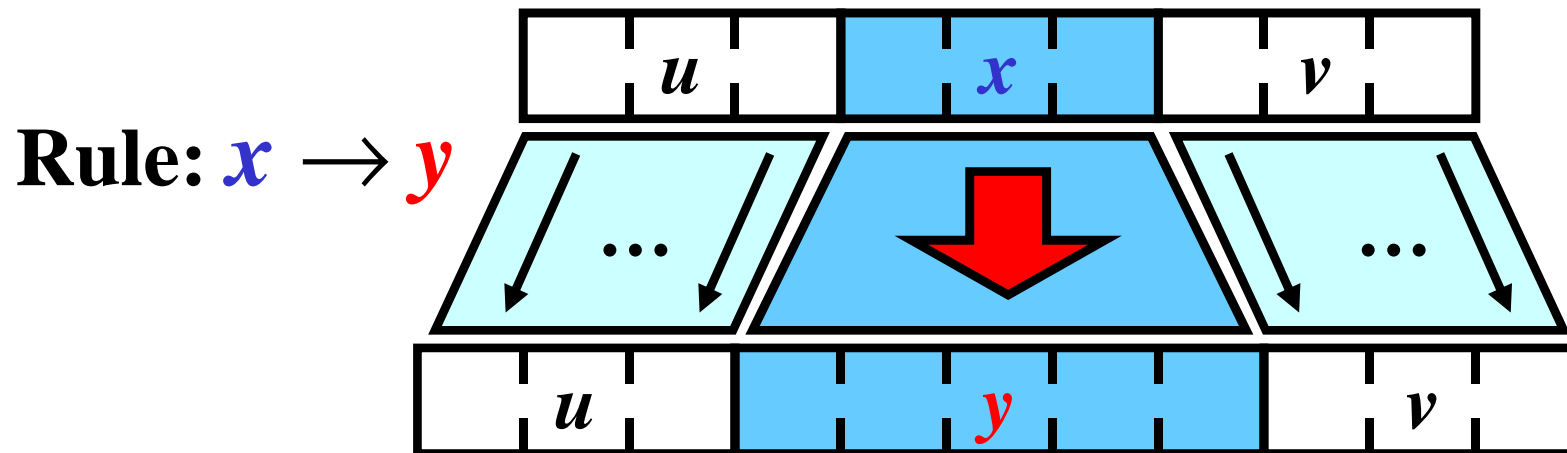


**Rule:**  $x \rightarrow y$

# Derivation Step

**Gist: A change of a string by a rule.**

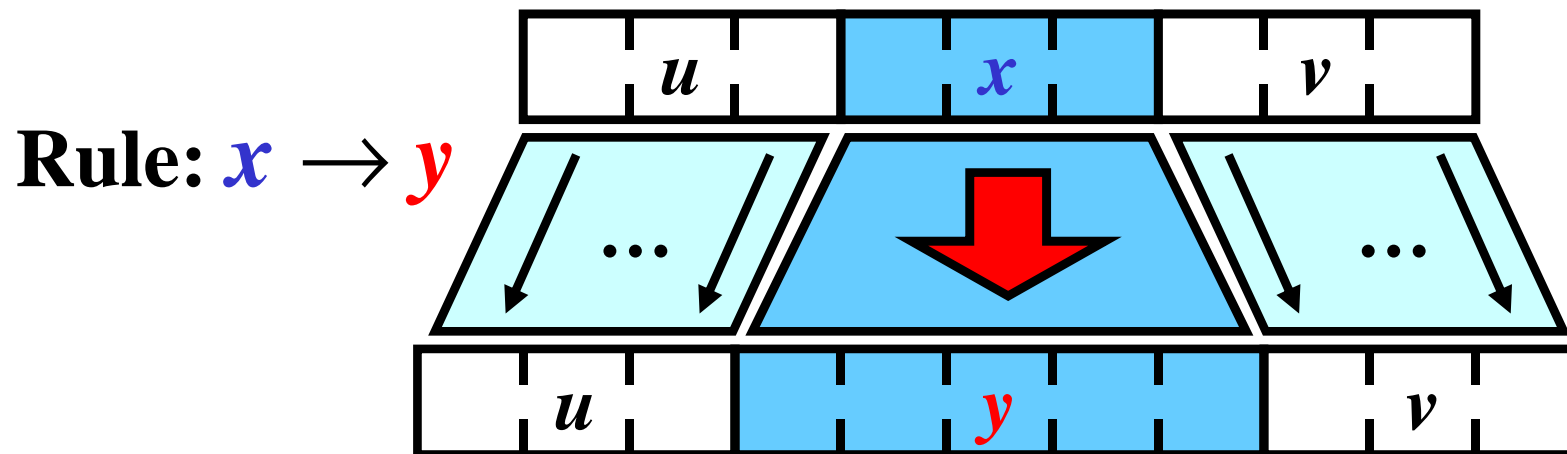
**Definition:** Let  $G = (N, T, P, S)$  be a URG. Let  $u, v \in (N \cup T)^*$  and  $p: x \rightarrow y \in P$ . Then,  $uxv$  directly derives  $uyv$  according to  $p$  in  $G$ , written as  $uxv \Rightarrow uyv [p]$  or, simply,  $uxv \Rightarrow uyv$ .



# Derivation Step

**Gist: A change of a string by a rule.**

**Definition:** Let  $G = (N, T, P, S)$  be a URG. Let  $u, v \in (N \cup T)^*$  and  $p: x \rightarrow y \in P$ . Then,  $uxv$  directly derives  $uyv$  according to  $p$  in  $G$ , written as  $uxv \Rightarrow uyv [p]$  or, simply,  $uxv \Rightarrow uyv$ .



**Note:**  $\Rightarrow^n$ ,  $\Rightarrow^+$ ,  $\Rightarrow^*$  and  $L(G)$  are defined by analogy with the corresponding definitions in terms of CFGs.

# Unrestricted Grammar: Example

$G = (N, T, P, S)$ , where  $N = \{S, A, B\}$ ,  $T = \{a\}$

$P = \{$  1:  $S \rightarrow ASB$ , 2:  $S \rightarrow a$ ,  
3:  $Aa \rightarrow aaA$ , 4:  $AB \rightarrow \varepsilon$   $\}$

---

$S \Rightarrow a$  [2]

$S \Rightarrow \underline{A}SB$  [1]  $\Rightarrow \underline{A}aB$  [2]  $\Rightarrow aa\underline{AB}$  [3]  $\Rightarrow aa$  [4]

$S \Rightarrow \underline{A}SB$  [1]  $\Rightarrow AA\underline{S}BB$  [1]  $\Rightarrow AA\underline{A}BB$  [2]  $\Rightarrow$   
 $\underline{A}aaABB$  [3]  $\Rightarrow aa\underline{A}aABB$  [3]  $\Rightarrow$   
 $aaaaA\underline{ABB}$  [3]  $\Rightarrow aaaa\underline{AB}$  [4]  $\Rightarrow aaaa$  [4]  
 $\vdots$

---

**Note:**  $L(G) = \{a^{2^n} : n \geq 0\}$

# Recursively Enumerable Languages

**Definition:** Let  $L$  be a language.  $L$  is a *resurcively enumerable language* if there exists a Turing machine  $M$  that  $L = L(M)$ .

**Theorem:** For every URG  $G$ , there is a TM  $M$  such that  $L(G) = L(M)$ .

**Proof:** See page 714 in [Meduna: Automata and Languages]

**Theorem:** For every TM  $M$ , there is a URG  $G$  such that  $L(M) = L(G)$ .

**Proof:** See page 715 in [Meduna: Automata and Languages]

**Conclusion:** The fundamental models for recursively enumerable languages are

- 1) **Unrestricted grammars**
- 2) **Turing Machines**

# Context-Sensitive Grammar

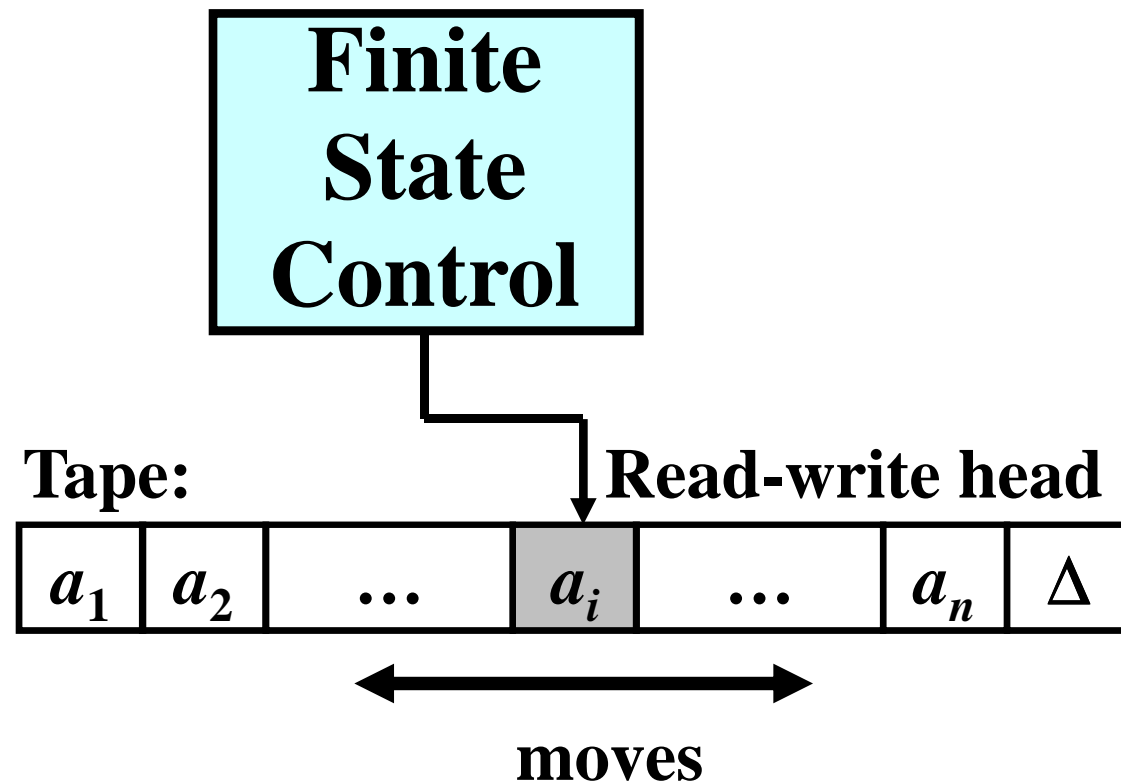
## Gist: Restriction of URG

**Definition:** Let  $G = (N, T, P, S)$  be an unrestricted grammar.  $G$  is a *context-sensitive* (or *length-increasing*) grammar (CSG) if every rule  $x \rightarrow y \in P$  satisfies  $|x| \leq |y|$ .

**Note:**  $\Rightarrow, \Rightarrow^n, \Rightarrow^+, \Rightarrow^*$  and  $L(G)$  are defined by analogy with the definitions of the corresponding notions on URGs.

# Linear Bounded Automaton

**Gist: A Turing machine with a Tape Bounded by the Length of the Input String.**



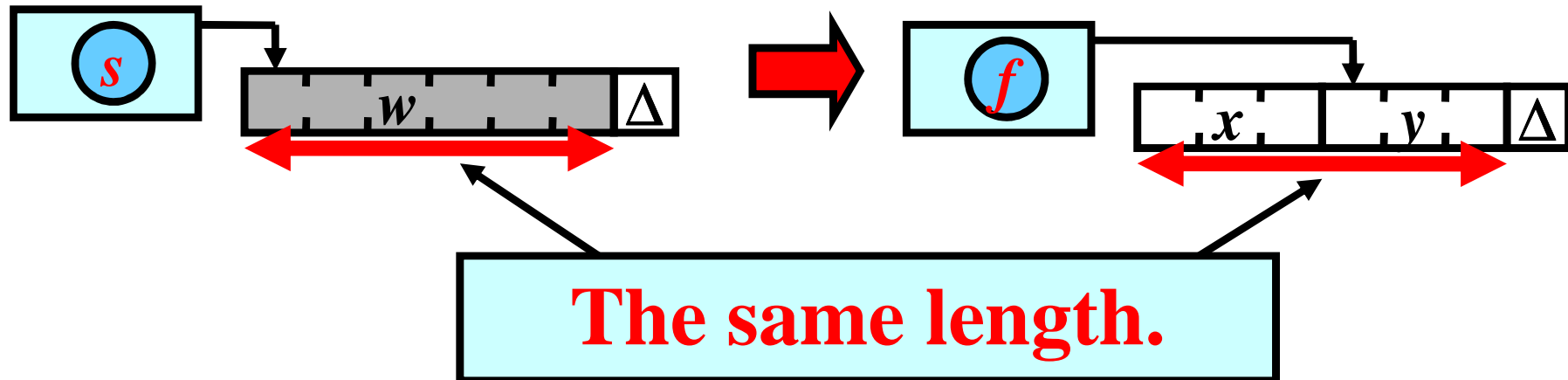


# Linear Bounded Automaton: Definition

**Gist:** With  $w$  on its tape,  $M$ 's tape is restricted to  $|w|$  squares.

**Definition:** A *linear bounded automaton* (LBA) is a TM that cannot extend its tape by any rule.

**Accepted language: Illustration**



# Context-sensitive Languages

**Definition:** Let  $L$  be a language.  $L$  is a *context-sensitive* if there exists a context-sensitive grammar  $G$  that  $L = L(G)$ .

**Theorem:** For every CSG  $G$ , there is an LBA  $M$  such that  $L(G) = L(M)$ .

**Proof:** See page 732 in [Meduna: Automata and Languages]

**Theorem:** For every LBA  $M$ , there is a CSG  $G$  such that  $L(M) = L(G)$ .

**Proof:** See page 734 in [Meduna: Automata and Languages]

**Conclusion:** The fundamental models for context-sensitive languages are

- 1) **Context-sensitive grammars**
- 2) **Linear bounded automata**

# Right-Linear Grammar: Definition

**Gist:** A CFG in which every rule has a string of terminals followed by no more than one nonterminal on the right-hand side.

**Definition:** Let  $G = (N, T, P, S)$  be a CFG.  $G$  is a *right-linear grammar* (RLG) if every rule  $A \rightarrow x \in P$  satisfies  $x \in T^* \cup T^*N$ .

## Example:

$G = (N, T, P, S)$ , where  $N = \{S, A\}$ ,  $T = \{a, b\}$

$P = \{1: S \rightarrow aS, 2: S \rightarrow aA, 3: A \rightarrow bA, 4: A \rightarrow b\}$

- $S \Rightarrow aA [2] \Rightarrow ab [4]$
- $S \Rightarrow aS [1] \Rightarrow aaA [2] \Rightarrow aab [4]$
- $S \Rightarrow aA [2] \Rightarrow abA [3] \Rightarrow abb [4]$
- $\vdots$

**Note:**  $L(G) = \{a^m b^n : m, n \geq 1\}$

# Grammars for Regular Languages

**Theorem:** For every RLG  $G$ , there is an FA  $M$  such that  $L(G) = L(M)$ .

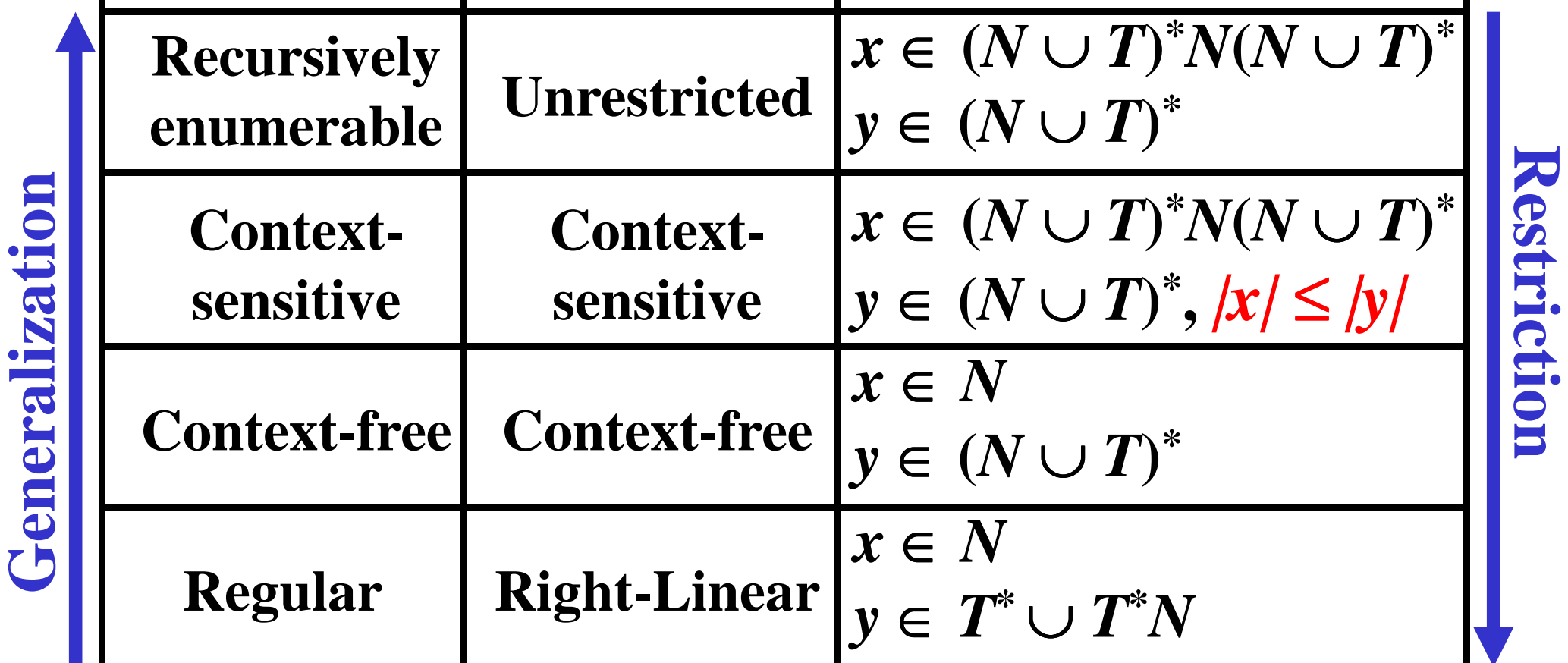
**Proof:** See page 575 in [Meduna: Automata and Languages]

**Theorem:** For every FA  $M$ , there is an RLG  $G$  such that  $L(M) = L(G)$ .

**Proof:** See page 583 in [Meduna: Automata and Languages]

**Conclusion:** Grammars for regular languages are  
**Right-linear grammar**

# Grammars: Summary



Languages	Grammar	Form of rules $x \rightarrow y$
Recursively enumerable	Unrestricted	$x \in (N \cup T)^* N (N \cup T)^*$ $y \in (N \cup T)^*$
Context-sensitive	Context-sensitive	$x \in (N \cup T)^* N (N \cup T)^*$ $y \in (N \cup T)^*,  x  \leq  y $
Context-free	Context-free	$x \in N$ $y \in (N \cup T)^*$
Regular	Right-Linear	$x \in N$ $y \in T^* \cup T^* N$

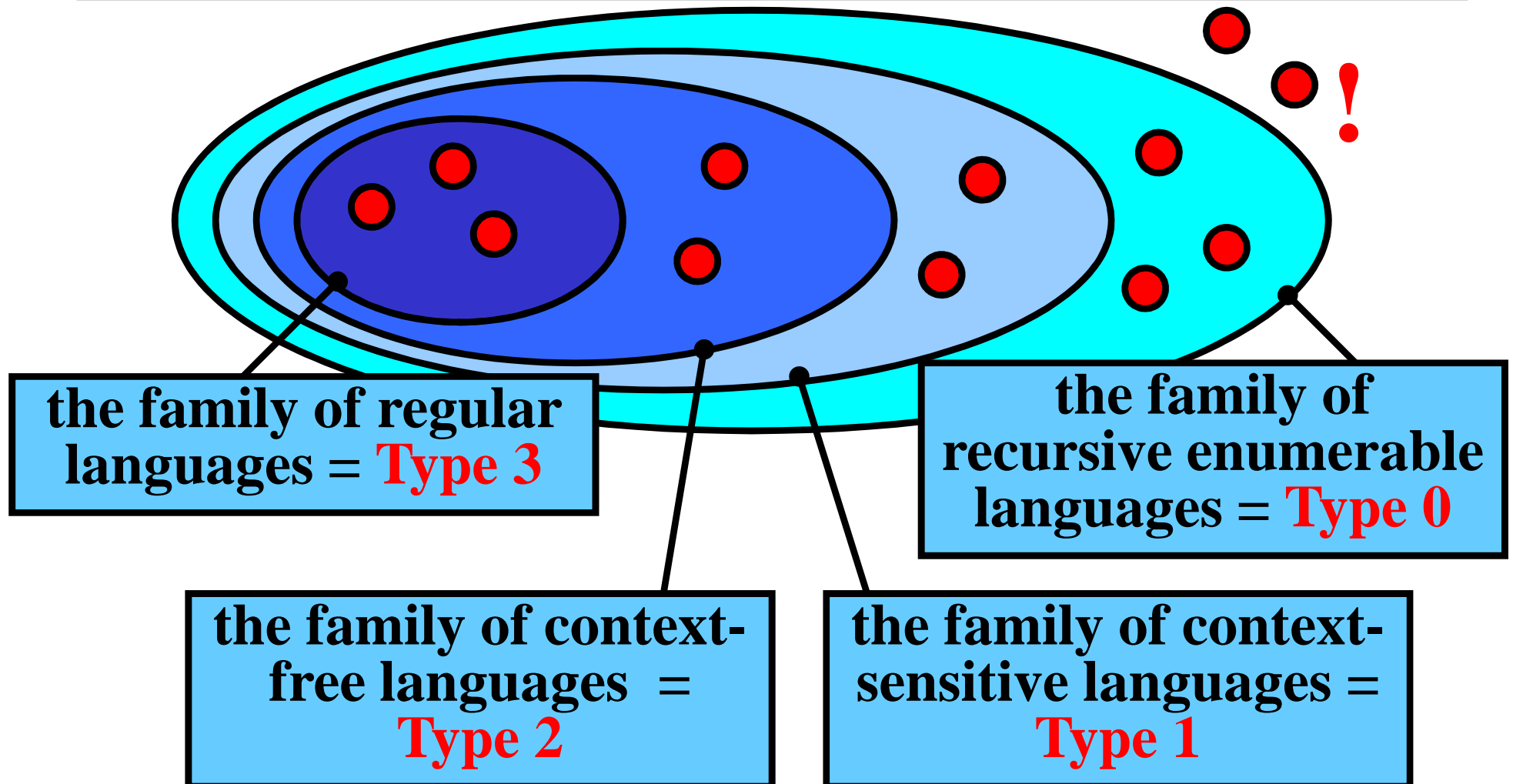
**Generalization** (upward arrow)

**Restriction** (downward arrow)

# Automata: Summary

<b>Generalization</b> ↑	<b>Languages</b>	<b>Accepting Device</b>	<b>Restriction</b> ↓
	<b>Recursively enumerable</b>	<b>Turing machine</b>	
	<b>Context-sensitive</b>	<b>Linear bounded automaton</b>	
	<b>Context-free</b>	<b>Pushdown automaton</b>	
	<b>Regular</b>	<b>Finite automaton</b>	

# Chomsky Hierarchy



---

**Type 3  $\subset$  Type 2  $\subset$  Type 1  $\subset$  Type 0**

# Language $L_{\text{SelfAcceptance}}$ 1/2

**Gist:**  $L_{\text{SelfAcceptance}}$  is the language over  $\{0, 1\}^*$ , which contain a string  $\delta(M)$ , if and only DTM  $M$  accepts  $\delta(M)$ .

## Definition:

$$L_{\text{SelfAcceptance}} = \{ \delta(M) : M \text{ is a DTM, } \delta(M) \in L(M) \}$$

**Illustration:**

TM  $M$



# Language $L_{\text{SelfAcceptance}}$ 1/2

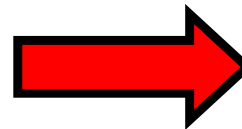
**Gist:**  $L_{\text{SelfAcceptance}}$  is the language over  $\{0, 1\}^*$ , which contain a string  $\delta(M)$ , if and only DTM  $M$  accepts  $\delta(M)$ .

## Definition:

$L_{\text{SelfAcceptance}} = \{ \delta(M) : M \text{ is a DTM, } \delta(M) \in L(M) \}$

**Illustration:**

TM  $M$



Description of  $M$ :  
 $\delta(M) = 1110\dots1$

# Language $L_{\text{SelfAcceptance}}$ 1/2

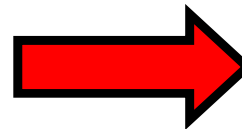
**Gist:**  $L_{\text{SelfAcceptance}}$  is the language over  $\{0, 1\}^*$ , which contain a string  $\delta(M)$ , if and only DTM  $M$  accepts  $\delta(M)$ .

## Definition:

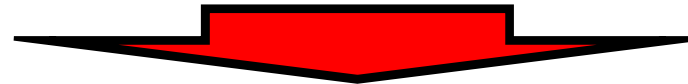
$$L_{\text{SelfAcceptance}} = \{ \delta(M) : M \text{ is a DTM, } \delta(M) \in L(M) \}$$

**Illustration:**

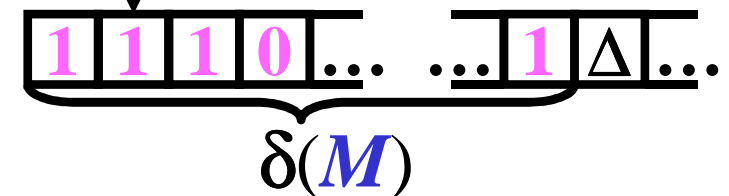
TM  $M$



Description of  $M$ :  
 $\delta(M) = 1110\dots 1$



TM  $M$



# Language $L_{\text{SelfAcceptance}}$ 1/2

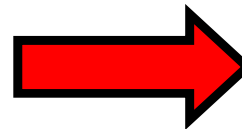
**Gist:**  $L_{\text{SelfAcceptance}}$  is the language over  $\{0, 1\}^*$ , which contain a string  $\delta(M)$ , if and only DTM  $M$  accepts  $\delta(M)$ .

## Definition:

$$L_{\text{SelfAcceptance}} = \{ \delta(M) : M \text{ is a DTM, } \delta(M) \in L(M) \}$$

**Illustration:**

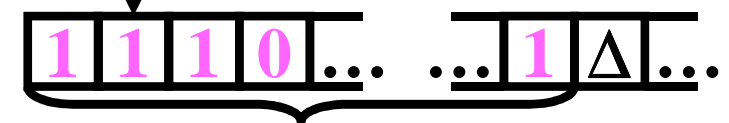
TM  $M$



Description of  $M$ :  
 $\delta(M) = 1110\dots 1$



TM  $M$



- Does TM  $M$  accept  $\delta(M) = 1110\dots 1$  ?

# Language $L_{\text{SelfAcceptance}}$ 1/2

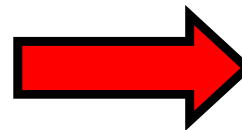
**Gist:**  $L_{\text{SelfAcceptance}}$  is the language over  $\{0, 1\}^*$ , which contain a string  $\delta(M)$ , if and only DTM  $M$  accepts  $\delta(M)$ .

## Definition:

$$L_{\text{SelfAcceptance}} = \{ \delta(M) : M \text{ is a DTM, } \delta(M) \in L(M) \}$$

**Illustration:**

TM  $M$



Description of  $M$ :  
 $\delta(M) = 1110\dots 1$



TM  $M$

1 1 1 0 ... .. 1 Δ ...  
 $\delta(M)$

- Does TM  $M$  accept  $\delta(M) = 1110\dots 1$  ?

YES

$\delta(M) \in L_{\text{SelfAcceptance}}$

NO

$\delta(M) \notin L_{\text{SelfAcceptance}}$

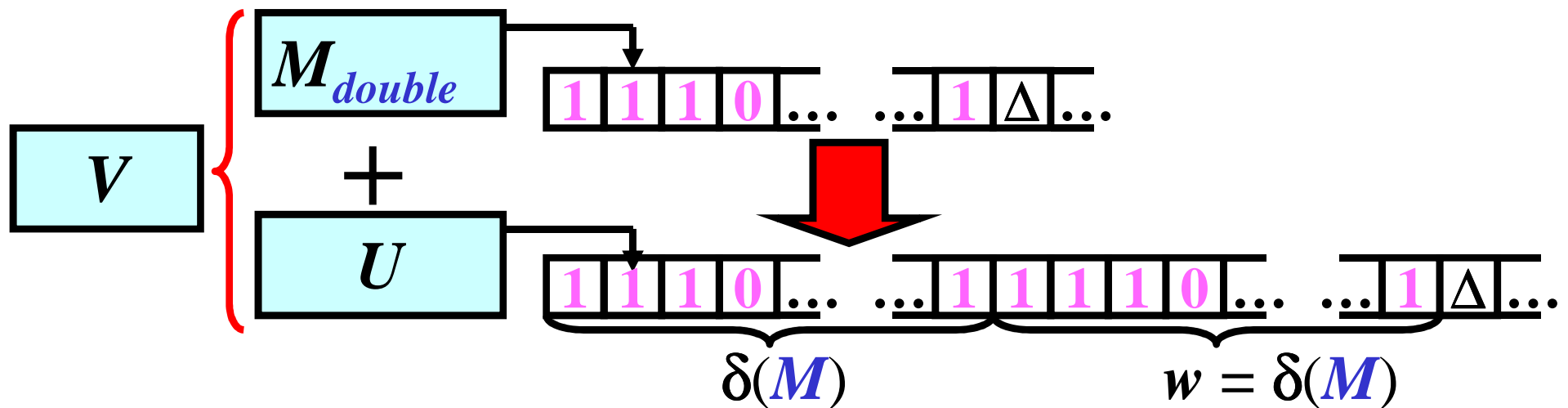
# Language $L_{\text{SelfAcceptance}}$ 2/2

**Theorem:**  $L_{\text{SelfAcceptance}}$  is accept by some TM.

**Proof (idea):**

- We construct a DTM  $V$ , which:
  - 1) Replace an input string  $w = \delta(M)$  with  $\delta(M)\delta(M)$
  - 2) Simulate an activity of a universal TM  $U$
- Then,  $L(V) = L_{\text{SelfAcceptance}}$ , thus theorem holds.

**Illustration:**



# Language $L_{\text{NonSelfAcceptance}}$ 1/3

**Gist:**  $L_{\text{NonSelfAcceptance}} = \overline{L_{\text{SelfAcceptance}}}$

**Definition:**

$$L_{\text{NonSelfAcceptance}} = \{0, 1\}^* - L_{\text{SelfAcceptance}}$$

TM  $M$

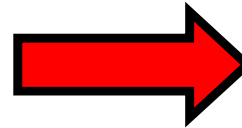
# Language $L_{\text{NonSelfAcceptance}}$ 1/3

**Gist:**  $L_{\text{NonSelfAcceptance}} = \overline{L_{\text{SelfAcceptance}}}$

**Definition:**

$$L_{\text{NonSelfAcceptance}} = \{0, 1\}^* - L_{\text{SelfAcceptance}}$$

TM  $M$



Description of  $M$ :  
 $\delta(M) = 1110\dots1$

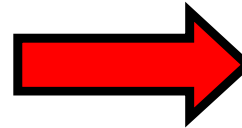
# Language $L_{\text{NonSelfAcceptance}}$ 1/3

**Gist:**  $L_{\text{NonSelfAcceptance}} = \overline{L_{\text{SelfAcceptance}}}$

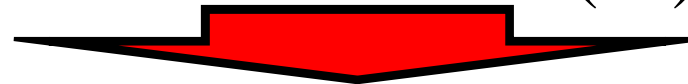
**Definition:**

$$L_{\text{NonSelfAcceptance}} = \{0, 1\}^* - L_{\text{SelfAcceptance}}$$

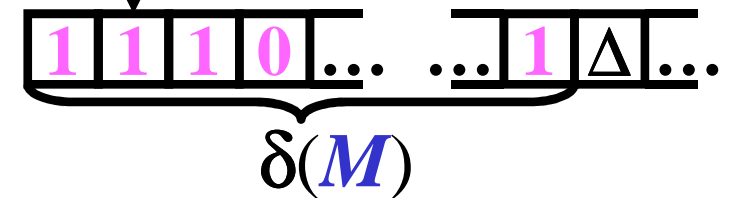
TM  $M$



Description of  $M$ :  
 $\delta(M) = 1110\dots 1$



TM  $M$





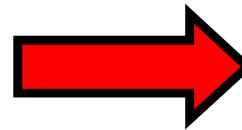
# Language $L_{\text{NonSelfAcceptance}}$ 1/3

**Gist:**  $L_{\text{NonSelfAcceptance}} = \overline{L_{\text{SelfAcceptance}}}$

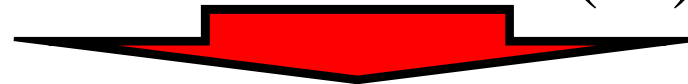
**Definition:**

$$L_{\text{NonSelfAcceptance}} = \{0, 1\}^* - L_{\text{SelfAcceptance}}$$

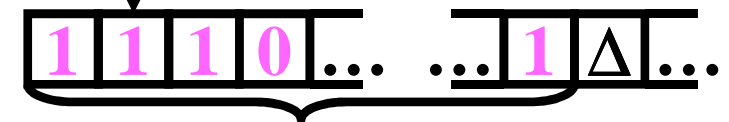
TM  $M$



Description of  $M$ :  
 $\delta(M) = 1110\dots 1$



TM  $M$



- Does TM  $M$  accept  $\delta(M) = 1110\dots 1$  ?

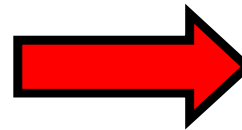
# Language $L_{\text{NonSelfAcceptance}}$ 1/3

**Gist:**  $L_{\text{NonSelfAcceptance}} = \overline{L_{\text{SelfAcceptance}}}$

**Definition:**

$$L_{\text{NonSelfAcceptance}} = \{0, 1\}^* - L_{\text{SelfAcceptance}}$$

TM  $M$



Description of  $M$ :  
 $\delta(M) = 1110\dots 1$



TM  $M$

$\underbrace{1\ 1\ 1\ 0\ \dots}_{\delta(M)} \dots \underbrace{\dots\ 1\ \Delta\ \dots}_{\delta(M)}$

- Does TM  $M$  accept  $\delta(M) = 1110\dots 1$  ?

YES

$\delta(M) \notin L_{\text{NonSelfAcceptance}}$

NO

$\delta(M) \in L_{\text{NonSelfAcceptance}}$

# Language $L_{\text{NonSelfAcceptance}}$ 2/3

**Theorem:**  $L_{\text{NonSelfAcceptance}}$  is accept by no TM.

**Proof** (by contradiction):

- Assume that  $L_{\text{NonSelfAcceptance}}$  is accepted by a TM.  
Consider this infinite table:

	$M_i$	$m_i = \delta(M_i)$	$\text{SelfAcceptance}(M_i)$
All TMs ↓	$M_1$	111001001001101	Yes
	$M_2$	11101010111100101	No
	$M_3$	1110010001010001001001	Yes
	$\vdots$	$\vdots$	$\vdots$

**Note:**

- $\text{SelfAcceptance}(M_i) = \text{Yes}$  if  $m_i \in L(M_i)$   
 $\text{No}$  if  $m_i \notin L(M_i)$

# Language $L_{\text{NonSelfAcceptance}}$ 3/3

- **Notice:**  $L_{\text{NonSelfAcceptance}} = \{ \mathbf{m}_i : \mathbf{m}_i \notin L(\mathbf{M}_i), i = 1, \dots \}$
- Let  $L(\mathbf{M}_k) = L_{\text{NonSelfAcceptance}}$

# Language $L_{\text{NonSelfAcceptance}}$ 3/3

- **Notice:**  $L_{\text{NonSelfAcceptance}} = \{\mathbf{m}_i : \mathbf{m}_i \notin L(\mathbf{M}_i), i = 1, \dots\}$
- Let  $L(\mathbf{M}_k) = L_{\text{NonSelfAcceptance}}$
- *SelfAcceptance*( $\mathbf{M}_k$ ) = **No** implies
  - $\mathbf{m}_k \notin L(\mathbf{M}_k)$  implies
  - $\mathbf{m}_k \in L_{\text{NonSelfAcceptance}}$  implies
  - $\mathbf{m}_k \in L(\mathbf{M}_k)$

# Language $L_{\text{NonSelfAcceptance}}$ 3/3

- **Notice:**  $L_{\text{NonSelfAcceptance}} = \{\mathbf{m}_i : \mathbf{m}_i \notin L(\mathbf{M}_i), i = 1, \dots\}$
- Let  $L(\mathbf{M}_k) = L_{\text{NonSelfAcceptance}}$
- *SelfAcceptance*( $\mathbf{M}_k$ ) = **No** implies
  - $\mathbf{m}_k \notin L(\mathbf{M}_k)$  implies
  - $\mathbf{m}_k \in L_{\text{NonSelfAcceptance}}$  implies
  - $\mathbf{m}_k \in L(\mathbf{M}_k)$
  - contradiction**

# Language $L_{\text{NonSelfAcceptance}}$ 3/3

- **Notice:**  $L_{\text{NonSelfAcceptance}} = \{\mathbf{m}_i : \mathbf{m}_i \notin L(\mathbf{M}_i), i = 1, \dots\}$
- Let  $L(\mathbf{M}_k) = L_{\text{NonSelfAcceptance}}$
- *SelfAcceptance*( $\mathbf{M}_k$ ) = **No** implies
  - $\mathbf{m}_k \notin L(\mathbf{M}_k)$  implies
  - $\mathbf{m}_k \in L_{\text{NonSelfAcceptance}}$  implies
  - $\mathbf{m}_k \in L(\mathbf{M}_k)$
  - contradiction**
- *SelfAcceptance*( $\mathbf{M}_k$ ) = **Yes** implies
  - $\mathbf{m}_k \in L(\mathbf{M}_k)$  implies
  - $\mathbf{m}_k \notin L_{\text{NonSelfAcceptance}}$  implies
  - $\mathbf{m}_k \notin L(\mathbf{M}_k)$

# Language $L_{\text{NonSelfAcceptance}}$ 3/3

- **Notice:**  $L_{\text{NonSelfAcceptance}} = \{ \mathbf{m}_i : \mathbf{m}_i \notin L(\mathbf{M}_i), i = 1, \dots \}$
- Let  $L(\mathbf{M}_k) = L_{\text{NonSelfAcceptance}}$
- *SelfAcceptance*( $\mathbf{M}_k$ ) = **No** implies
  - $\mathbf{m}_k \notin L(\mathbf{M}_k)$  implies
  - $\mathbf{m}_k \in L_{\text{NonSelfAcceptance}}$  implies
  - $\mathbf{m}_k \in L(\mathbf{M}_k)$
  - contradiction**
- *SelfAcceptance*( $\mathbf{M}_k$ ) = **Yes** implies
  - $\mathbf{m}_k \in L(\mathbf{M}_k)$  implies
  - $\mathbf{m}_k \notin L_{\text{NonSelfAcceptance}}$  implies
  - $\mathbf{m}_k \notin L(\mathbf{M}_k)$
  - contradiction**



# Language $L_{\text{NonSelfAcceptance}}$ 3/3

- **Notice:**  $L_{\text{NonSelfAcceptance}} = \{ \mathbf{m}_i : \mathbf{m}_i \notin L(\mathbf{M}_i), i = 1, \dots \}$
- Let  $L(\mathbf{M}_k) = L_{\text{NonSelfAcceptance}}$
- *SelfAcceptance*( $\mathbf{M}_k$ ) = **No** implies
  - $\mathbf{m}_k \notin L(\mathbf{M}_k)$  implies
  - $\mathbf{m}_k \in L_{\text{NonSelfAcceptance}}$  implies
  - $\mathbf{m}_k \in L(\mathbf{M}_k)$
  - contradiction**
- *SelfAcceptance*( $\mathbf{M}_k$ ) = **Yes** implies
  - $\mathbf{m}_k \in L(\mathbf{M}_k)$  implies
  - $\mathbf{m}_k \notin L_{\text{NonSelfAcceptance}}$  implies
  - $\mathbf{m}_k \notin L(\mathbf{M}_k)$
  - contradiction**
- $L_{\text{NonSelfAcceptance}}$  is accepted by **no** TM  $\mathbf{M}_k$

# Recursive Language

**Gist: Recursive Language accepts TM that always halt**

**Definition:** Let  $L$  be a language. If  $L = L(M)$ , where  $M$  is DTM that always halts, then  $L$  is a *recursive language*.

**Theorem:** The family of recursive languages is closed under complement.

**Proof:** See page 693 in [Meduna: Automata and Languages]

**Theorem:** The family of recursively enumerable languages is not closed under complement.

**Proof:** See the  $L_{\text{SelfAcceptance}}$

# Other Hierarchy of Languages

