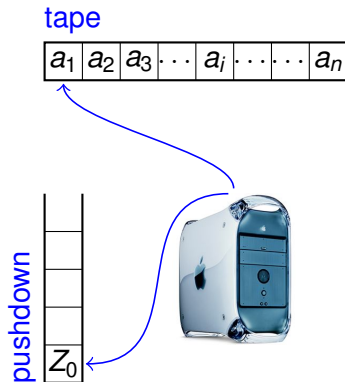


Regulated Nondeterminism in Pushdown Automata

Tomáš Masopust

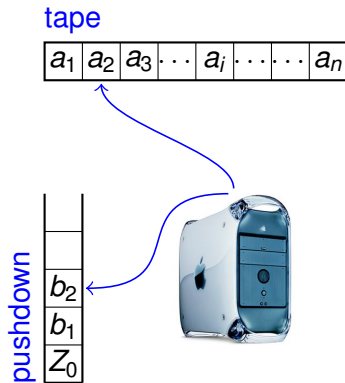
VZ FM, 2009

Pushdown Automaton



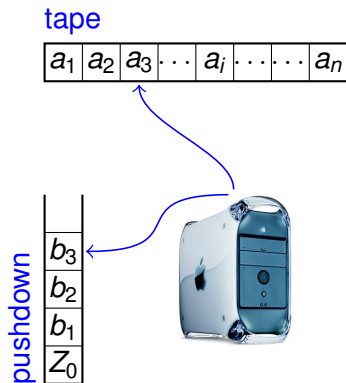
Transitions used:

Pushdown Automaton



Transitions used: r_1

Pushdown Automaton



Transitions used: r_1, r_2

Regulated PDAs (Kolář and Meduna, 2000)

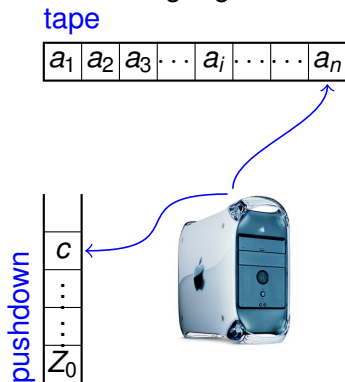
- Motivated by regulations in grammars.
- Given a PDA M and a control language R .

Transitions used: r_1, r_2, \dots, r_k

- It accepts the input (by a final state) if M accepts the input and $r_1 r_2 \dots r_k \in R$.

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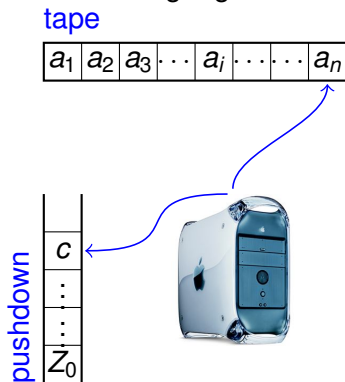


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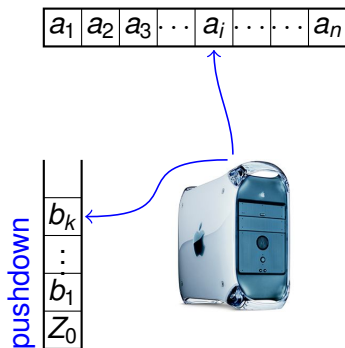
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Regulated PDAs (Kolář and Meduna, 2000)

- Regulated PDAs with **regular control languages** are ordinary PDAs.
- Regulated PDAs with **non-regular (linear) control languages** are computationally complete.

Regularly Regulated Pushdowns (Křivka, 2007)

- Given a PDA M and a regular control language R .

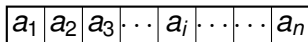


- It accepts the input if M accepts and $b_1 \dots b_k \in R$ (in each step).
- Equivalent to ordinary pushdown automata.

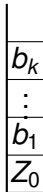
Regularly Regulated Pushdowns (Křivka, 2007)

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tape



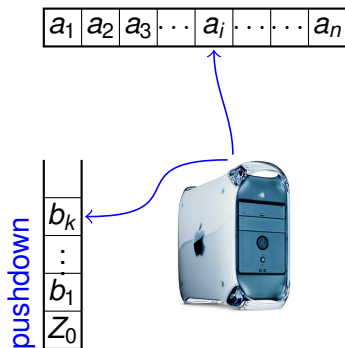
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R -PDAs (Kutrib, Malcher, Werlein, 2007)

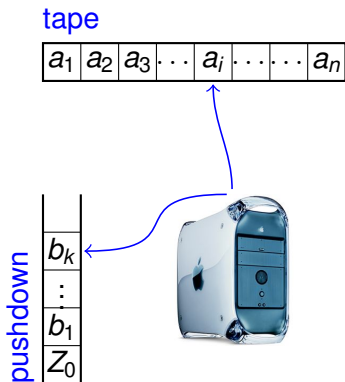
- Generalization: considering **nondeterminism**.
- Given a PDA M and a control language R

Next step is

$$\left\{ \begin{array}{l} b_1 \dots b_k \in R \quad \text{nondeterministic} \\ b_1 \dots b_k \notin R \quad \text{deterministic} \end{array} \right.$$

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Definition

Given a PDA

$$\mathcal{M} = (Q, \Sigma, \Gamma, \delta, q_0, Z_0, F)$$

and a control language $R \subseteq (\Gamma \setminus Z_0)^*$. \mathcal{M} is an **R-PDA** if:

- 1 for all $q \in Q$, $a \in \Sigma \cup \{\lambda\}$, and $Z \in \Gamma$, δ can be written as

$$\delta(q, a, Z) = \delta_d(q, a, Z) \cup \delta_{nd}(q, a, Z),$$

where d = deterministic and nd = nondeterministic, and

- 2 for all $q, q' \in Q$, $a \in \Sigma \cup \{\lambda\}$, $w \in \Sigma^*$, $Z \in \Gamma$, and $\gamma \in \Gamma^*$,

$$(q, aw, Z\gamma) \vdash_{\mathcal{M}} (q', w, \gamma'\gamma) \text{ if}$$

- 1 either $(q', \gamma') \in \delta_{nd}(q, a, Z)$, $Z\gamma = \gamma''Z_0$, and $(\gamma'')^R \in R$,
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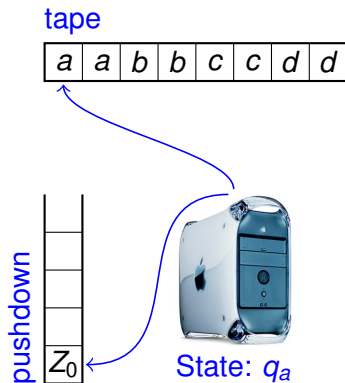
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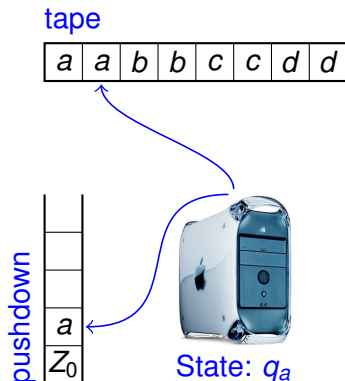
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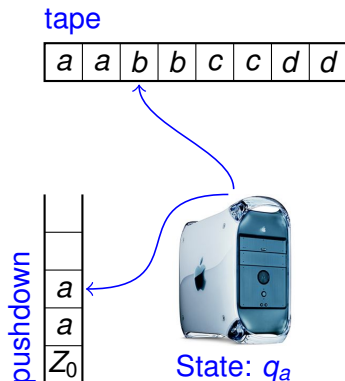
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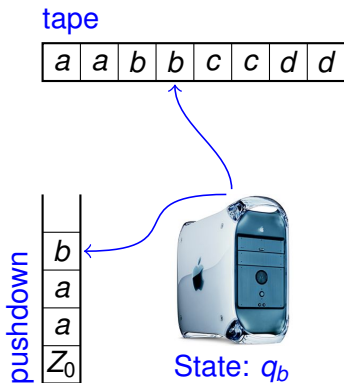
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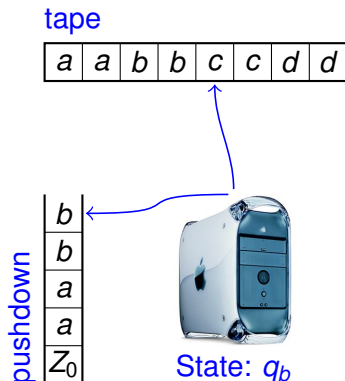
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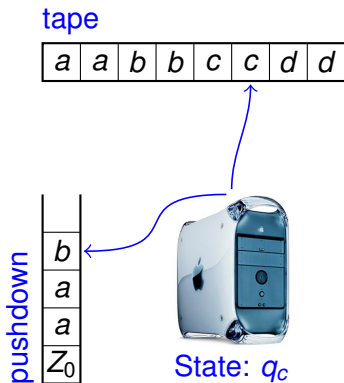
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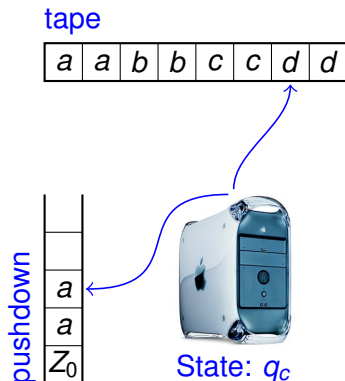
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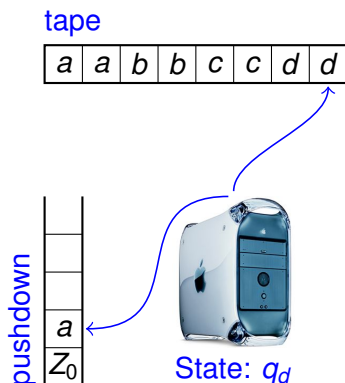
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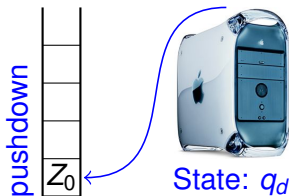
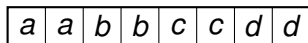
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tape



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Example – $R = \{a^n b^n : n \geq 1\}$

tape

a	a	b	b	c	c	d	d
---	---	---	---	---	---	---	---

pushdown



State: OK

- \mathcal{M} nondeterministically checks that $Z_0 a^m b^n \in R$, i.e., $m = n$.

$$T(\mathcal{M}) = \{a^n b^n c^n d^n : n \geq 1\}.$$

Properties

- R -PDAs behave nondeterministically iff their pushdown content forms a string belonging to R .
- R is **regular**, then the power of PDAs.

Theorem

Let R be a regular language and \mathcal{M} be an R -PDA. Then, an equivalent PDA \mathcal{M}' can effectively be constructed.

- R is **linear**, then the power increases.
- What is the power of R -PDAs with non-regular control languages?

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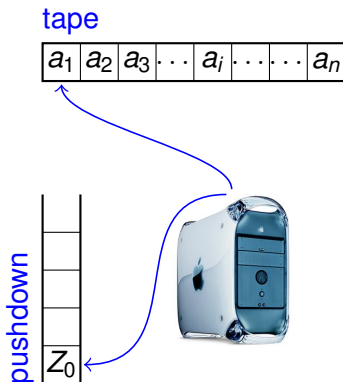
R-PDAs: The Non-Regular Case

Theorem

Let $L \in RE$. Then, there is a linear language R and an R-PDA \mathcal{M} such that

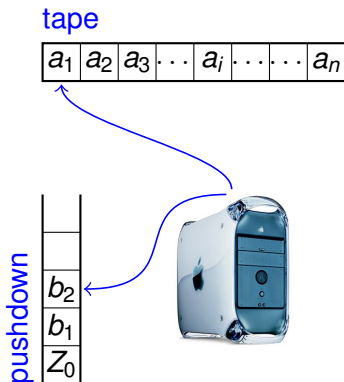
$$L = T(\mathcal{M}).$$

Proof (sketch) – $L^R = h(L_1 \cap L_2)$, L_1, L_2 linear



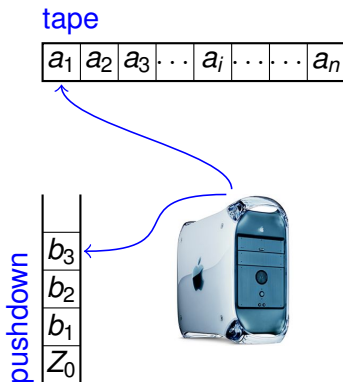
- \mathcal{M} nondeterministically pushes symbols onto its pushdown.

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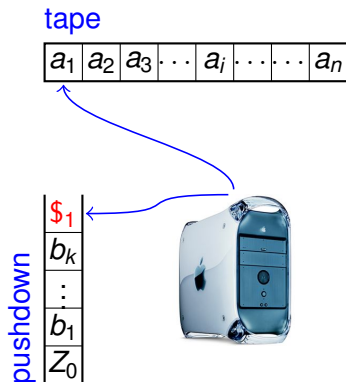
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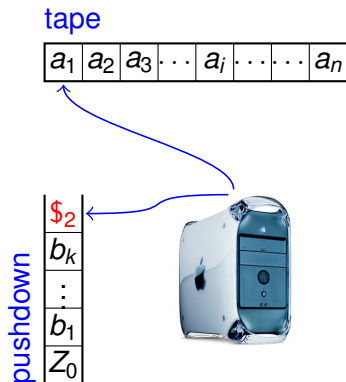
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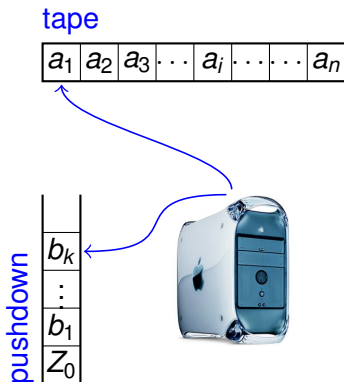
- $\gamma \$1 \in L_1 \$1?$

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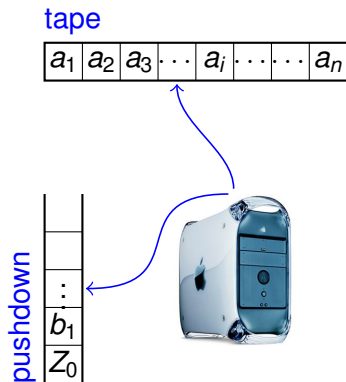
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- $\gamma \$_1 \in L_1 \$_1$ – YES; $\gamma \$_2 \in L_2 \$_2$ – YES; we have $\gamma \in L_1 \cap L_2$.

Proof (sketch) – $L^R = h(L_1 \cap L_2)$, L_1, L_2 linear



- Remove b_k , read $h(b_k)^R$ from the input.

Corollary

Let $L \in RE$. Then, there is a linear context-free language R and an R -PDA

$$\mathcal{M} = (Q, \Sigma, \Gamma, \delta, q_0, Z_0, F)$$

such that $L = T(\mathcal{M})$,

- $|Q| \leq 3$,
- $|\Gamma| \leq |\Sigma| + 7$.

State-Controlled R -PDAs (PDAs with an oracle)

Let

$$\mathcal{M} = (Q, \Sigma, \Gamma, \delta, q_0, Q_c, Z_0, F)$$

be a PDA, where $Q_c \subseteq Q$ is a set of **checking states**. $R \subseteq (\Gamma \setminus Z_0)^*$.

\mathcal{M} is called a **state-controlled R -PDA** (R -sPDA) if for all $q, q' \in Q$, $a \in \Sigma \cup \{\lambda\}$, $w \in \Sigma^*$, $Z \in \Gamma$, and $\gamma \in \Gamma^*$,

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In addition, \mathcal{M} checks the pushdown content no more than *twice* during any computation.

Corollary

Let $L \in RE$. Then, there is a linear language R and an R -sPDA

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which checks the pushdown content no more than **twice** during any computation, such that

- $|Q| \leq 4$,
- $|Q_c| = 1$,
- $|\Gamma| \leq |\Sigma| + 6$,

and $L = T(\mathcal{M})$.

Open Problems

By the example, there is a (deterministic) R -sPDA \mathcal{M} , where

- $R = \{a^n b^n : n \geq 1\}$ is linear, deterministic context-free,
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Open Problems (Deterministic R -sPDAs)

- Deterministic R -sPDAs (R -sDPDAs), R linear.
- $DCF \subset R\text{-sDPDA} \subseteq REC$ ($CS, \text{det}CS$).
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