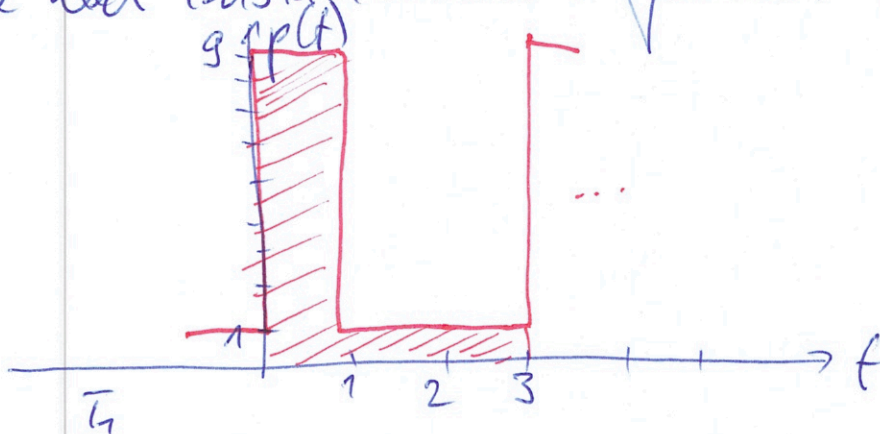


2. Mean value:

$$\bar{x} = \frac{1}{T_1} \int_0^{T_1} x(t) dt = \frac{1}{3} (3 \cdot 1 + 2 \cdot (-1)) = \frac{1}{3}$$

3. We need instantaneous power $p(t) = x^2(t)$



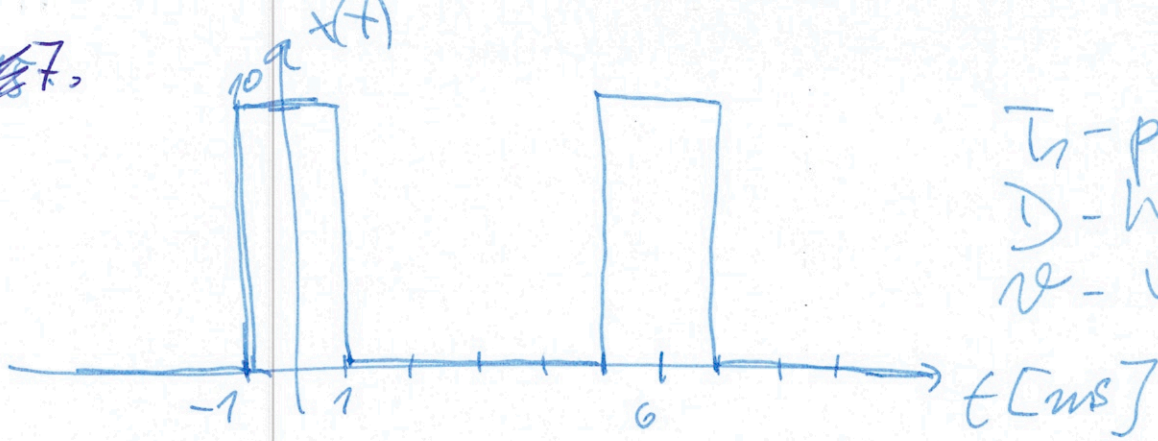
$$E = \int_0^{T_1} p(t) dt = 9 + 2 = \underline{\underline{11}}$$

4. $P = \frac{E}{T_1} = \frac{11}{3} = \underline{\underline{3,66}}$

5. $C_{ef} = \sqrt{P} = \sqrt{3,66} = \underline{\underline{1,91}}$

6. See above the green and black lines. Different, because negative signal decreases the mean value, but contributes to the power.

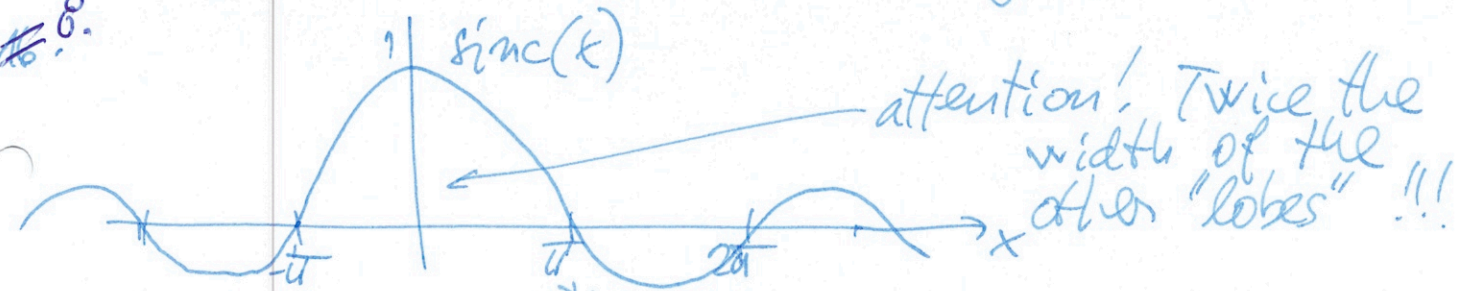
#7.



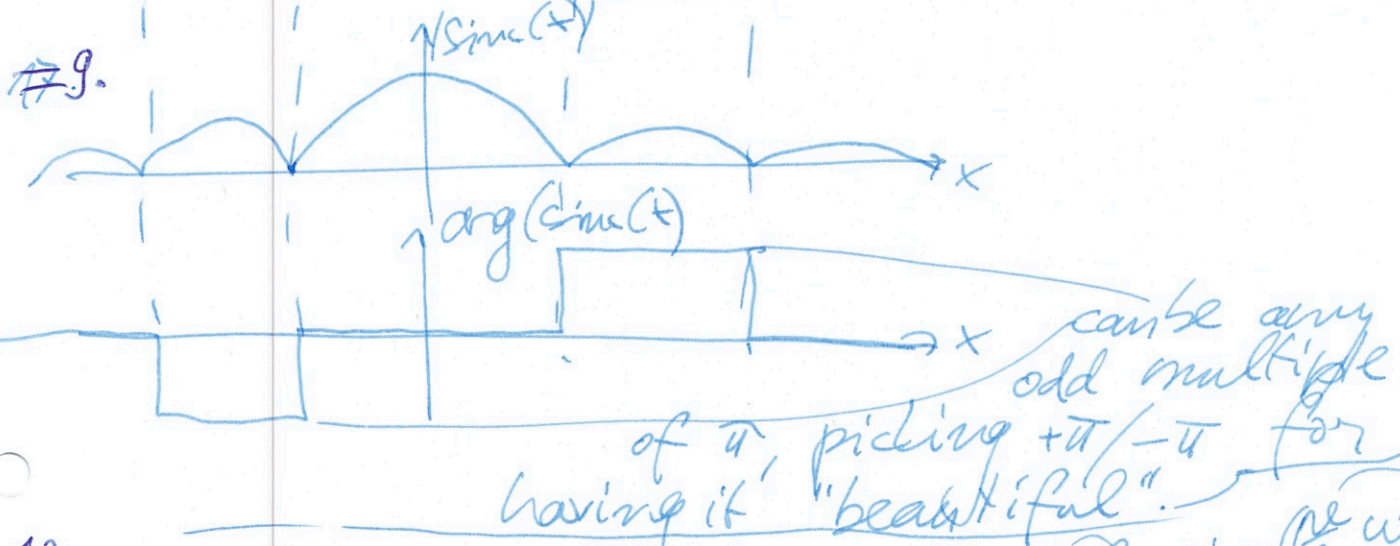
(2) ~~4.~~
 T_1 - period $6 \cdot 10^{-3}$
 D - height 10
 v - width $2 \cdot 10^{-3}$

$\frac{v}{T_1} = \text{"duty cycle"}$

#8.



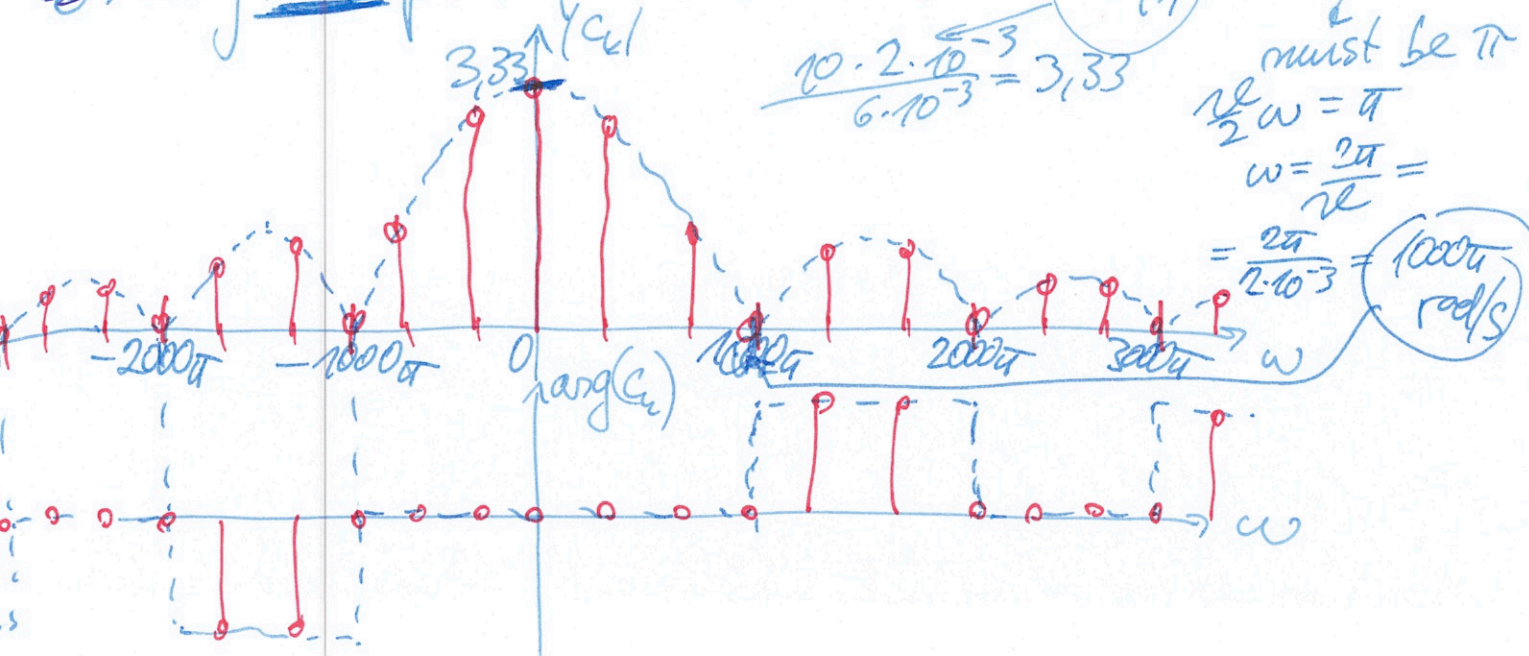
#9.



10. ~~8.~~ only blue part first !!! It is $\frac{D \cdot v}{T_1} \cdot \text{sinc}\left(\frac{v \omega}{2}\right)$

$\frac{10 \cdot 2 \cdot 10^{-3}}{6 \cdot 10^{-3}} = 3,33$

must be π
 $\frac{v \omega}{2} = \pi$
 $\omega = \frac{2\pi}{v}$
 $= \frac{2\pi}{2 \cdot 10^{-3}} = 1000\pi \text{ rad/s}$

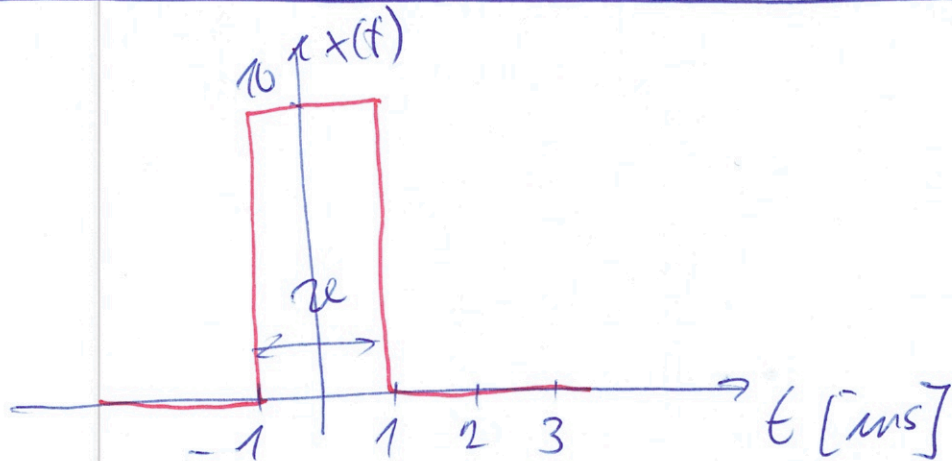


11. $\omega_1 = \frac{2\pi}{T_1} = \frac{2\pi}{6 \cdot 10^{-3}} = 333,3\pi \text{ rad/s}$ (3)

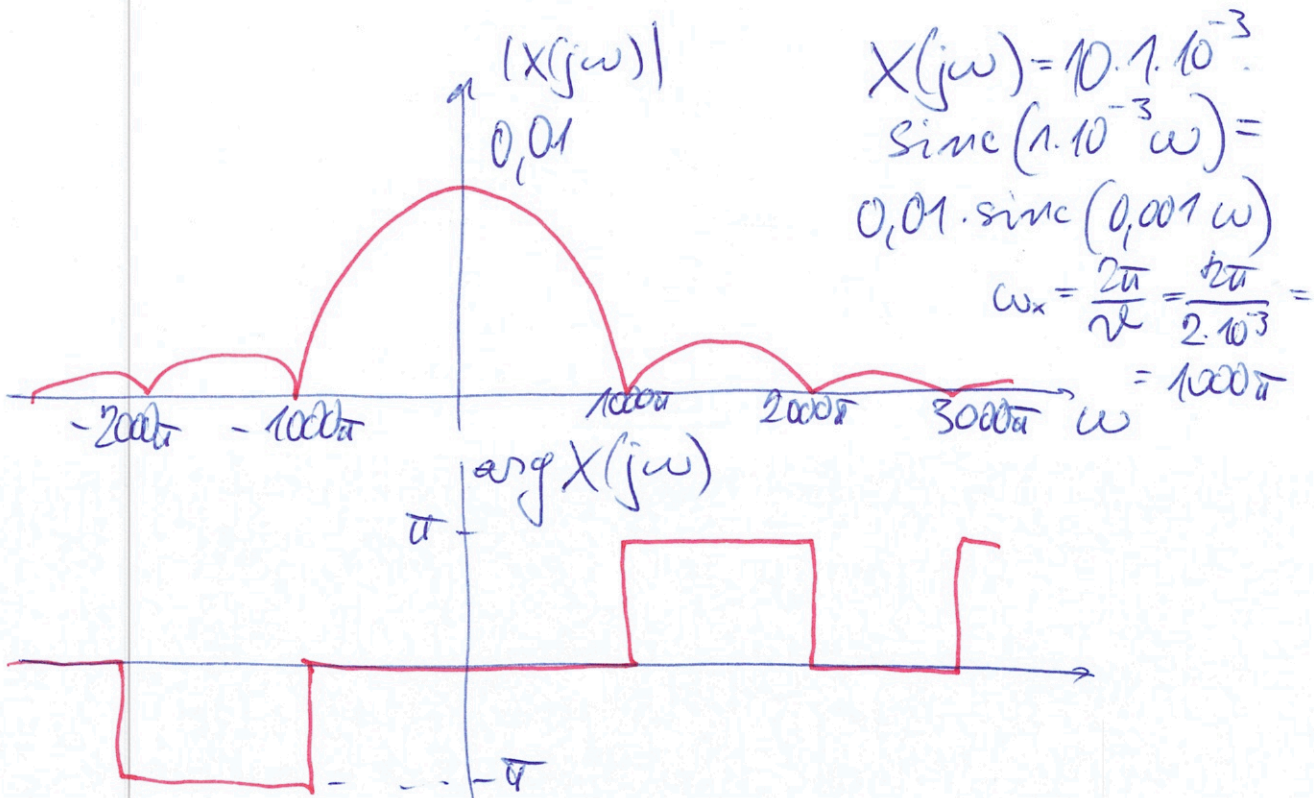
Drawing the red coefficients c_k at the multiples of $333,3\pi$.

For $c_3, c_6, c_9, \dots, c_{-3}, c_{-6}, c_{-9}, \dots$ the phase can be zero, π , $-\pi$ or anything else, as the magnitude is zero. We set it to zero.

12.



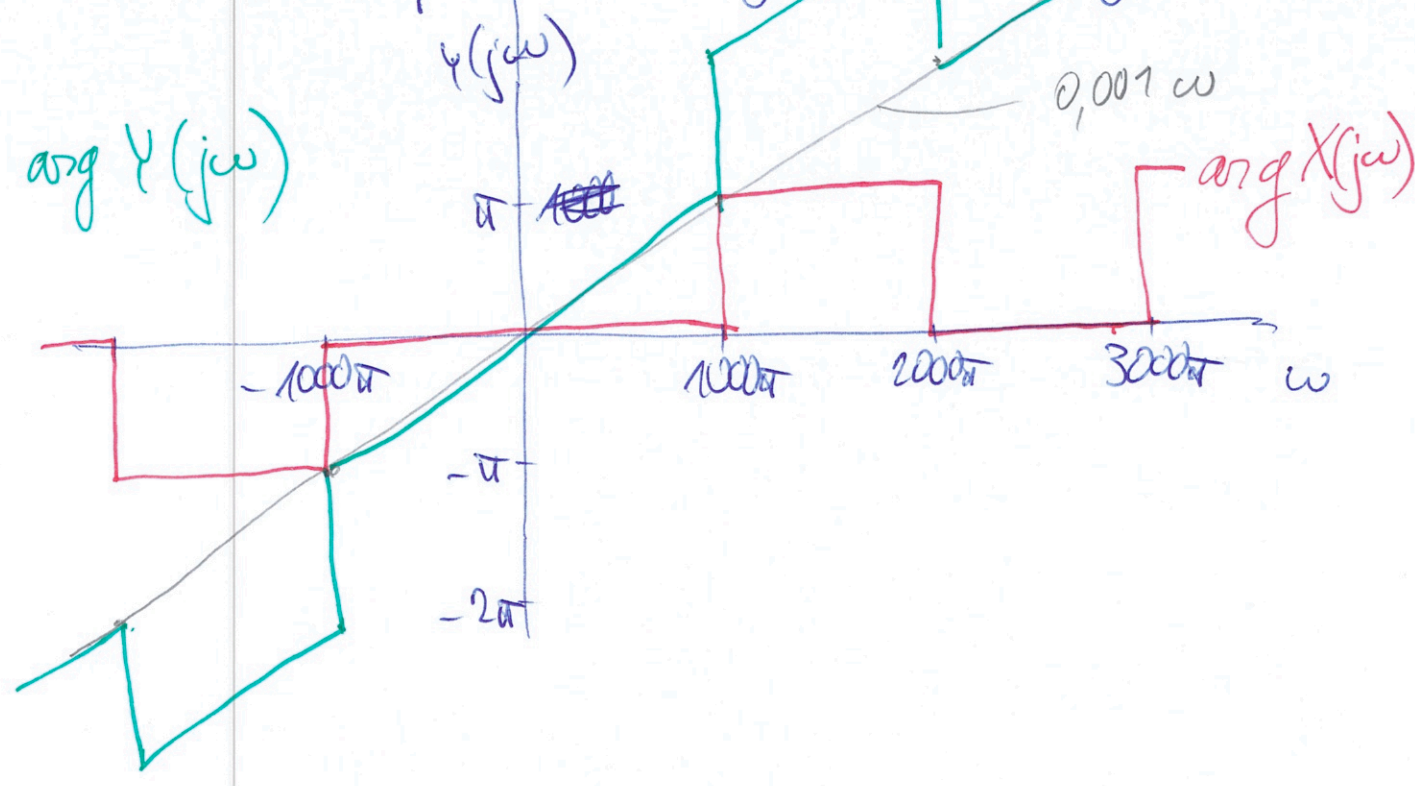
13.



14. $y(t) = x(t + 1ms)$

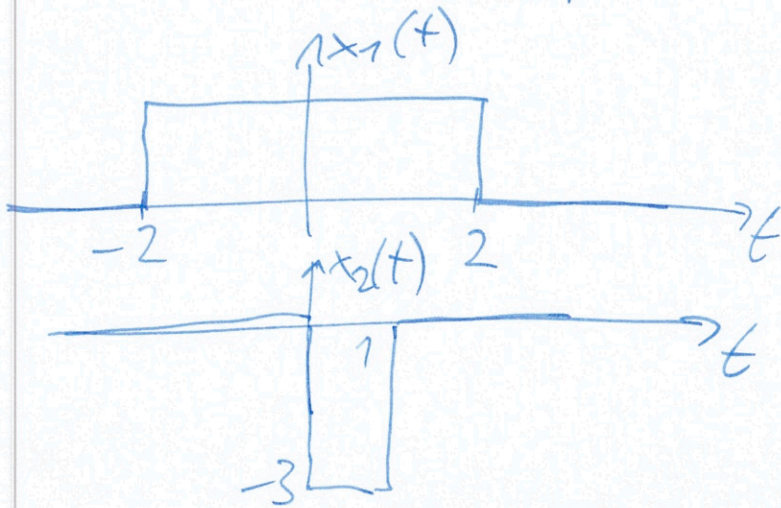
$Y(j\omega) = X(j\omega) \cdot e^{+j\omega 0,001}$

- the magnitude does not change
- the phase changes: adding $0,001\omega$.

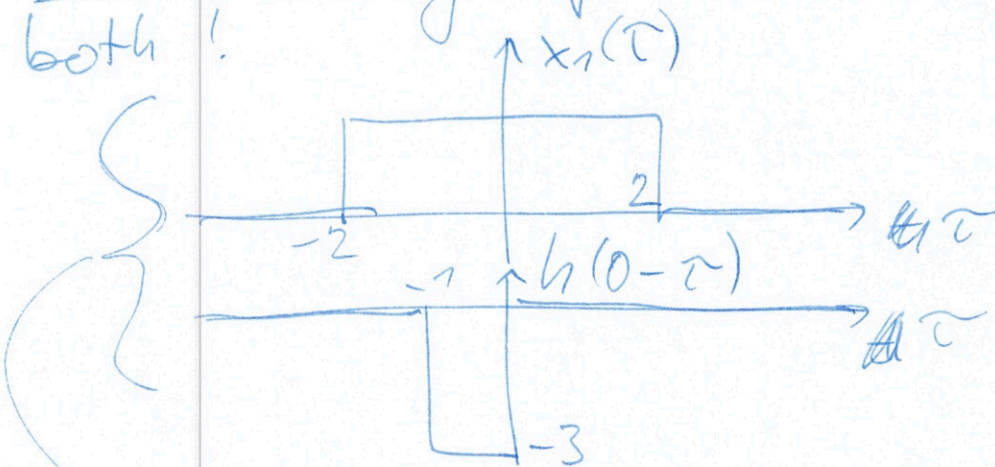


~~SS Exercise #4~~

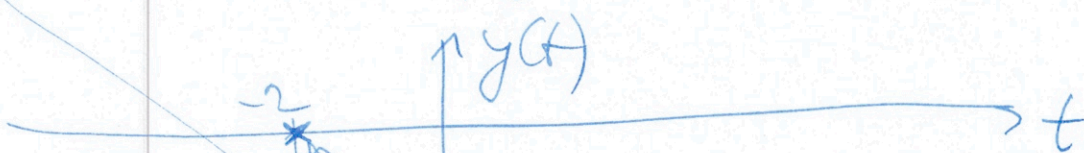
15



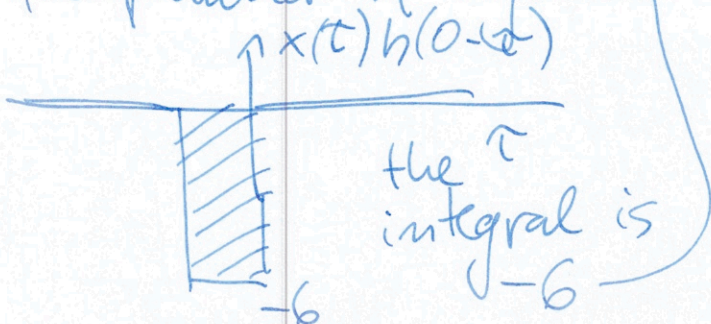
16) Selecting the 1st. variant but divide students in group and let them pick both!



17

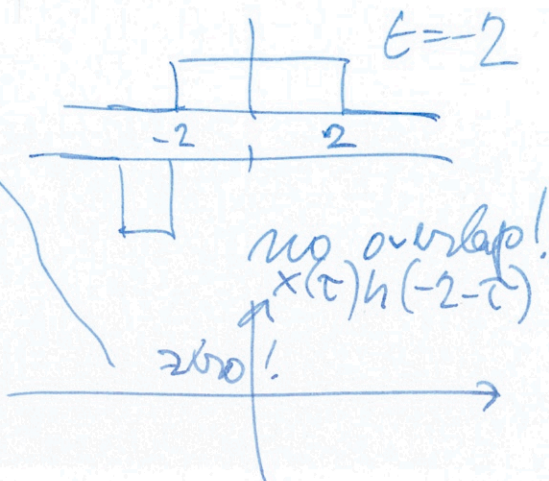


the product of signals



the integral is \int_{-6}^{τ}

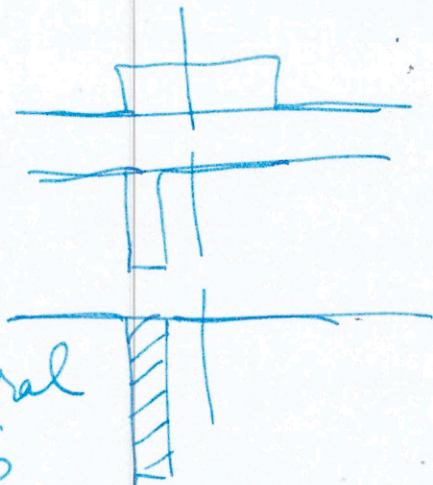
18



no overlap! zero!

(19)

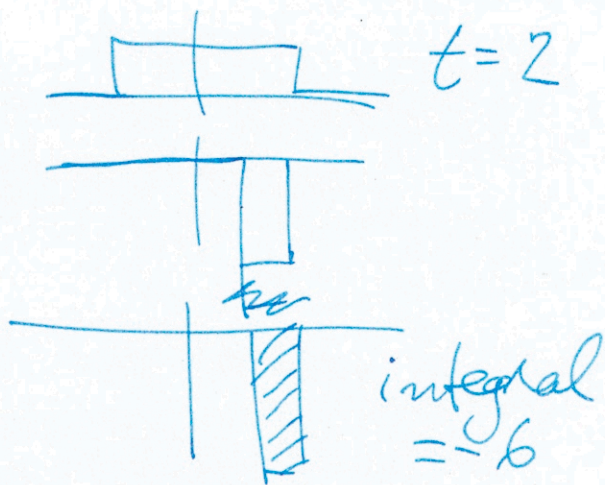
~~$t = -1$~~



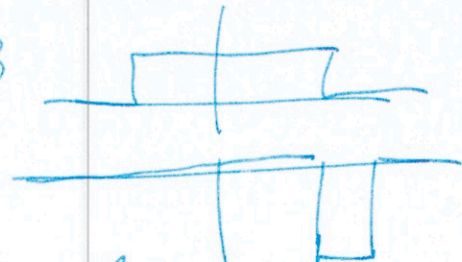
(6)

(20)

$t = 2$

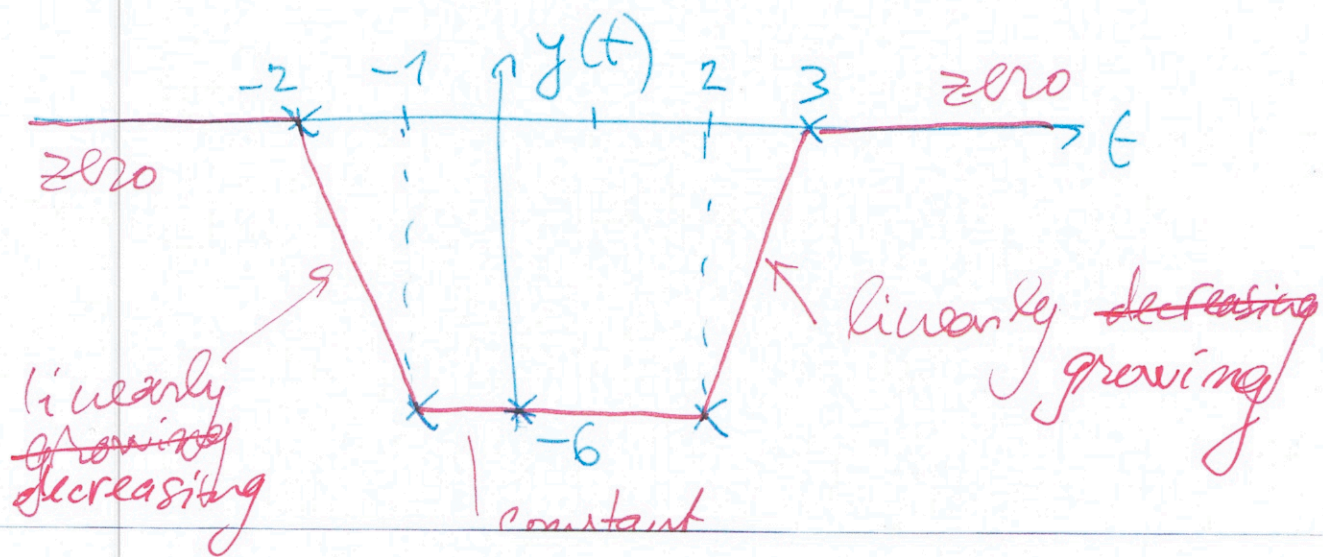


(21) $t = 3$



no overlap \Rightarrow zero.

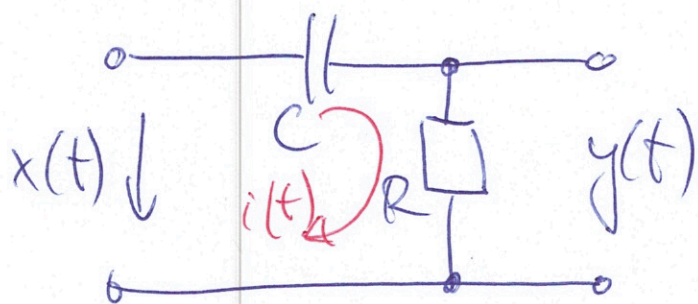
(22)



Lab #3 Continuous-time systems

4

We will study the behavior of the following circuit:



① Find differential equation describing the circuit.

We'll use current $i(t)$ that can be determined in two ways =

$$i(t) = \frac{y(t)}{R}$$

$$i(t) = C \frac{d(x(t) - y(t))}{dt}$$

} this is the same current!

$$y(t) = RC \frac{dx(t)}{dt} - RC \frac{dy(t)}{dt}$$

② Do its Laplace transform and find the transfer function of the circuit:

"Vocabulary" of LT =

$$x(t) \rightarrow X(s)$$

$$a x(t) \rightarrow a X(s)$$

$$\frac{dx(t)}{dt} \rightarrow s X(s)$$

that's all we need!

$$Y(s) = RCsX(s) - RCsY(s)$$

... let's try to group everything depending on $Y(s)$ on the ~~right~~ left, $X(s)$ on the right...

$$Y(s)[1 + RCs] = X(s)RCs$$

Now, find $H(s)$ that is defined as $\frac{Y(s)}{X(s)}$

26.

$$H(s) = \frac{Y(s)}{X(s)} = \frac{RCs}{1 + RCs}$$

27. What are the coefficients b_k, a_k ?

$$H(s) = \frac{\sum_{k=0}^M b_k s^k}{\sum_{k=0}^N a_k s^k}$$

$$b_0 = 0 \quad b_1 = RC \quad M = 1$$

$$a_0 = 1 \quad a_1 = RC \quad N = 1$$

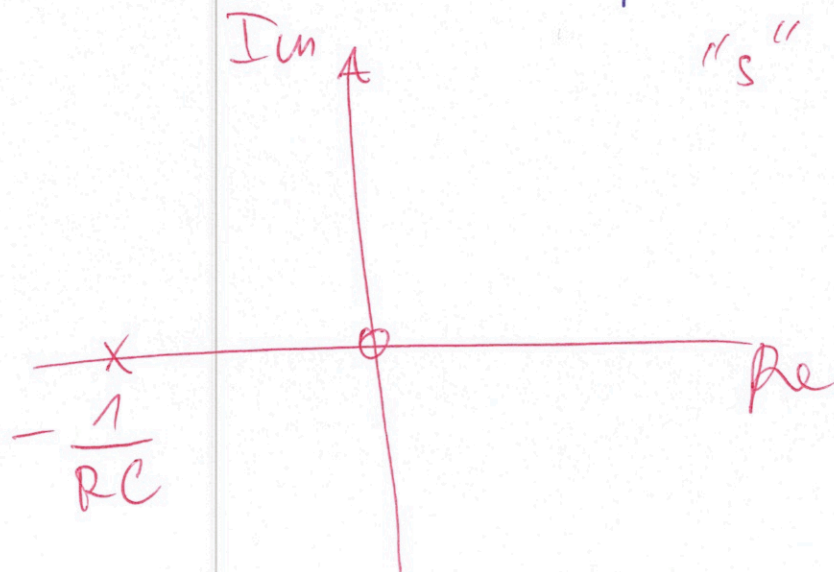
28. Convert it to the form including zeros and poles

$$H(s) = \frac{b_M}{a_N} \cdot \frac{\prod_{k=1}^M (s - m_k)}{\prod_{k=1}^N (s - p_k)} = \frac{RC (s - 0)}{RC (s - (-\frac{1}{RC}))}$$

$$= \frac{s - 0}{s - (-\frac{1}{RC})}$$

0 is the only zero
 $-\frac{1}{RC}$ is the only pole.

29) Draw them into the "s" plane and check stability of the circuit ...



Real part of $-\frac{1}{RC}$ smaller than zero \Rightarrow stable :-)

30) Determine the frequency response, pay particular attention to

$$\omega = 0,000001$$

$$\omega = \frac{1}{RC}$$

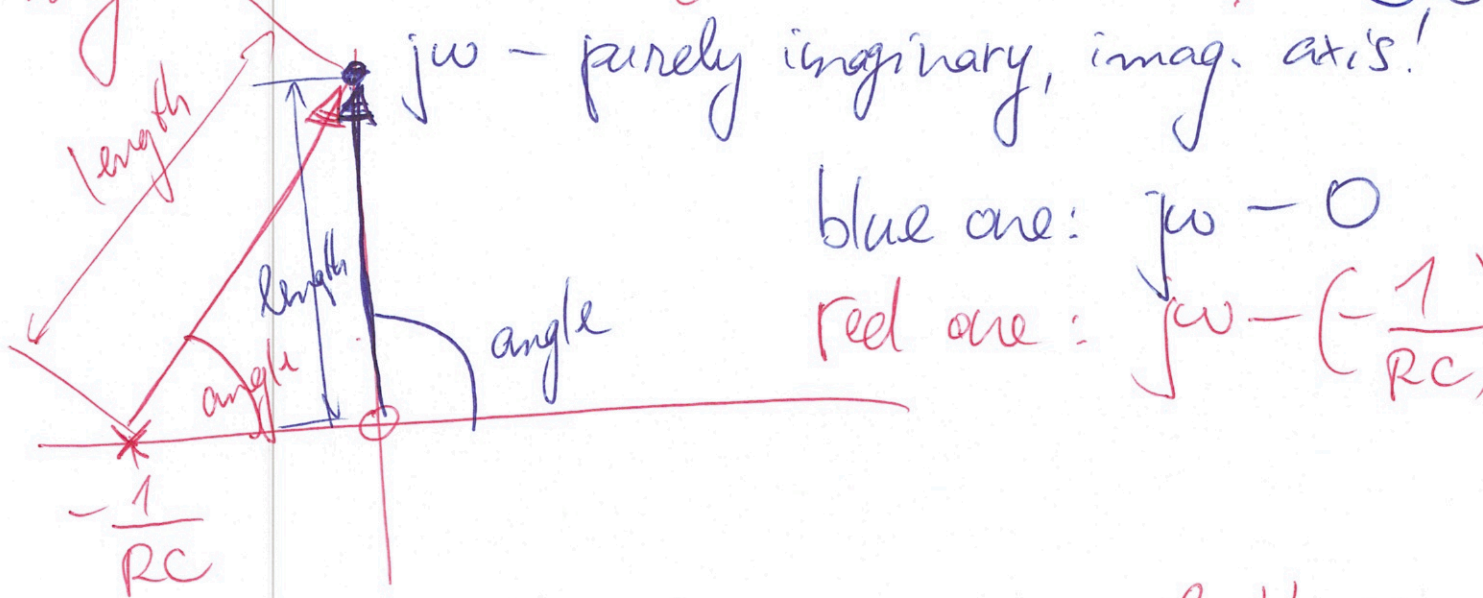
$$\omega = \infty$$

$$H(j\omega) = \frac{b_m \prod_{k=1}^M (j\omega - h_k)}{a_n \prod_{k=1}^N (j\omega - p_k)}$$

$H(s)$ to $H(j\omega)$
by simply re-writing all occurrences of 's' by 'j\omega'

$$= \frac{j\omega - 0}{j\omega - \left(-\frac{1}{RC}\right)}$$

Numerator and denominator are complex numbers
They can be visualized as vectors! (10)



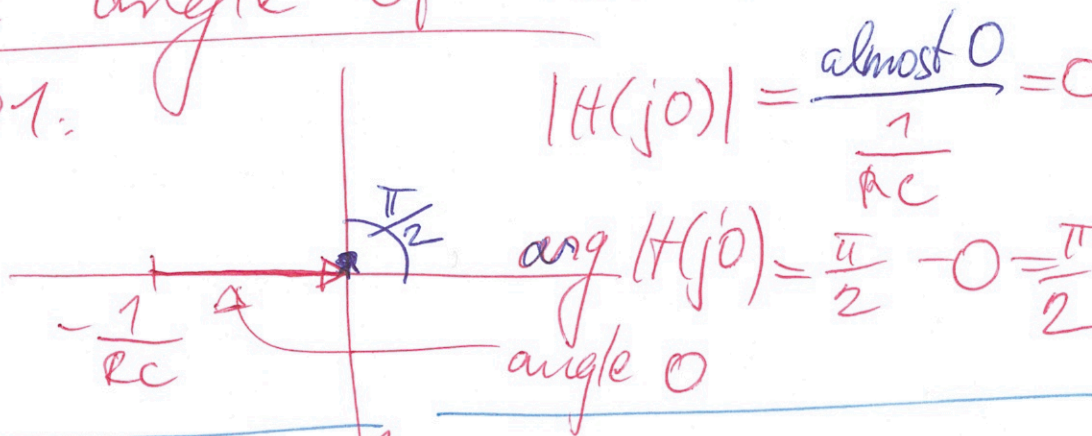
$H(j\omega)$ is given by division of these complex numbers:

module is division of modules
argument is subtraction of arguments

Module \approx length of vector

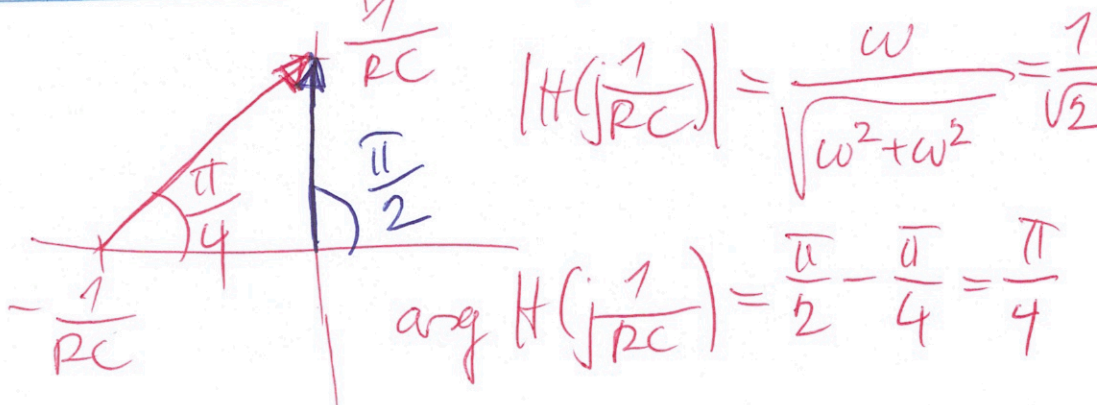
Arg \approx angle of vector

$\omega = 0, 000001:$

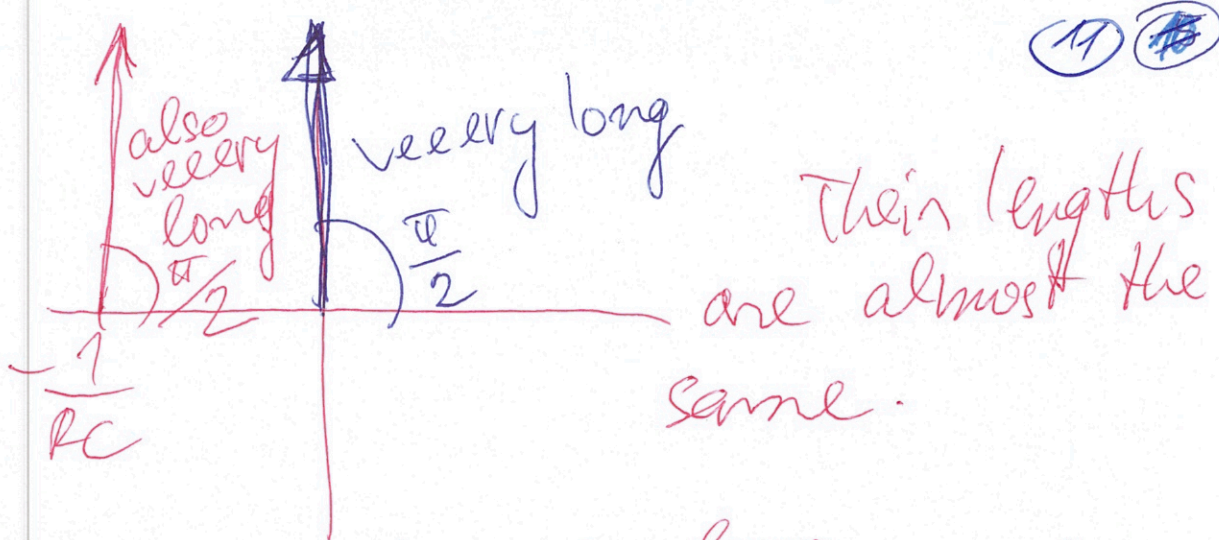


31.

$\omega = \frac{1}{RC}$



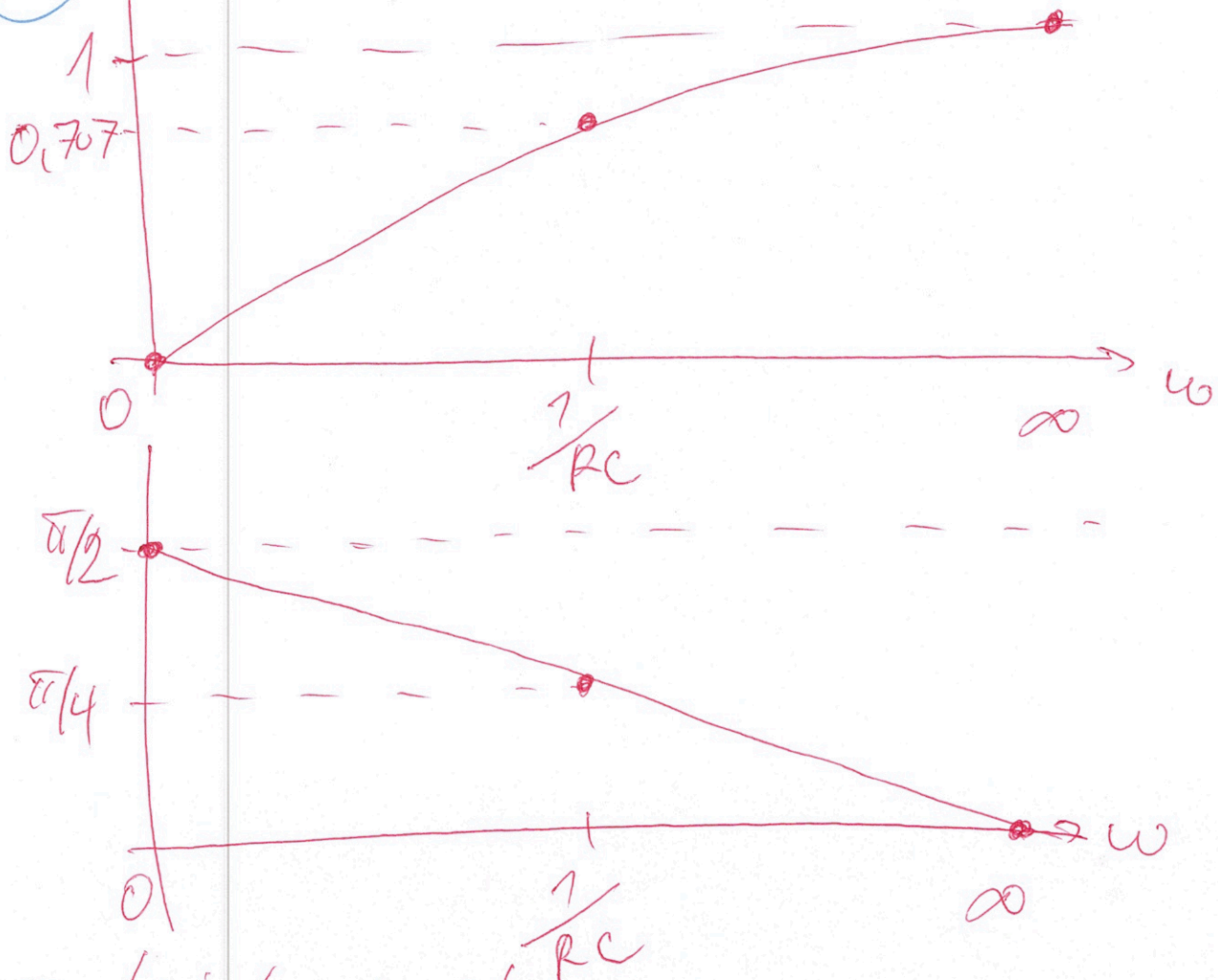
32.
 $\omega = \infty$



$$|H(j\infty)| = \frac{\text{very long}}{\text{very long}} = 1$$

$$\arg H(j\infty) = \frac{\pi}{2} - \frac{\pi}{2} = 0$$

33.



⇒ High-pass!

⇒ look at the plot for $R = 1k\Omega$
 $C = 1000pF$