

Compositional Entailment Checking for a Fragment of Separation Logic

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Introduction

- Procedure for checking **entailments** in **separation logic**.
- **Separation logic (SL)**:
 - ▶ a formalism for reasoning about **heaps**,
 - ▶ allows for **scalability**: **local reasoning**,
 - ▶ used, e.g., in Space Invader, Slayer, HIP/SLEEK, Predator, S2, ...

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- Procedure for checking **entailments** in **separation logic**.
- **Separation logic (SL)**:
 - ▶ a formalism for reasoning about **heaps**,
 - ▶ allows for **scalability**: **local reasoning**,
 - ▶ used, e.g., in Space Invader, Slayer, HIP/SLEEK, Predator, S2, ...
- Reasoning about **heap-manipulating programs**:
 - ▶ crucial for many program analysis tasks,
 - ▶ difficult: ∞ sets of graphs,
 - ▶ still under heavy research.

Separation Logic

■ Basic formulae of SL:

$$\varphi ::= \exists x_1, \dots, x_n . \Pi \wedge \Sigma$$

$$\Pi ::= x_1 = x_2 \mid x_1 \neq x_2 \mid x = \text{null} \mid \Pi_1 \wedge \Pi_2$$

$$\Sigma ::= \text{emp} \mid x \mapsto \{(f_1, x_1), \dots, (f_n, x_n)\} \mid \Sigma_1 * \Sigma_2$$

pure part
shape part

■ Example:

$$\varphi = \exists x_1 . E \mapsto \{(\text{next}, x_1)\} * x_1 \mapsto \{(\text{next}, F)\}$$

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Inductive predicates:

▶ Abstraction:

- a data structure of any length (size) via **recursion**.

▶ Example (singly linked list):

$$\begin{aligned} \text{sll}(E, F) \stackrel{\text{def}}{=} & (E = F \wedge \text{emp}) \vee \\ & (E \neq F \wedge \exists X_{tl} . E \mapsto \{(\text{next}, X_{tl})\} * \text{sll}(X_{tl}, F)) \end{aligned}$$

Entailments in Separation Logic (1/2)

$$\varphi \stackrel{?}{\models} \psi$$

Is φ an unfolding of ψ ?

■ Example:

$$\exists x_1, x_2. E \mapsto \{(next, x_1)\} * sll(x_1, x_2) * x_2 \mapsto \{(next, F)\}$$

$$\stackrel{?}{\models} sll(E, F)$$

■ where

$$sll(E, F) \stackrel{\text{def}}{=} (E = F \wedge emp) \vee (E \neq F \wedge \exists X_{tl}. E \mapsto \{(next, X_{tl})\} * sll(X_{tl}, F))$$

Entailments in Separation Logic (2/2)

- **Invariant** checking for heap-manipulating programs:
 - ▶ resolving verification conditions in **deductive verification**,
 - ▶ fixpoint checking in **abstract interpretation**-based approaches.
- In general **undecidable**.
- There exist **decision procedures** for various fragments.
 - ▶ In what follows, one such fragment and a decision procedure are presented.
 - ▶ Originally published at APLAS'14.

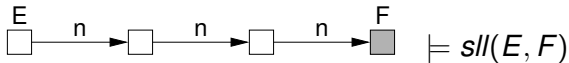
Considered Singly-Linked Fragment (1/3)

We start with various kinds of **singly-linked lists** expressible using the template:

$$P(E, F, \vec{B}) = (E = F \wedge emp) \vee \\ (E \notin \{F\} \cup \vec{B} \wedge \exists X_{tl} \exists \vec{Z} . \Sigma(\mathbf{E}, X_{tl}, \vec{Z} \cup \vec{B}) * P(X_{tl}, F, \vec{B}))$$

This template allows us to express:

- **Simple singly-linked lists (SLLs):**



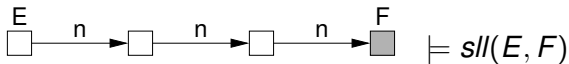
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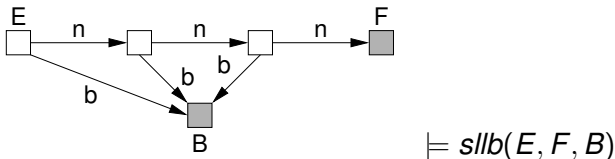
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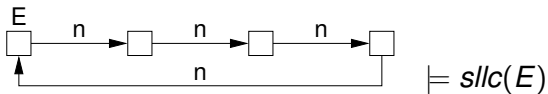
- SLLs with additional (e.g. head/tail) pointers:



Considered Singly-Linked Fragment (2/3)

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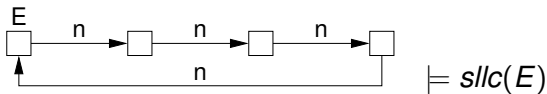
■ Cyclic lists:



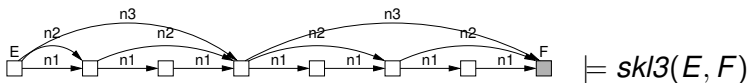
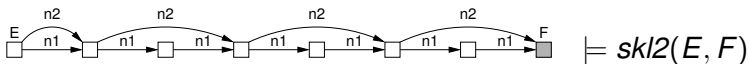
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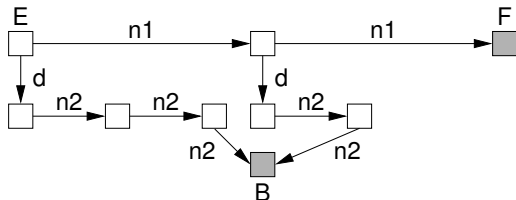
Skip lists:



Considered Singly-Linked Fragment (3/3)

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- **Nested** combinations of the above:



$\models nsll(E, F, B)$

Overview

$$\underbrace{\exists \vec{X}. \Pi_{\varphi} \wedge \Sigma_{\varphi}}_{\varphi} \stackrel{?}{\models} \underbrace{\Pi_{\psi} \wedge \Sigma_{\psi}}_{\psi}$$

1 Normalize φ and ψ :

- ▶ add implied (dis)equalities,
- ▶ remove empty inductive predicates.

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- 4 Reduce the rest of Σ_{φ} and Σ_{ψ} to:

$$\varphi_1 \stackrel{?}{\models} P_1 \quad \wedge \quad \varphi_2 \stackrel{?}{\models} P_2 \quad \wedge \quad \varphi_3 \stackrel{?}{\models} P_3 \quad \wedge \quad \dots$$

- 1 Transform $\varphi_i \rightsquigarrow$ tree \mathcal{T}_{φ_i} :
 - spanning tree + routing expressions.

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- 3 Test:
 $\mathcal{T}_{\varphi_i} \stackrel{?}{\in} \mathcal{L}(\mathcal{A}_{P_i})$

Normalization (1/3)

$$\underbrace{\exists \vec{X}. \Pi_{\varphi} \wedge \Sigma_{\varphi}}_{\varphi} \stackrel{?}{\models} \underbrace{\Pi_{\psi} \wedge \Sigma_{\psi}}_{\psi}$$

Boolean abstractions of φ and ψ :

- A **conjunctive** formula constructed as follows:
- Start with \emptyset and process the **pure** part first.

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- Add an encoding of Π :
 - ▶ For $E = F$ in Π , add $[E = F]$ for a Boolean variable $[E = F]$.
 - ▶ For $E \neq F$ in Π , add $\neg[E = F]$.

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- Add an encoding of **equality**:
 - ▶ **reflexivity**: $[E = E]$ for all E ,
 - ▶ **symmetry**: $[E = F] \Leftrightarrow [F = E]$ for all E, F ,
 - ▶ **transitivity**: $[E = F] \wedge [F = G] \Rightarrow [E = G]$ for all E, F, G .

Normalization (2/3)

$$\underbrace{\exists \vec{X}. \Pi_{\varphi} \wedge \Sigma_{\varphi}}_{\varphi} \stackrel{?}{\models} \underbrace{\Pi_{\psi} \wedge \Sigma_{\psi}}_{\psi}$$

Boolean abstractions of φ and ψ :

- **Pure** part Π finished, now do the **shape** Σ .
- Add an encoding of Σ :
 - ▶ For $a = E \mapsto \{f_1 \mapsto x_1, \dots\}$ in Σ , add $[E, a]$. (E is allocated in a .)
 - ▶ For $a = P(E, F, \vec{B})$ in Σ , add $[E, a] \oplus [E = F]$.

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- Add an encoding of **separating conjunction** $*$:
 - ▶ $([E = F] \wedge [E, a]) \Rightarrow \neg[F, a']$ for all $E, F, a \neq a'$.

Normalization (3/3)

$$\underbrace{\exists \vec{X}. \Pi_{\varphi} \wedge \Sigma_{\varphi}}_{\varphi} \stackrel{?}{\models} \underbrace{\Pi_{\psi} \wedge \Sigma_{\psi}}_{\psi}$$

Boolean abstraction of φ (for ψ similar):

■ Properties of $BoolAbs[\varphi]$:

- ▶ φ and $BoolAbs[\varphi]$ are **equisatisfiable**.
- ▶ $\varphi \Rightarrow E = F$ iff $BoolAbs[\varphi] \Rightarrow [E = F]$.
- ▶ $\varphi \Rightarrow E \neq F$ iff $BoolAbs[\varphi] \Rightarrow \neg[E = F]$.

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■ Normalization of φ :

- ▶ If $BoolAbs[\varphi]$ is UNSAT:

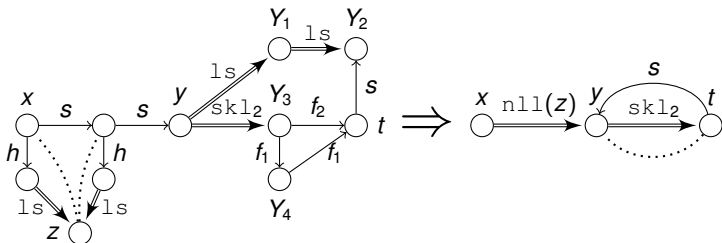
- $\varphi' := \text{false}$; return φ' ;

- ▶ If $BoolAbs[\varphi]$ is SAT:

- $\varphi' := \varphi$;
- $\varphi' := \varphi \cup$ (dis)equalities implied by $BoolAbs[\varphi]$;
- $\varphi' := \varphi \setminus$ **empty** inductive predicates; // $P(E, F, \vec{B})$ s.t. $E = F$ in φ'
- return φ' ;

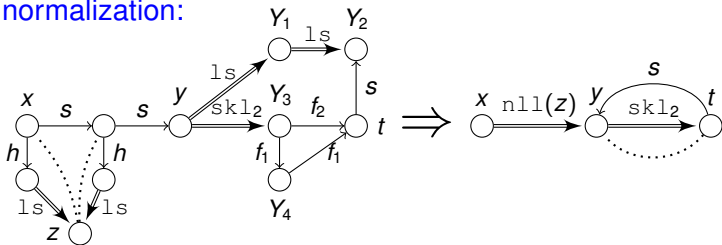
A Complex Entailment Example $\psi_1 \Rightarrow \psi_2$ (1/3)

$$\begin{aligned}
 \psi_1 &\equiv \exists Y_1, Y_2, Y_3, Y_4, Z_1, Z_2, Z_3. x \neq z \wedge Z_2 \neq z \wedge \\
 &\quad x \mapsto \{(s, Z_2), (h, Z_1)\} * Z_2 \mapsto \{(s, y), (h, Z_3)\} * \text{ls}(Z_1, z) * \text{ls}(Z_3, z) \\
 &\quad \text{ls}(y, Y_1) * \text{skl}_2(y, Y_3) * \text{ls}(Y_1, Y_2) * \\
 &\quad Y_3 \mapsto \{(f_2, t), (f_1, Y_4)\} * Y_4 \mapsto \{(f_2, \text{null}), (f_1, t)\} * t \mapsto \{(s, Y_2)\} \\
 \psi_2 &\equiv y \neq t \wedge \text{null}(x, y, z) * \text{skl}_2(y, t) * t \mapsto \{(s, y)\}
 \end{aligned}$$

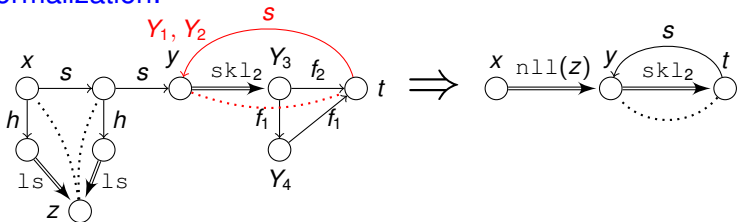


A Complex Entailment Example $\psi_1 \Rightarrow \psi_2$ (2/3)

Before normalization:



After normalization:



Entailment of Shape Parts

$$\underbrace{\exists \vec{X}. \Pi_{\varphi'} \wedge \Sigma_{\varphi'}}_{\varphi'} \stackrel{?}{\models} \underbrace{\Pi_{\psi'} \wedge \Sigma_{\psi'}}_{\psi'}$$

For every **shape atom** of $\Sigma_{\psi'}$, find a subformula of $\Sigma_{\varphi'}$:

- For each **points-to** $E \mapsto \{(f_1, x_1), \dots\}$ in $\Sigma_{\psi'}$:
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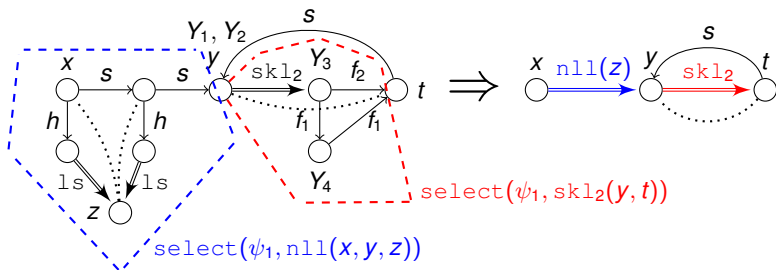
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 - ▶ test: $\mathcal{T}_G \stackrel{?}{\in} \mathcal{L}(\mathcal{A}_{P(E, F, \vec{B})})$

A Complex Entailment Example $\psi_1 \Rightarrow \psi_2$ (3/3)

Selected subgraphs:



Entailment of Shape Parts

Transforming Graphs into Trees (1/2)

Identify a **unique spanning tree** of a rooted graph:

- Construct an **ordering on selectors** such that:
 - ▶ selectors of a predicate \prec selectors of its nested predicates,
 - ▶ “forward” selectors \prec selectors going “down” to nested predicates,
 - ▶ selectors going “down” \prec selectors going to the border.
- **Spanning tree edges**: a part of minimal paths to particular nodes.

Entailment of Shape Parts

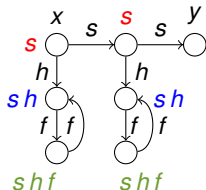
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Label nodes with **minimal compacted paths**:

- each f^n in a path, $n \geq 1$, replaced by f ,
- identifies **repeated nodes** of the same kind.



Entailment of Shape Parts

Transforming Graphs into Trees (2/2)

Split every join node (> 1 incoming edges) into several copies:

- one for every incoming edge $\notin ST$,
- label every copy with an **alias**:
 - ▶ **paths to variables**: $alias[M], M \in Vars$,
 - ▶ go “up” to the closest *label* (**loops**): $alias \uparrow [label]$,
 - ▶ go “up” and then “down” (**multiple joining paths**): $alias \uparrow \downarrow [label]$.
- If no alias available, return \perp (out of fragment).

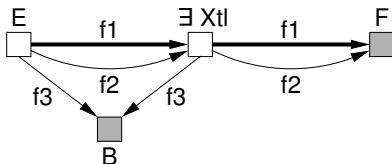
Entailment of Shape Parts

Transforming Graphs into Trees (2/2)

Split every join node (> 1 incoming edges) into several copies:

- one for every incoming edge $\notin ST$,
- label every copy with an **alias**:
 - ▶ **paths to variables**: $alias[M]$, $M \in Vars$,
 - ▶ go “up” to the closest **label** (**loops**): $alias \uparrow [label]$,
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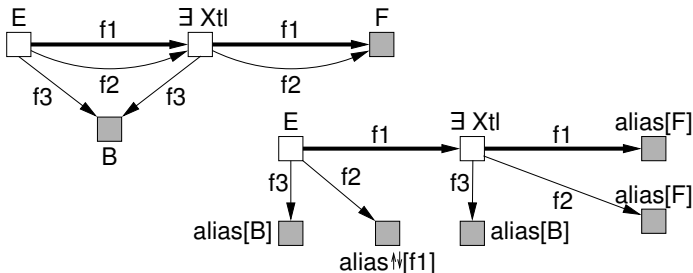
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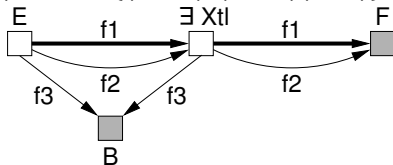
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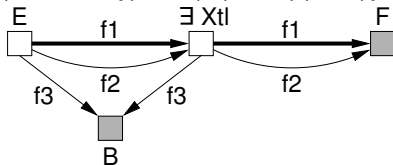
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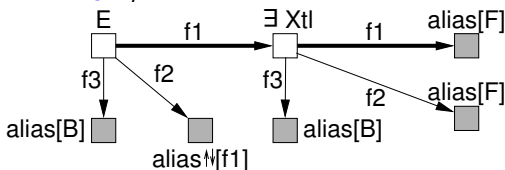
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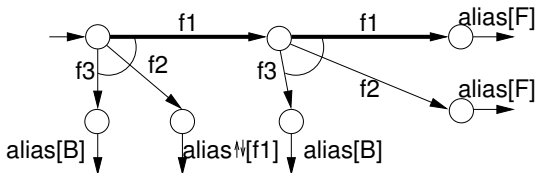
2 Get the **tree encoding** $\mathcal{T}_{P^{[2]}}$:



Entailment of Shape Parts

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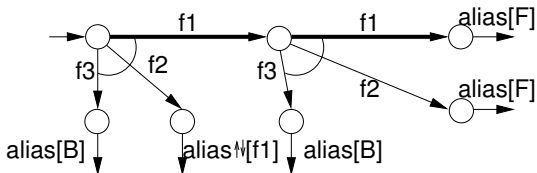
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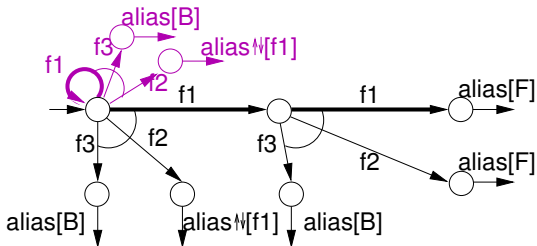
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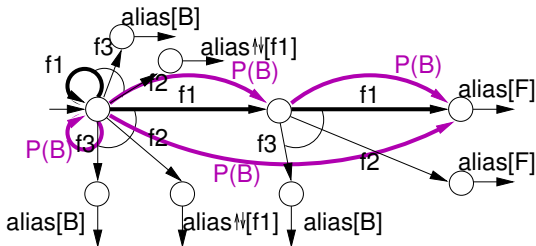
- 4 Add a loop enabling construction of the **list backbone** of size ≥ 2 :



Entailment of Shape Parts

Transforming Inductive Predicates into Tree Automata (3/3)

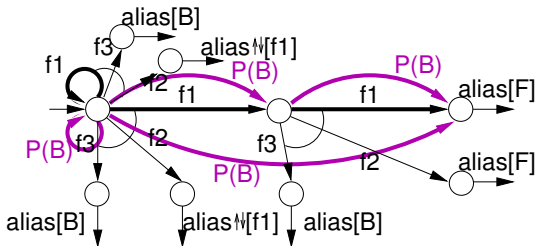
- 5 Duplicate backbone transitions with transitions over $P \rightsquigarrow \mathcal{A}_{P[2+]}$,
▶ to enable arbitrary interleaving:



Entailment of Shape Parts

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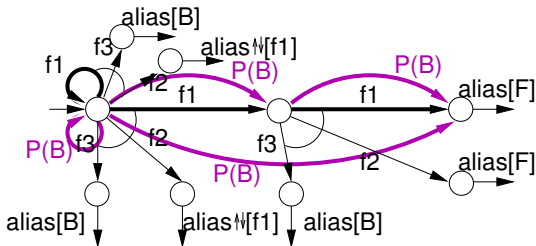


- 6 For every nested predicate edge over Q , insert \mathcal{A}_Q ,
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Entailment of Shape Parts

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- 6 For every nested predicate edge over Q , insert \mathcal{A}_Q ,
▶ and modify the aliases appearing in \mathcal{A}_Q .
- 7 Unite $\mathcal{A}_{P[2+]}$ with $\mathcal{A}_{P[1]} \rightsquigarrow \mathcal{A}_{P[1+]}$.

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The decision procedure is:

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The decision procedure is:

- **sound**,
- **polynomial** (relative to SAT) and **incomplete**:
 - ▶ issues with possibly empty nested lists and consequent aliasing,
- an easy extension – **exponential** and **complete**:
 - ▶ exponential in the maximum height of the hierarchy of nested predicates.

Doubly-Linked Lists

$$\text{dll}(E, F, P, S) = (E = S \wedge F = P \wedge \text{emp}) \vee \\ (E \neq S \wedge F \neq P \wedge \exists X_{t_1}. E \mapsto \{(next, X_{t_1}), (prev, P)\} * \text{dll}(X_{t_1}, F, E, S)).$$

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A new kind of label is needed to close the next/prev loops:

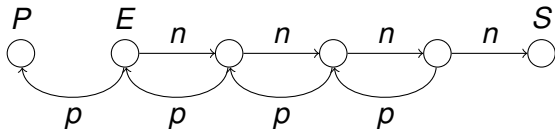
- second predecessor with a given label.

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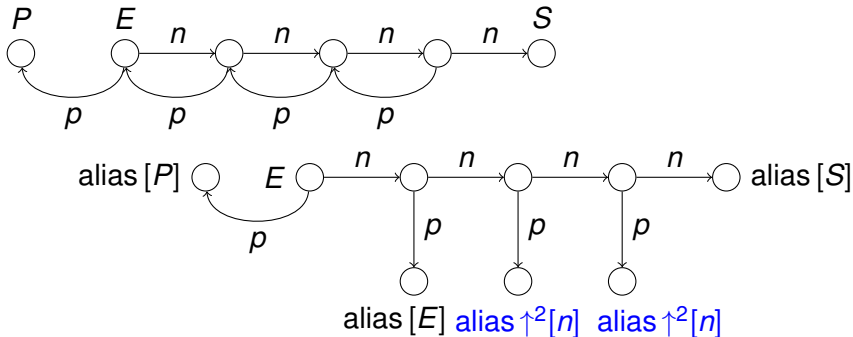


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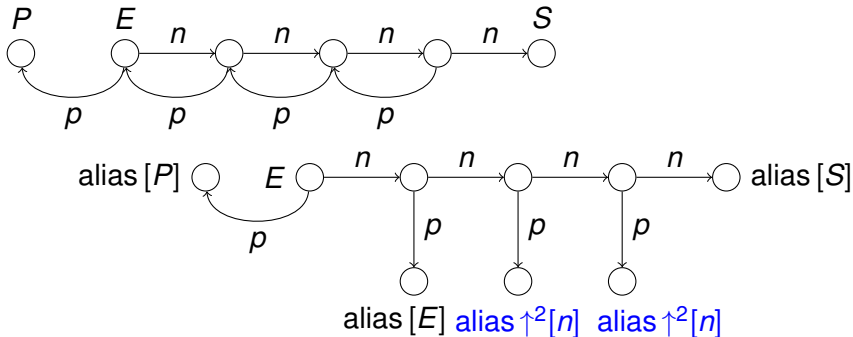


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A new kind of label is needed to close the **next/prev loops**:

- **second predecessor** with a given label.



One more kind of label needed for **circular DLLs**.

Experimental Results

Implemented in a solver **SPEN**.

- Input format: SMTLIB2,
 - ▶ extension for separation logic.
- Uses:
 - ▶ MINISAT,
 - ▶ VATA tree automata library.
- Benchmarks (from SL-COMP'14):
 - ▶ 292 $1s$ problems: $< 8s$ – 2nd place,
 - ▶ 43 “*fixed definitions*” problems – operations on:
 - nested singly-linked lists,
 - nested circular singly-linked lists,
 - 3-level skip lists,
 - doubly-linked lists.
 - average time: 0.35 s – 1st place.

Future work

- **Generalize** to a more expressive fragment of SL.
- Combine with reasoning about **other kinds of data**.
- Integrate into a **program analysis** framework.